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ON THE COVER

It's been more than half a century since the picture phone made its debut at the 1939 World's Fair. It was a big idea, with a price tag and equipment sized to match. Now there's an IC that greatly reduces the cost and size of a video-phone system. Our version of the video phone, or video modem, transmits and receives high-resolution, still-video frames. It consists of a base unit that we show connected to a small CCD camera module and to a Sony Watchman: a standard video camera or camcorder and a monitor will work just as well. You can send or receive images anywhere in the world, as long as the person at the other end has a video phone too. Turn to page 33 to find out how to make a couple of video phones—or get a friend to build the second!

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CIRCLE 78 ON FREE INFORMATION CARD
How they captured the Olympics.

In mid-September 1990, the city of Atlanta, GA celebrated the International Olympic Committee’s (IOC) announcement that it had been chosen as the site for the 1996 Summer Olympics. Perhaps one of the factors influencing that decision was the high-tech, multi-media presentation of Atlanta’s proposal. Developed by researchers at the Georgia Institute of Technology with the assistance of Georgia State University and several private companies, the innovative system used three videodisc players, three computers, computer-composed music, digitized narration, and a unique interaction system that includes a computer-animated, touch-sensitive model of the proposed Olympic Village. The presentation was controlled by a Commodore Amiga computer; an Apple Macintosh IICx and a smaller computer-interface device were also used.

Computer graphics, which provided both detailed interior scenes and a bird’s-eye view of the entire Olympic Village from an altitude of about 500 feet, were merged with real images shot on film; a computer-generated “Golden Athlete” carried the Olympic torch to open the program. Faced with a tight budget and limited production time, the researchers managed to get high-quality images without using multiple cameras by using an anamorphic lens and telecine techniques. Three side-by-side video-projection screens provided a 120 degree wrap-around view. The musical accompaniment was composed and generated on the Amiga computer, which was used to coordinate all the various activities.

The presentation package used a touch-sensitive, three-dimensional map of the proposed Olympic village. Animation included clouds, moving vehicles, and fireworks display, along with the icons used to choose portions of the presentation for viewing. Because of the raised buildings molded into the maps, conventional touch-sensitive conductive areas or infrared beams couldn’t be used. Instead, load cells located on the four corners of the model sensed pressure exerted by users pressing on the icons, and a small computer determined what information the user would like to see. A sample of the presentation is shown in Fig. 1.

Georgia Tech hopes to use the Olympic project as a stepping stone to the formation of a new, industrially sponsored, multimedia technology research center. Research projects will include telecommunications technology and policy, computer graphics and scientific visualization, translations for the hearing impaired, and a workstation teleconference prototype.

Digital simulcast HDTV system.

The Advanced Television Research Consortium (ATRC)—which includes NBC, the David Sarnoff Research Center, Philips Consumer Electronics Company, and Thomson Consumer Electronics, Inc.—is focusing on a digital simulcast system that it believes offers a practical digital solution for HDTV. The proposed Advanced Digital Television system, to be jointly developed by the David Sarnoff Research Center and Philips, would preserve existing NTSC channel allocations and ensure the availability of high-quality television images in the United States through the established terrestrial transmission system. According to the ATRC, the digital approach will also include a new modulation technique developed by the ATRC allowing the digital information to be transmitted at low levels of power so that it doesn’t interfere with existing NTSC stations. The digital transmission is also relatively resistant to interference from the analog NTSC transmission.

Another key development in the digital simulcast system is the introduction of a highly efficient digital data-compression approach for encoding HDTV. The technique allows the high-definition pictures to be squeezed into the existing broadcasting frequencies, and provides for good picture performance even in the presence of transmission errors.

The consortium hopes that the proposed simulcast HDTV system will be the present day equivalent of the NTSC’s “early superhighway for technology”—a base system that will provide for technological growth and expansion for many decades.

The original NTSC system, which offered only black-and-white video with mono audio, was extremely versatile. Color was later added to the system, as was multichannel television sound (MTS) stereo audio, a second audio program (SAP) channel for bilingual programming, and captioning for the hearing impaired. It is hoped that an HDTV system will turn out to be just as flexible.
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RCA adopts VCR Plus+. VCR Plus+, the instant VCR programming system keyed to special code numbers printed in program listings of newspapers and some editions of TV Guide (Radio-Electronics, October 1990), will be built into some models of RCA VCR's, according to manufacturer Thomson Consumer Electronics. The program code listings premiered last December in some 30 newspapers and reports at that time indicated a sellout of the $59.95 remote-control gadget, which could program most VCR's and cable boxes. The version to be built into RCA VCR's will use on-screen prompts. It won't program cable boxes, however.

Is it really stereo? Some TV sets that are advertised as receiving "broadcast TV stereo" are not delivering the goods, according to dbx Technology Licensing, which administers patent rights on one component of the multichannel TV sound (MTS) system. Those sets have stereo amplifiers and two sets of speakers—the necessary ingredients for stereo sound—but fail to properly decode the received TV audio signal, the licensing company says.

When the MTS standard was adopted by an all-industry committee in 1983, a major component was a companding, or noise-reduction, system. The dbx system was chosen, and stations broadcasting with stereo audio were required to encode the signal using the dbx process. To properly receive the audio signal in stereo, according to the committee, receivers were to include a dbx decoding system. Some TV sets being marketed today don't use dbx decoding, employing instead other types of expanding circuitry or simply a filter. The purpose, presumably, is to save money, including the licensing fee. However, the chief engineering officer of one TV-set manufacturer that does use dbx throughout its line maintains that use of dbx circuitry adds a maximum of only $2 to the cost of a set, or perhaps 10%-to 15% of the cost of adding stereo (dual amplifiers and extra speakers).

The dbx licensing organization and some set manufacturers maintain that receivers that don't use dbx have as little as 3- to 4-dB of stereo separation under some conditions—not enough to provide any noticeable stereo effect—and can add noise, "pumping" effects, and wandering or shifting sound in many cases. dbx Technology Licensing calls that "pseudo stereo" and says it plans to initiate an advertising and public-relations campaign to urge buyers to insist on TV receivers with dbx decoders. Manufacturers of TV brands that don't use dbx in some of their sets have steadfastly refused to comment on the situation.

SuperNTSC. As we went to press, SuperNTSC was scheduled for a nationwide test as an alternative to high-definition TV. SuperNTSC, developed by Yves Faroudja, who designs picture-clarifying broadcast systems, uses many different technologies to produce the best possible picture from the existing National TV System Committee (NTSC) color standard. Backed by ABC, Continental Cablevision, General Instrument, Scientific-Atlanta, Viacom, Westinghouse, and other powerhouse in broadcasting and cable, the system uses a combination of image-processing techniques to remove artifacts from the NTSC picture. In addition, signals are originated in non-interlaced scanning at 1,050 lines per second and converted to a standard 525-line NTSC signal just before transmission. A standard receiver will display a conventional image, but a SuperNTSC set will capitalize on all of the picture improvements and convert the picture back into 1,050 non-interlaced lines. According to inventor Faroudja, a SuperNTSC decoder should add about $300 to the cost of a TV set.

Big-screen sets grow. Although 1990 was the first year in the last eight in which TV set sales didn't set a record, large-screen set sales rose. An analysis of sales figures for last year's first nine months shows that table-model sets in the 27-to-29-inch screen sizes were up 26.4% from the same period in 1989, while the 30-inch-and-up category rose about 96%. All sizes below 27-inch, except 20-inch, declined (and 20-inch was up just 1%). Projection TV sales set a new record in 1990, and for the first nine months were up nearly 30%.

Confirming the trend to higher-value TV sets in 1990 were figures on sales for January through October. In that period, multichannel TV sound (MTS) was built into 31.7% of all sets sold, up from 27.6% in the comparable period of 1989.

SkyPix. The 80-channel direct satellite-broadcasting system, which bills itself as "the first in-home video store," plans to start broadcasting next summer and is already lining up retailers for its complete receiver package—dish, decoder, and everything needed to convert a standard TV set to receive its DBS signal—which will carry a list price of $699. SkyPix's compressed signals will include 40 to 50 channels of pay-per-view movies, according to its developers, and will transmit a picture with 480 lines of horizontal resolution, considerably better than Super VHS or laserdisc.
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I recently purchased a program called "Video Tilter Plus" for my old Apple II Plus Computer. It's produced by a company called Datasoft and is designed to let you create graphic titles on the computer and then transfer them to your VCR. The problem I'm having is that none of the titles show up in color on my TV. Is there any way to get my Apple graphics recorded in color without actually pointing a camera at the computer screen?—M. Marks, Pittsburgh, PA

Even though some may think of electronics as an exact science, the best answer I can give you in this case is a definite maybe. It may not be all that satisfying, but what can I tell you?

Since you can get the titles up on the screen, there's evidently no problem with the software, which is a good thing since I believe that the company who produced it is out of business. The reason you're having a problem getting color in the recorded image is, as you suspect, that the old Apple II Plus, as well as the newer IIe and IIgs, don't generate interlaced video.

If you throw the output of the Apple's composite video port on a scope, you'll see that it's real close to NTSC, but when you're talking about video, a miss is as good as a mile. I have an Apple II Plus and, back in the old days, used to run the video through a VCR to get an instant replay on some computer games. Some VCR's and TV's (usually the older ones), would swallow the Apple video and produce color images. The newer video equipment is much more finicky about details like interface and, if the waveform isn't a real close match to NTSC, color disappears. It's amazing how important half lines can be.

I can offer you three possibilities for solving the problem but I'm not going to guarantee that any of them will work. The first, and most obvious, is to try an older VCR, or at least a different one. Based on the experience I had, cheaper models with fewer features seem to be a better choice.

The second option is to try adjusting the operating frequency of the Apple itself. That's fairly simple to do since there's a small trimmer capacitor in the main clock circuit located between A1 and B1 on the motherboard. Those are Apple's grid coordinates and you'll find them along the edges of the board. If the Apple is slightly off frequency, the burst frequency will be off as well and the difference may be enough to keep your VCR from recognizing it.

You should use a scope for this but, if you don't have one, a bit of freehand experimentation can't hurt anything. Just be sure to mark the original position of the trimmer in case you run into problems. A second trimmer is on the motherboard at location G14 and you can play around with that one as well. It changes the phase angle of the burst and will change the hue of the colors on the screen. It shouldn't do anything to help your problem, but then again, you never know.

If none of those two work, your only available option is to look around for some hardware that will solve the problem. Quite frankly, I wouldn't hope for much since the computer is rather old. It's true that there are some expansion slot similarities between it and the later IIe, but that whole market isn't what it used to be. Check with some Apple magazines and, if all else fails, you might try contacting Apple itself. Good luck.

A LONG PLAYING RECORDER

How would I modify an ordinary cassette recorder to make it into a super long-playing recorder? I understand only one or two electronic components are necessary.—L. Krenek, La Grange, TX

I haven't had the occasion to take apart a wide variety of cassette recorders but the ones I have seen are easily modified to increase the recording time. Before we get any further along with this, you should NEVER try to modify store-bought equipment without either a lot of paperwork, a lot of experience, or a lot of nerve. Consumer stuff has gotten so sophisticated that opening the case often requires a manual.

But seriously folks, most good cassette recorders can be modified without adding any components at all. The motor has a tachometer on it that the cassette's circuitry uses to monitor the speed of the motor and make sure that the speed remains constant. Some motors have a small AC generator running off the motor shaft inside the motor housing, and others have a small pickup head mounted outside the motor that gets pulses from a metal wheel attached to the motor shaft.

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- AC & DC Power cords w/ mntg hardware.
- One Year Limited Warranty.

Options:
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  25 to 1000MHz w 50' coax. AS300  $59.95
  Mag Mnt Mobile Antenna. 15' coax. MA100  $25.00
- Cigarette Lighter power adaptor. CP100  $4.00
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  with mobile mount. MS100  $19.50
- Extended Warranty. 2/3 yrs  $40/$55

Specifications:
Sensitivity: .4uV Lo,Hi. 8uV Air. .5uV
Speed: 15 ch/sec.
IF: 21.4MHz, 455KHz
Increments: 10, 12.5, 25, 30
Audio: 1W
Power: 12.8VDC, 200MA
Antenna: BNC
Display: LCD w/backlight
Dimensions: 2 1/4H x 5 5/8W x 6 1/2D. 14oz wt.
AR2500 $499

2016 Channels. 1 MHz to 1500 MHz

Standard Features
• Continuous coverage
• AM, FM, wide band FM, & BFO for SSB, CW.
• 64 Scan Banks.
• 16 Search Banks.
• RS232 port built in.
• Includes AC/DC pwr crd. Antenna, Mntng Brckt.
• One Year Limited Warranty.

Options:
- Earphone.
- External Speaker.
- Mobile Mount.
- Extended Warranty. 2/3 yrs.
- Mobile Mounting Bracket.
- RS232 Control Package (software & cable) offers spectrum display and database.

Specifications:
- Coverage: 1 MHz - 1500MHz
- Sensitivity: .35uV NFM, 1.0uV WFM, 1.0AM/SSB/CW
- Speed: 38 ch/sec. scan, 38 ch/sec. search
- IF: 750.00, 45.0275, 5.5MHz 455KHz
- Increments: 5,12,5,25 kHz
- Audio: 1.2 Watts at 4 ohms
- Power: Input 13.8 V. DC 300mA
- Antenna: BNC
- Display: LCD, backlighted.
- Dimensions: 2 1/4H x 5 5/8W x 6 1/2D Wt. 1lb.

AR3000 $995

400 Channels. 100KHz to 2036MHz

Standard Features:
• Extremely compact size.
• Continuous coverage
• Attenuation Programmable by Channel.
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• Tuning increments down to 50Hz.
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Specifications:
- Coverage: 100KHz - 2036MHz
- Sensitivity: .35uV NFM, 1.0uV WFM, 1.0AM/SSB/CW
- Speed: 20 ch/sec. scan, 20ch/sec. search
- IF: 736.23, (352.23) (198.63) 45.0275, 455KHz
- Increments: 50Hz and greater
- Selectivity: 2.4KHz/-6db (SSB) 12KHz/-6db (NFM/AM)
- Audio: 1.2 Watts at 4 ohms
- Power: Input 13.8 V. DC 500mA
- Antenna: BNC
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STEREOPHILE RESPONDS

I was interested to read Larry Klein’s Audio Update in the December issue of Radio-Electronics, in which he discussed Bob Carver’s attempts to match one amplifier’s transfer characteristic to that of another. Opinions are opinions, and Mr. Klein is entitled to draw any conclusion he wishes from Stereophile magazine’s editorial coverage of Mr. Carver’s products.

Facts are facts, however, and I was disturbed to see that a responsible and conscientious journalist like Mr. Klein had intentionally or unintentionally misrepresented the facts of Stereophile’s involvement with the various “Carver Challenges.”

Briefly, here is what happened: Sometime in 1985, Mr. Carver challenged Stereophile’s then editor, J. Gordon Holt, and its publisher, Larry Archibald, that he could match the sound of any amplifier they chose with one of his inexpensive “Magnetic-Field” power amplifiers. Mr. Carver did, indeed, visit Santa Fe to try to modify his amplifier so that it matched the sound of an expensive tube design. The degree to which the two amplifiers matched was confirmed using the null test described by Mr. Klein. At first, however, even though the measured null was 35 dB down from the amplifier’s output levels (meaning that any difference was at the 1.75% level), Mr. Holt and Mr. Archibald were able to distinguish the Carver from the target amplifier by ear. It was only when Mr. Carver lowered the level of the null between the two amplifiers to −70 dB—a 0.03% difference—that the listeners agreed that the Carver and the reference amplifier were sonically indistinguishable. (The entire series of tests was covered in the October 1985 issue of Stereophile.)

Mr. Klein wrote in his column that “Upon reflection, reconsideration, and relistening to the original modified Carver amp plus other samples that Carver had modified similarly, Stereophile’s staff decided that the amplifiers really didn’t sound alike after all.”

That is not true. Neither Mr. Holt nor I had further access to the original prototype amplifier from the 1985 tests. Some 18 months later, however, Stereophile was sent a production version of an amplifier that we had understood Mr. Carver intended to sound and measure identically to the prototype that had featured in the 1985 listening tests, the Carver M-1.0t. Because of that sonic “cloning,” the production M-1.0t was advertised as sounding identical to the tube amplifier that had featured in the 1985 Stereophile tests.

After careful and independent auditioning of the production M-1.0t, Mr. Holt and I felt that, while it sounded similar to the tube design, it did not sound identical. It certainly could not be said that we deemed it the sonic equivalent of the “very expensive amplifiers”—as Carver’s ads said. Measuring the outputs of the two amplifiers at the loudspeaker terminals while each was driving a pair of Celestion SL600 speakers revealed minor frequency-response differences due to the amplifiers having different output impedances. In addition, carrying out a null test between the production M-1.0t amplifier and the reference tube amplifier revealed that, at best, the two amps would only null to −40 dB at 2 kHz, a 1% difference, diminishing to −20 dB below 100 Hz and above 15 kHz, a 10% difference.

Those null figures were not significantly altered by changing the tube amplifier’s bias or by varying the line voltage with a Variac. We then borrowed another sample of the M-1.0t from a local dealer and nulled that against the target amplifier. The result was an even shallower null. In the original tests, Mr. Holt and Mr. Archibald had proven to Mr. Carver that they could identify by ear two amplifiers that had produced a 35-dB null. The 1987 measurements reinforced the idea that the production M-1.0t did not sound the same as the target amplifier.
amplifier.

After being informed of these results, Mr. Carver flew out to Santa Fe at the end of February, 1987, and carried out a set of null tests that essentially agreed with our measurements, a fact confirmed by Mr. Carver in a letter published in Stereophile. "...the null product between the amplifiers...is 28 dB, not 70 dB! Your tests showed this, and so did mine," he wrote. He went on to say that "Since my own research has shown that the threshold for detecting differences is about 40 dB, I knew there was enough variance between the amps to be detectable by a careful listener." Mr. Carver then asked us to participate in a series of single-blind tests comparing the production M1.0t with the tube amplifier, with himself acting as the test operator. We agreed, and Mr. Holt proved to be able to distinguish the two amplifiers by ear alone in those tests—also discussed in a letter from Mr. Carver published in Stereophile.

Despite the fact that the M-1.0t didn't sound the same as the target tube amplifier, we felt it offered a very high power output for the price. It therefore became a regularly recommended amplifier in Stereophile's biannual "Recommended Components" feature.

Far from "recanting" their original findings, as stated by Mr. Klein, Stereophile's staff reported what they had measured and what they had heard under carefully controlled conditions regarding the performance of the production Carver M-1.0t amplifier—just as they do with any component being reviewed. The fact that those findings were at odds with their earlier experience can be explained by the fact that the amplifiers auditioned were not identical: The 1985 tests involved a hand-tweaked prototype based on a Carver M-1.5 chassis; the 1987 tests involved a sample M-1.0t taken from the production line.

Contrary to what was suggested by Mr. Klein, Stereophile's premises is not that there are "mysterious audible differences that differentiate audiophile equipment from that produced by 'mass merchandisers' such as Carver." Indeed, as the magazine's editor, I feel that all audible differences can ultimately be explained by measurement, though showing the causal connection between what is heard and what is measured is not a trivial task. But it is important to try, as Mr. Carver himself said in the February 1990 Stereophile interview.

In his column, Mr. Klein drew his own conclusion from those "Carver Challenges:" that a magazine like Stereophile has to deny Mr. Carver's achievement on the grounds that "it wipes out the justification for overpriced and overdesigned high-end audio equipment." I draw a different, two-fold, conclusion. First, if a high-priced amplifier sounds better and measures better, its purchase is justifiable. Second, while it would indeed appear possible for Mr. Carver, on an individual, hand-tweaked basis, to achieve a null of -70 dB between two entirely different amplifiers, routinely repeating that feat in production is not possible (something implied by Mr. Carver's own statements). And, if it is not possible, then it is likely that such amplifiers could sound different from one another.

JOHN ATKINSON
Editor, Stereophile
Santa Fe, NM

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If you’re looking for ways to make your measurement tasks easier, then you’ll be interested in the Fluke Model 45 dual-display multimeter from Fluke (John Fluke Mfg. Co., Inc., P.O. Box 9090, Everett, WA 98206). The Fluke 45 makes it possible to measure two signal parameters from a single test connection. For example, you can measure the DC output of a power supply at the same time you measure the AC ripple on the output. Or you can measure the voltage of an AC signal at the same time you measure its frequency to, for example, determine an amplifier’s frequency response.

The Fluke 45 is a 5-digit 100,000-count meter that is housed in a plastic case that measures about 3 ¾ inches x 7 1/8 inches and weighs about 5 pounds. (An optional battery adds about two pounds.) Basic accuracy specifications are impressive: DC voltage, 0.02% DC current 0.05%.

If you’re more interested in speed than in accuracy, fast- and medium-speed measurements can be selected from the front panel. While the measurement speed can increase dramatically (20 readings per second in the fast mode as compared to 2 ½ per second in the slow mode) the accuracy and resolution of the display decreases (5 digits, 99,999 counts in the slow mode as compared to 3 ½ digits, 3000 counts in the fast mode).

What sets the Fluke 45 apart from the meter you have on your benchtop is its dual display. All measurement functions, including AC and DC voltage and current readings, resistance, and frequency, can be displayed on either the primary or the smaller secondary readout.

Function modifiers increase the versatility of the meter, and can speed up some important measurements (although they can be used only with the primary display). For example, when the REL or relative-readings modifier is used, the display shows the difference between the relative base and the input signal. If the relative base is 1000 ohms and the current reading is 1200 ohms, the display will show 200 ohms.

The dB modifier takes a voltage measurement, converts it to dBm (decibels measured with respect to one milliwatt) and displays the result on the primary display. The reference impedance can be set to any of 21 values from 2 ohms to 8000 ohms. When the reference impedance chosen is 2, 4, 8, or 16 ohms, the meter can be used to make audio power measurements.

The HOLD modifier lets you hold a measurement on the display when you might not want to take your eyes off the probes to read the display. It can be used separately or in combination with the MIN MAX or minimum maximum modifier, which lets the meter store the minimum and maximum inputs measured after the modifier is selected.

A compare or COMP modifier gives you an easy way to determine if a measurement falls within an acceptable range of values. Once the acceptable range is input (which can be done in several ways), each measurement shows either "HI," "Low," or "PASS" in the secondary display.

**Using the meter**

Although the Fluke 45 provides some complex measurement capabilities, it’s quite easy to use. For standard measurements, it’s operation is intuitive—even when using both the primary and secondary displays at the same time. Some of the more advanced functions take a little experience before their use becomes second nature. The meter’s front panel features a clean, logical layout. Its readout is a bright, easy-to-read vacuum-fluorescent display.

The dual display can speed up some test and measurement tasks dramatically. For example, by measuring DC voltage and current (which requires three leads), you can easily check a power supply’s load regulation. By measuring AC voltage and current, you can determine a transformer’s saturation. The second display can also be used to take full advantage of some of the meter’s functions. For example, when the meter is in it’s minimum/maximum mode, the secondary display can show the current measurement. Or in the hold mode, the running actual value can be shown in the secondary display while the previously held value is show in the primary display.

The Fluke 45 offers an RS-232 interface as standard equipment for sending or printing measurement data. Reading rates can be adjusted from one reading every 75 ms to one reading every 5.6 hours. An optional IEEE-488 interface is also available.

Not everyone needs the accuracy and convenience that the Fluke 45 offers. Even some who do might balk at the unit’s suggested retail price of $635. This is a case, however, of getting what you pay for.
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The Kit-5 solder-paste kit costs $89.00.—ESP Solder Plus, 14 Blackstone Valley Place, Lincoln, RI 02865-1145; Tel: 1-800-338-4353.

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The signal analyzer can send trace plots directly to printers and plotters through the rear-panel EIA-232D (RS-232C) connection. It will print to HP LaserJet and QuietJet printers and plotters including the HP 7550A and HP 7475A. It can transfer data from internal memory directly to a printer with a capacity of 500 state/trace combinations. A PC-based data-transport utility converts HP 3560A data to standard-data format for post-measurement analysis by other HP products.

Data can also be transported to third-party measurement and analysis packages using the included file utility.

The HP 3560A signal analyzer costs $7500.—Hewlett-Packard Company, Inquiries, 19310 Pruneridge Avenue, Cupertino, CA 95014; Tel: 1-800-752-0900.

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The LS-812 surge suppressor has a suggested retail price of $99.95.—Perma Power Electronics, Inc., 5601 West Howard Ave., Chicago, IL 60648; Tel: 312-763-0763; Fax: 312-763-8330.

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EVER SINCE IT WAS DEMONSTRATED at the 1939 World's Fair, the picture phone was something placed at the top of many people's wish list. Unfortunately it remained out of reach of the average person—even those who could afford the expense often could not afford the physical space required for such a system. However, videophones were recently made available to consumers at affordable prices, thanks to a new IC that greatly reduces the cost and size of a videophone system. And even though it was possible to build a videophone before the advent of this new chip (see Radio-Electronics, August 1982), it's never been easier than now.

This article presents a videophone, or videomodem, that transmits and receives still video frames over the phone line, in high-resolution (200 × 242 pixel) video with a six-bit (60-level) gray scale. It provides a substantially better picture than the low-resolution 96 × 96 pixel units with limited gray scale that you may have seen.

The project basically consists of the videophone base unit; you can buy it as a bare board in kit form or as an assembled and tested unit. Among other components, the board contains one IC that does all of the dirty work. The base unit is connected to a small CCD camera module and Sony Watchman. However, the unit uses standard monochrome NTSC-type 1-volt p-p video for the input and output, so if you already have a standard video camera (or camcorder) and monitor, you can use them and save money.

To send or receive a video image, you do, of course, need two complete units, or at least know somebody else who is building one. When you order the PC board from Colby Systems, you will receive a list of users that have Colby videophone units. That will give you contacts to help get your unit up and running and people who you can exchange pictures with. If you would like to have your name and phone number included on this
list, please let Colby Systems know about it.

**Uses**

The videophone has many potential uses other than simply showing off the kids to the grandparents. Such uses might be a commercial artist and page layout person collaborating on a catalog page layout, or perhaps a construction foreman observing a detail on location to an architect in his office half way around the world.

An automatic mode makes another interesting application possible: the videophone can be used to remotely monitor your house or business, or perhaps a volume gauge on an oil pumping station. By setting up a video camera to view an area, the videophone’s automatic mode could be used to send a new video frame every 38 seconds over an ordinary phone line.

However, that scheme would work only if you had called another videophone and left the phone off the hook while you were away. That would be expensive to have a phone line in use 24 hours a day—but for certain monitoring situations, the cost might be acceptable. For in-house lines, it might be a convenient way to remotely monitor something without running new wires.

Another way to do monitoring...

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**FIG. 1—THE VIDEOPHONE CONSISTS OF THREE SECTIONS:** the CCD camera module at the top, the video monitor, and the base unit that contains the videophone circuitry.

---

**All resistors are 1/8-watt, 5%, unless otherwise noted.**

- R1—510 ohms (× 4) 8-pin SIP
- R2—390 ohms (× 5) 10-pin SIP
- R3—10,000 ohms (× 4) 8-pin SIP
- R4—4700 ohms (× 5) 10-pin SIP
- R5—1000 ohms (× 7) 8-pin SIP, pin 1 common
- R6—1000 ohms (× 5) 10-pin SIP
- R7—1000 ohms (× 3) 6-pin SIP
- R8—110,000 ohms (× 3) 6-pin SIP
- R9—680 ohms
- R10, R19—6800 ohms
- R11—27 ohms
- R12—2000 ohms
- R13—3900 ohms
- R14—8200 ohms
- R15—15,000 ohms
- R16—27,000 ohms
- R17—4700 ohms
- R18—1800 ohms
- R20—75 ohms

**Capacitors**

- C1, C4, C5, C15, C17, C20—470 µF, 16 volts, radial electrolytic
- C2, C3, C9, C18—100 µF, 16 volts, radial electrolytic
- C6, C10, C24—10 µF, 35 volts, radial electrolytic
- C7, C12, C13, C14, C21, C22, C23—0.1 µF, monolithic
- C8—0.1 µF, 200 volts, polyester
- C11—0.05 µF, ceramic
- C16—not used
- C19—4.7 µF, radial electrolytic

**Semiconductors**

- IC1, IC2—7805 5-volt regulator
- IC3—MP7682 A-to-D converter
- IC4—LM324 quad op-amp
- IC5, IC6—MB81464-12 64K × 4 DRAM
- IC7—PMC-VP video controller
- IC9—GAL16V8 custom A-to-D filter
- IC9—LM355 low-power voltage comparator
- DN1—1N914 (× 8) diode network (contains D1, D3, D9—D13, D16)
- D2, D4, D5—1N4001 diode
- D6—D8, D14, D15—not used
- LED1—LED4—miniature red light-emitting diode
- Q1, Q2, Q5—2N2222 NPN transistor
- Q3, Q4—2N3906 PNP transistor

**Other components**

- FB1—FB9—ferrite bead over jumper wire
- J1—coaxial power jack
- J2, J6—RCA jack
- J3—miniature phone jack
- J4, J5—modular phone jack
- J7—miniature phone jack
- J8, J9—3-pin header jumper block
- T1—600/600 ohm audio isolation transformer, 1500 volt rating
- XTAL1—3.57 MHz crystal
- S1—SPST switch
- S2—SS—momentary pushbutton
- RY1—SPST relay, 12-volt coil

**Miscellaneous:** four 3/8-inch LED stand-offs, PC board, 120 VAC to 12 VDC adapter, three 18-pin IC sockets, one 14-pin IC socket, one 20-pin IC socket, one 48-pin IC socket, one 8-pin IC socket, one 16-pin IC socket, jumper wire, project case, video camera, video monitor, coaxial interconnecting leads (for power and video between base unit and monitor and camera), solder, etc.

**Note:** The following items are available from Colby Systems Corporation, 2991 Alexis Drive, Palo Alto, California, 94304—(415) 941-9090, Fax (415) 949-1019. Send check or US postal money order. Checks take 2–3 weeks to clear. California residents add 7.25% sales tax. All prices include FOB Palo Alto or Clovis, California. Shipping charges are UPS ground, continental US only, and insurance is included. Add $5.00 handling fee to each order.

- Bare PC board (PCB-VP)—$129.99 + $3.50 S&H
- PMC-VP video controller IC (PMC-U7)—$49.99 + $3.50 S&H
- Kit of all other IC's including preprogrammed IC8 (Kit IC-8)—$39.99 + $3.50 S&H
- Kit of all discrete components (resistors, capacitors, diodes, transistors, crystal, transformer, jacks, switches, LED's, relay) (Kit-VP)—$49.99 + $3.50 S&H
- AC adapter (VP-AC)—$12.99 + $4.50 S&H
- Kit of all of the above parts (everything to build one complete videophone base unit, except case) (Kit-unit)—$169.99 + $7.50 S&H
- 240 x 320 line CCD camera module (XP-CCD-1)—$299.99 + $5.50 S&H
- Sony 2.7-inch monitor (Sony-2) —$129.99 + $4.50 S&H
- Videophone-to-monitor power & video cable (PVC-M)—$9.95 + $3.50 S&H
- Videophone-to-camera power & video cable (PVC-C)—$9.95 + $3.50 S&H
- All of the above items ordered at one time (Kit-complete)—$599.99 + $13.25 S&H
- A VHS video tape showing step-by-step assembly and testing, including sample pictures—$19.95 + $4.75 S&H
- An assembled and tested version of the videophone will be available as soon as FCC testing and registration are completed. Write Colby Systems for price list.

The following items are available from Gettys Electronics, 22018 Frontier Road, Clovis, CA 93612—(209) 299-7828.

- Round video camera case (Cam-case-1)—$29.99 + $5.50 S&H
- Videophone case with metal bottom and plastic top (VP-case-1)—$34.99 + $5.50 S&H.
is to connect the output of the videophone in parallel with a phone answering machine with no message—or perhaps a short message to tell you which monitoring station you have reached. After the outgoing message, record 2 or 3 minutes of silence. (You must use the older type of machine that lets you control the end of the outgoing message.) Then you will be able to use the answering machine for both the announcement function and the off-hook timer, to allow the videophone to output one or more frames of video.

Overview

As shown in Fig. 1, the videophone consists of three main sections: the CCD camera module at the top, the video monitor, and the base unit that contains the videophone circuitry. Because the camera module is mounted on the TV's antenna, and because the antenna isn't needed when feeding the monitor with a direct video input, the camera can be easily pointed in any direction.

Take a look at the block diagram in Fig. 2. The video output of any standard video camera, camcorder, VCR, videodisc, etc., is fed into J2; it is then amplified, digitized, and converted to a series of audio tones to be sent over standard telephone lines. It takes 9 to 12 seconds to send or receive a still video picture, during which time both phones are silenced. The data being sent are pulse-width modulated with data rates of about 32 kilobits per second. The data transmission rate is about half that of the new
ISDN system (see Radio-Electronics, May and June 1989), but it works on standard phone lines. Each baud is one pixel, with up to 6 bits of gray scale per baud—12 bits per cycle are sent since one baud is ½ cycle in length.

The camera
The video camera used with the prototype unit is a pre-assembled and tested Chinon CCD module; it consists of two very small PC boards with surface-mounted parts on both sides of each board; it measures $1 \times 1\frac{3}{16} \times 2\frac{3}{4}$ inches, and weighs an incredible 2.1 oz. (60 grams). The camera is shown inside its circular housing in Fig. 3. Included is a fixed-focus, 4.5 mm, F1.8 lens, which is somewhere between normal and wide angle. It provides a good compromise for use in this application; a person’s face fills about $\frac{2}{3}$ of the screen at a distance of 1½ to 2 feet from the camera. Depth of field is 6 inches to infinity, which means that everything farther than 6 inches from the camera will be in focus.

The module has a built-in electronic shutter with a range of 0 to 1.5 volts is therewith set between 0 and 100,000, which is output code of 0. An analog input of 0 volts produces an output code of 1 volt p-p into 75 ohms.

The camera operates on an input voltage of 7 to 12 volts DC at about 75 mA. The videophone base unit provides power for the camera from J3. A jumper block (J9) inside the unit allows either 12 or 5 volts DC to be available at J3. If you use the same camera we did, be sure to set the J9 jumper to the A-B position (12 volts). The B-C position provides 5 volts at J3.

Mounted in a circular housing, the camera module attaches to the monitor’s antenna with nylon clamps. The mounting arrangement allows the camera to be pointed in any direction, which is a lot more versatile than fixed-camera type systems where the subject must be moved into the field of view of the camera instead of the other way around.

The camera module is available from the source mentioned in the parts list. However, if you already have a video camera that puts out a 1-volt p-p standard composite video signal, you are free to use it instead, but you’ll be losing the compactness and ease of aiming the camera when you do that.

The TV/monitor module
The TV monitor we used is an un-modified, off-the-shelf, Sony black-and-white Watchman TV (model FD-250). The unit has a composite-video input jack so it can directly accept the video from the videophone base unit. The picture is surprisingly sharp and clear, but that partially depends on the quality of the camera you use.

The monitor attaches to the top of the base unit with a bracket and a strip of velcro. The bracket attaches to the monitor’s rear support foot. The monitor is available from the source mentioned in the parts list and, more than likely, at a store near you.

The base unit
The base unit contains the electronics for the videophone. It also contains a double-sided PC board with eight ICs and other assorted parts. The back panel contains an on/off switch and input and output jacks for video, power, and the phone line. The front panel contains four push-button switches and indicator LEDs.

The schematic for the circuit is shown in Fig. 4; let’s first discuss how a video image is sent from one videophone to another. The video signal from the camera enters J2 where it is coupled by C1 and R4-c to the input of IC3, a flash A/D converter. The flash A/D converter is used to convert the incoming analog video into a digital signal.

A block diagram of the flash A/D is shown in Fig. 5. The input signal is connected to the non-inverting inputs of 64 comparators. The inverting side of each input comparator is connected to one resistor in a series ladder configuration. The resistor ladder is connected to an external reference-voltage generator (IC4, Q3, and Q2), which keeps the input of each comparator in the chain referenced to a slightly higher voltage than its neighbor. An analog input is applied to the non-inverting input of the comparators. The comparators that have a reference voltage on their inverting inputs that is greater than the video voltage at that point in time will switch to a different output state. The outputs of the 64 comparators are fed into the 64 inputs of the latches which are enabled by every clock pulse at a rate of 3.58 MHz.

At this point the input signal has been converted a group of 64 on-off conditions. The 64 on-off levels are then encoded into a 6-bit byte which is output through a flip-flop and three-state buffer for each of the six bits. An analog input of 0 volts produces an output code of 0. An analog input of 1.5 volts produces an output code of 100,000 (with a $V_{\text{REF}}$ of 3.2 volts).

The 6-bit digital output code of a number between 0 and 100,000 representing a video input level between 0 and 1.5 volts is then fed into pins 27–32 of IC7, the
FIG. 4—SCHEMATIC FOR THE VIDEOPHONE CIRCUIT. The video signal enters J2 where it is coupled by C1 and R4-c to the input of IC3, a flash A/D converter.

videophone controller chip. Inside this 48-pin IC, the digital input is converted to a series of audio tones in the 1200- to 3450-Hz range and fed out of pin 23 to the primary of transformer T1, which isolates and couples the signal to the telephone line through relay RY1 and RJ-11 jack.
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FIG. 5—THE FLASH A/D CONVERTER is used to convert the incoming analog video signal into a digital signal. The input signal is connected to the non-inverting inputs of 64 comparators.

J5. At the start of a transmission, there is a short 3442-Hz tone burst that triggers the receiving videophone to go into the receive mode.

Receiving an image

When a 3442-Hz tone is present at pin 24 of IC7, it automatically switches the system into the receive mode. The tones coming from the phone line at J5 (representing video information) are coupled by C8 to T1. The secondary of T1 is connected to the differential inputs of IC9, an LM393 op-amp, which amplifies the audio tones and presents them to pin 24 of IC7.

The video controller chip (IC7) then converts the audio tones into 6-bit digital words and stores the video frame in digital form in DRAM’s IC5 and IC6. The digital data is then output to IC8, a proprietary Colby programmable logic array (PAL), which functions as a D/A converter and filter. The PAL converts the digital signal back into composite video which is further amplified by Q4 and Q5 and then coupled by C15 to the video output jack, J6. The video format is standard NTSC (or PAL on special order), so it can be fed into any video tape recorder or video monitor.

The audio tones containing the video information (available at J5) can also be recorded on an ordinary audio cassette if desired. If you do that, you must attenuate the signal out of J5 if you want to run it into the recorder’s microphone input. For playback, the signal out of the recorder must be within the videophone’s input range of 250 mV to 5 volts p-p.

Power distribution

A 120 volt AC to 12 volt DC, 1-amp AC adapter (a 220-volt version is also available) provides power for the videophone, and it is input at J1. The voltage passes through D1, a polarity protecting diode, to S1, the main power switch. From there, the 12 volts is applied to 7805 voltage regulators IC1 and IC2; IC2 supplies +5 volts to most of the circuitry, and IC1 puts out 5.7 volts because of D4 in its ground return path. Jumper blocks J8 and J9 are used to select the output voltage to power the camera and monitor.

If you use the Sony monitor, place jumper on J8 in the B-C position. That will supply 5.7 volts DC at J7; if you use a 12-volt monitor, place the jumper in the A-B position. Maximum current out of J7 is 450 mA at 5.7 volts or 650 mA at 12 volts. (That also depends on how much power you are drawing out of J3 for the camera power.)

If you use the CCD camera module mentioned in this article, set the jumper on J9 to the A-B position to provide +12 V to J3 for the camera (the B-C position provides 5 volts to J3). If you use different cameras or monitors, be careful to observe the power ratings of both the AC adapter (which is rated 12V at 1 amp, or 12 watts), IC1 and IC2 which, without a heatsink should not put out more than 55 mA each.

The videophone base unit requires 12 volts at 150 mA, or 1.8 watts; the CCD camera requires 12 volts at 75 mA, or 0.9 watts; and the Sony monitor requires 6 volts at about 380 mA, or 2.3 watts; the three units total about 5 watts. Other camera/monitor combinations may require the use of separate AC adapters to supply power to them. Of course, when you use separate adapters, you would then lose the ability to turn all three units on and off with the one power switch on the rear of the videophone.

Next month

That’s all we have room for this month. In the meantime, we have provided the list of parts you’ll need, as well as places to get them. You might want to obtain everything you need right now, so that next month you’ll be able to complete this project. We’ll be going over all of the construction details, as well as the hookup and operation of the unit.
TURN YOUR PC INTO A UNIVERSAL FREQUENCY COUNTER

Build a frequency-counter board that operates in a Windows environment in your personal computer.

JOEY GRASTY and BILL SCHULZ

LAST MONTH WE STARTED TALKING about the PC10's circuitry. So let's pick up where we left off. The pin description and equations for the PAL (IC4), mentioned last month, is shown in Listing 1.

Shown in Fig. 3 are two 74HCT374 eight-bit registers (IC9 and IC10) that control operation of the PC10. The registers are of the write-only type: they may not be read back. Register 1 (REG1) controls the source selection for inputs A and B of the OE10 and the prescale used for frequency measurements. Register 2 (REG2) selects the input source for the pulse-width measurement, the pulse-width polarity, and hysteresis and gain levels for the input amplifiers. See the PC10 register map (Table 2) for more details.

Input signals to the A and B inputs on the OE10 are selected using 74AC11151 eight-to-one multiplexers (IC16-IC18). The input-A multiplexer, IC16, controlled by ASEL2-ASEL0 in register 1, determines which input signal drives input A. The output of the multiplexer drives one input of relay RY3, which selects either the multiplexer output or the output of the 50-ohm amplifier. That circuit is required because the 50-ohm amplifier generates signals that are higher in frequency than the multiplexer can pass. Relay RY3 is also controlled by ANSEL2–ANSEL0, decoded by IC23-a, the 74ALS12 NAND gate, which in turn drives Q3. Similarly, BSEL2–BSEL0 control which input signal drives input B with multiplexer IC17, but no relay is required.

An AD7528 (IC11) dual 8-bit multiplying digital-to-analog converter (DAC) is used to provide a threshold voltage for each high impedance amplifier. That type of DAC provides only a current output, so each of the two outputs is converted to a voltage with one section of IC12 (IC12-a and IC12-b), a TL074 quad operational amplifier. Two additional op-amps (IC12-c and IC12-d), configured as adders, convert the unipolar outputs of the first two op-amps to bipolar signals. The 2.5-volt reference voltage for each DAC is provided by IC13, and AD580 voltage reference.

The addition of an edge-detection circuit (Fig. 4) allows a pulse width to be measured. Two 74HCT74 D-type flip flops (IC19-a and -b) and two 74HC00 NAND gates (IC20-a and -b) form rising and falling edge detection circuits: IC20-a provides an active-low pulse, one timebase clock long, each time a rising edge is detected, and IC20-b provides a pulse for each falling edge. A 74HC157 quad two-input multiplexer (IC21) selects which edge detector goes to input C or D of the OE10. If a rising-edge pulse is sent to input C and a falling-edge pulse is sent to input D, positive-going pulse widths will be measured. The opposite selection measures negative-going pulse widths.

The PC10 provides a single 50-ohm input amplifier (see Fig. 5), typically used for input from RF circuits. The incoming signal is first amplified by IC25 and IC26, monolithic microwave integrated circuit (MMIC) 50-ohm amplifiers, each with a gain of 11 to 20.
Each amplifier is powered from +5 volts through a 75-ohm resistor, a 100-µF inductor, and several decoupling capacitors. Those components supply power to each amplifier and prevent high-frequency signals from entering the power-supply rails.

In order to provide frequency-measurement capabilities far higher than the input capabilities of the OE10, prescaling has been provided. The MMIC amplifiers drive two cascaded prescalers: a UP582C divide-by-four prescaler (IC27), and a general-purpose CA3199E divide-by-four prescaler (IC28). When the two are cascaded, divide-by-16 prescaling is performed, allowing frequencies above 3 GHz to be measured.

Selection of the prescalers is controlled by the PREI and PREO signals from register 1. Those signals drive an LM339 quad voltage comparator (IC24), with a 2.5-volt threshold set by R15 and R16. If direct frequency measurements are required, PREI and PREO are both set to logic 0. The comparators' inputs are then driven below the threshold voltage, causing Q1 and Q2 to turn off. That causes relays RY1 and RY2 to be deactivated, turning off both prescalers. Diode D1 then routes the amplified signal to a third MMIC amplifier, IC11, before going to RY3, where the signal is sent on to the OE10. An input-bias adjustment potentiometer R31 is used to center the output of the MMIC amplifier at approximately 1.5 volts for best performance.

If measurements prescaled by 4 are required, PREI is set to logic 0 and PREO set to logic 1. That causes comparator IC24-c to activate, turning on Q1 and RY1. That forces IC27 to begin prescaling the signal, deactivates D1, activates D2, and routes the output of prescaler IC27 to the MMIC amplifier. Conversely, if measurements prescaled by 16 are required, PREI must be set to logic 1 and PREO to logic 0. That turns on both relays, causing both prescalers to start. Diodes D1 and D2 are then deactivated, sending the output of the second prescaler IC28 to the MMIC amplifier. The PC10's bypass capacitors and unused logic gates are shown in Fig. 6.

**AP10H amplifier board**

Because the insides of personal computers are electrically noisy, no high-impedance amplifiers are provided on the PC10. Instead, two high-impedance amplifiers are provided on an optional external amplifier board, the AP10H. That board, shown in Fig. 7, contains two identical 100-MHz high-impedance amplifiers, each with input attenuation, a low-pass filter for measuring low-frequency signals, and a variable threshold-level adjust. We will therefore discuss only one of the amplifier circuits.

Starting from the input BNC connector (J1), the input signal is terminated by R1 and R2 and C2 and C3. An attenuation of 20 dB is provided if RY1 is enabled. The signal is then sent through the input-protection circuits (D1-D4, R4, and R5) into the gate of an RF FET transistor Q1, which acts as an impedance converter, providing a low-impedance source to the remainder of the amplifier. The signal is then amplified by 20 dB by MMIC amplifier IC1. Relay RY2, when activated by Q3, low-pass filters the signal to provide noise-free measurements of low-frequency audio signals. Potentiometer R9 is

---

**LISTING 1**

<table>
<thead>
<tr>
<th>DEVICE</th>
<th>TITLE</th>
</tr>
</thead>
<tbody>
<tr>
<td>20V8;</td>
<td>PC COUNTER BOARD SELECTION LOGIC;</td>
</tr>
</tbody>
</table>

| PIN 1 | PIN 2 | PIN 3 | PIN 4 | PIN 5 | PIN 6 | PIN 7 | PIN 8 | PIN 9 | PIN 10 | PIN 11 | PIN 12 | PIN 13 | PIN 14 | PIN 15 | PIN 16 | PIN 17 | PIN 18 | PIN 19 | PIN 20 | PIN 21 | PIN 22 | PIN 23 |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| = AO; | = A1; | = A2; | = A3; | = A4; | = A5; | = IOW; | = IOR; | = AEN; | = S6; | = S7; | = S8; | = S9; | = IO; | = G; | = RT; | = COMP; | = DAC; | = REG2; | = REG1; | = OE10; | = IOW; | = IOR; |


**!OE10 = !A3 & !A5 & S6 & S7 & S8 & S9 & !AEN & !IOW & IOR;**

**!G = !A3 & !A5 & S6 & S7 & S8 & S9 & !AEN & !IOW & IOR;**

**!RT = RESET;**

adjusted so that the input to the variable threshold circuit formed around voltage-comparator IC2 will be 0 volts.

The variable threshold circuit allows the user to position the threshold to the best value to ensure accurate, noise-free measurements. The circuit provides 50 mV of hysteresis to give immunity to noise. The hysteresis window is centered around the threshold voltage provided by the dual-threshold DAC's on the
PC10. The threshold may be changed as required by the user. The LT1016 voltage comparator (IC2) is capable of operating at frequencies greater than 50 MHz. For better performance, a MAX9689 comparator may be used.

Two outputs are provided for each high-impedance amplifier from the LT1016: the true signal and its inverse. The desired output can be selected by the user. Both output signals are buffered by two 74LS04 inverters (IC3-f and IC3-a for the inverted output, and IC3-e and IC3-b for the non-inverted output) before being sent over a cable to the PC10. Input control signals from the PC10 at the DB25 connector P1 are also buffered by 74LS04 inverters. Table 3 is a description of the pin assignments for P1, the female DB25 connector that is used to connect the amplifier board to the PC10.

Software
The PC10 program, like most Windows programs, has a main window from which all functions of the program are controlled. In the upper-left corner is the control-menu box used to move, resize, close windows, or switch to another program. In the upper-right corner is the minimize button, which reduces the program to its OEl icon. The program name is shown in the title bar between the control-menu box and the minimize button. Beneath the title bar is the menu bar, which is used to select functions that do not appear on the main window.

The main window contains the main counter display, a mode-select group, gate/average/resolution select group, and three control buttons. The main counter display shows the results of the last measurement and its units. The mode-select group allows the user to choose which of five types of measurements are to be performed. The gate/average/resolution box allows the user to determine the gate time (frequency measurements), number of measurements to average (period, time interval, and pulse width), or the resolution (ratio measurements). For frequency or period measurements, reciprocal measurements may be selected by activating the reciprocal check box.

For frequency measurements, the gate group will be shown. The user can select four gate times.
FIG. 4—AN EDGE-DETECTION CIRCUIT allows a pulse width to be measured.

FIG. 5—THE PC10 PROVIDES a single 50-ohm input amplifier typically used for input from RF circuits.
FIG. 6—HERE ARE THE PC10’s bypass capacitors and unused logic gates.

All resistors are 1/4-watt, 5%, unless otherwise noted
R1—2200 ohms
R2, R30, R32—not used
R3—R6, R21—10,000 ohms, 1/8 watt
R7, R10—4990 ohms, 1%
R8, R9—10,000 ohms, 1%
R11—R14—20,000 ohms, 1%
R15, R16, R21—10,000 ohms, 1/8 watt
R17, R30—75,000 ohms, 1/8 watt
R18, R20—1000 ohms, 1/8 watt
R19—33,000 ohms, 1/8 watt
R22, R23—75 ohms, chip resistor
R24—91 ohms, chip resistor
R25—R28—1000 ohms, chip resistor
R29—47 ohms, chip resistor
R31—100,000-ohm potentiometer

Capacitors
C1, C3, C4—10 µF, 25 volts, radial electrolytic
C2—22 µF, 25 volts, radial electrolytic
C5—C7, C9—C12, C14, C16—C19, C24, C26—C33—0.1 µF, 50 volts, monolithic
C6, C13, C15, C20—C23, C25, C51, C54, C59, C64—C66, C68—not used
C34, C36—330 pF, NPO
C35—47 pF, NPO
C37, C38—8.2 pF, NPO
C39—2—7 pF NPO trimmer

PC10 PARTS LIST
C40—C50, C52, C53, C67—0.001 µF, 1206 chip capacitor
C55, C56, C58, C60—C63—0.1 µF, 1206 chip capacitor
C57—47 µF, 16 volts, radial electrolytic

Semiconductors
IC1—74HCT245 octal tristate transceiver
IC2, IC3—74HCT244 octal tristate buffer
IC4—20LB programmable array logic (PAL)
IC5—GE10 application-specific integrated circuit (ASIC)
IC6, IC8, IC14, IC15—not used
IC7—74HCT225 tristate quad buffer
IC9, IC10—74HC374 tristate octal D-type flip-flop
IC11—AD7528 dual 8-bit multiplying digital-to-analog converter (DAC)
IC12—TL074 quad op-amp
IC13—AD580 voltage reference
IC16—IC18—74AC1151 eight-to-one multiplexer
IC19—74HCT74 D-type flip-flop
IC20—74HC00 quad NAND gate
IC21—74HC157 quad two-input multiplexer
IC22—74LS86 quad XOR gate
IC23—74ALS12 triple 3-input NAND gate
IC24—LM339 quad voltage comparator
IC25, IC26, IC29—MAR6 MMIC
IC27—UPB582C high-performance divide-by-four prescaler
IC28—CA3199E general-purpose divide-by-four prescaler
D1, D2—HSMP3800 surface-mount pin diode
Q1—Q3—2N2907 PNP transistor
Q4, Q5—PN2369 NPN transistor

Other components
J1—BNC bulkhead (R141-306)
J2—SMB right-angle PC board connector (R114-665)
R1—R13—2N2907 PNP transistor
R4, R5—PN2369 NPN transistor

Miscellaneous: seven 14-pin IC sockets, four 16-pin IC sockets, six 20-pin IC sockets, one 24-pin IC socket (0.3-inches), one PLCC 44-pin IC socket, one G57 modified stamped PC bracket (Globe Mfg.), one lug (Zierick #334), 6-inch 50-ohm coaxial cable RG187 (0.1-inch diameter), PC board, solder, etc.
FIG. 7—THE INSIDES OF PERSONAL COMPUTERS are electrically noisy, so there are no high-impedance amplifiers provided on the PC10 board. Instead, two high-impedance amplifiers are provided on this AP1OH optional external amplifier board. It contains two identical 100-MHz high-impedance amplifiers, each with input attenuation, a low-pass filter for measuring low-frequency signals, and a variable threshold-level adjust.
0.01, 0.1, 1.0, or 10.0 seconds, or use the scroll bar to select any gate time between 0.1 and 28 seconds. For period, time-interval, or pulse-width measurements, the average group will appear. The user can then select 1, 10, 100, or 1000 measurements averaged to give the displayed result. The scroll bar can also be used to select any number of averages from 10 to 2800. Finally, for ratio measurements, the resolution group will appear, allowing the user to select resolutions of 100 kHz, 1 MHz, 10 MHz, or 100 MHz, or use the scroll bar for any resolution from 1 MHz to 280 MHz.

The three pushbuttons are used to start and stop measurements. The start button causes the counter to take continuous measurements until the stop button is clicked. Single measurements may be made by pressing the single button.

The menu bar has four menus: File, Configuration, Logging, and SetRadio. The File menu has two functions: Exit, used to end the program, and About, which shows some information about the program. The Configuration menu allows the user to set up the PC10 to take measurements. The Configuration menu has five functions: Input Selection, Calibrate, Units, Fonts, and Hardware. Each function causes a dialog box to appear. The Logging menu has one item, To File, which allows the user to specify what file measurements will be logged. The last menu, SetRadio, has four items: Radio, Threshold, Enable or Disable, and Manual Set. Each of those menu items are described as follows.

When the Input Selection item is selected from the Configuration menu, the Input Assignment dialog box appears. That dialog box allows the user to set which input amplifier is to be used and what configuration is to be selected. Two groups are available: the Input group and the Reference group. For frequency, period, or pulse-width measurements, only the Input group is active. Both groups are active when time-interval or ratio measurements are selected.

First, the user will select which input (A or B) to use. If A is selected, the user has the choice of either the low-impedance amplifier built-in to the PC10 or the A amplifier high-impedance amplifier on the AH10 board. If the low-impedance amplifier is selected.

Note: The following items are available from Optoelectronics Inc., 5821 N.E. 14th Ave., Ft. Lauderdale, FL 33334 (800) 327-5912, in Florida (305) 771-2050. FAX (305) 771-2052: Complete Kit of all parts to build the PC10, including software, $299; OE10 ASIC, $49; PC10 PC board, $59; software, $5; programmed PAL, $19; assembled and tested PC10, $339; complete kit of all parts to build the AP10H, $179; AP10H PC board, $39; machined and painted cabinet, $49; 6-foot 25-conductor straight-through cable, $20; assembled and tested AP10H, $229. Send SASE for priced out parts list. Include 5% shipping and 6% sales tax when shipped to Florida address.

### AP10H Parts List

<table>
<thead>
<tr>
<th>Pin</th>
<th>Pin Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1, 14</td>
<td>VCC</td>
<td>+5V supply from PC Bus</td>
</tr>
<tr>
<td>2, 5, 6</td>
<td>GND</td>
<td>Ground from PC Bus</td>
</tr>
<tr>
<td>3, 13, 15, 18, 19</td>
<td>-5V</td>
<td>-5V from PC Bus</td>
</tr>
<tr>
<td>7, 20</td>
<td>AHIPOS</td>
<td>Input from high impedance amplifier, not inverted, A input, TTL input levels</td>
</tr>
<tr>
<td>8, 21</td>
<td>AHINEG</td>
<td>Input from high impedance amplifier, inverted, A input, TTL input levels</td>
</tr>
<tr>
<td>3, 16</td>
<td>BHIPOS</td>
<td>Input from high impedance amplifier, not inverted, B input, TTL input levels</td>
</tr>
<tr>
<td>4, 17</td>
<td>BHINEG</td>
<td>Input from high impedance amplifier, inverted, B input, TTL input levels</td>
</tr>
<tr>
<td>12</td>
<td>ALEVEL</td>
<td>Comparison voltage level, A input, –2.5 to 2.5 volts</td>
</tr>
<tr>
<td>25</td>
<td>BLEVEL</td>
<td>Comparison voltage level, B input, –2.5 to 2.5 volts</td>
</tr>
<tr>
<td>24</td>
<td>AHYST</td>
<td>Hysteresis control, A input, 0 LOW hysteresis, 1 HIGH hysteresis, TTL output levels</td>
</tr>
<tr>
<td>11</td>
<td>BHYST</td>
<td>Hysteresis control, B input, 0 LOW hysteresis, 1 HIGH hysteresis, TTL output levels</td>
</tr>
<tr>
<td>10</td>
<td>GAINA</td>
<td>Gain control, A input, 0 LOW gain, 1 HIGH gain, TTL output levels</td>
</tr>
<tr>
<td>23</td>
<td>GAINB</td>
<td>Gain control, B input, 0 LOW gain, 1 HIGH gain, TTL output levels</td>
</tr>
</tbody>
</table>

**Capacitors**
- C1, C9–C11, C19, C20, C23–C26, C29, C30–0.1 μF, 50 volts, monolithic
- C2, C12–3.3 pF, chip
- C3, C13–33 pF, chip
- C4, C14–22 pF, monolithic
- C5, C8, C15, C19–μF, tantalum
- C6, C16–220 pF, chip
- C7, C17, C27, C28—not used
- C21, C22–220 μF, axial electrolytic

**Semiconductors**
- IC1, IC4–MA16 MMIC
- IC2, IC5–LT1016 voltage comparator
- IC3, IC6–74LS04 inverter
- D1–D8–1N6263A diode
- Q1, Q4–2N4416 RF FET transistor
- Q2, Q5–2N2222 NPN transistor
- Q3, Q6–2N2907 PNP transistor

**Other components**
- J1, J2–CP1094U BNC connector, modified
- RY1–RY4–SPDT DIP reed relay, 5-volt coil (form C)
- L1–L4–100 μH choke
- J3–male DB25 connector

**Miscellaneous**
- PC board, suitable enclosure, 6-foot 25-conductor straight-through cable, solder, etc.

**TABLE 3—PC10 TO AP10H AMPLIFIER BOARD CONNECTOR**

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1, 14</td>
<td>VCC</td>
<td>+5V supply from PC Bus</td>
</tr>
<tr>
<td>2, 5, 6</td>
<td>GND</td>
<td>Ground from PC Bus</td>
</tr>
<tr>
<td>3, 13, 15, 18, 19</td>
<td>-5V</td>
<td>-5V from PC Bus</td>
</tr>
<tr>
<td>7, 20</td>
<td>AHIPOS</td>
<td>Input from high impedance amplifier, not inverted, A input, TTL input levels</td>
</tr>
<tr>
<td>8, 21</td>
<td>AHINEG</td>
<td>Input from high impedance amplifier, inverted, A input, TTL input levels</td>
</tr>
<tr>
<td>3, 16</td>
<td>BHIPOS</td>
<td>Input from high impedance amplifier, not inverted, B input, TTL input levels</td>
</tr>
<tr>
<td>4, 17</td>
<td>BHINEG</td>
<td>Input from high impedance amplifier, inverted, B input, TTL input levels</td>
</tr>
<tr>
<td>12</td>
<td>ALEVEL</td>
<td>Comparison voltage level, A input, –2.5 to 2.5 volts</td>
</tr>
<tr>
<td>25</td>
<td>BLEVEL</td>
<td>Comparison voltage level, B input, –2.5 to 2.5 volts</td>
</tr>
<tr>
<td>24</td>
<td>AHYST</td>
<td>Hysteresis control, A input, 0 LOW hysteresis, 1 HIGH hysteresis, TTL output levels</td>
</tr>
<tr>
<td>11</td>
<td>BHYST</td>
<td>Hysteresis control, B input, 0 LOW hysteresis, 1 HIGH hysteresis, TTL output levels</td>
</tr>
<tr>
<td>10</td>
<td>GAINA</td>
<td>Gain control, A input, 0 LOW gain, 1 HIGH gain, TTL output levels</td>
</tr>
<tr>
<td>23</td>
<td>GAINB</td>
<td>Gain control, B input, 0 LOW gain, 1 HIGH gain, TTL output levels</td>
</tr>
</tbody>
</table>
FOIL PATTERN for the component side of the PC10 board.

the user can choose no prescale, prescale by 4 or prescale by 16. The remaining items are grayed, indicating that they may not be chosen. If the high-impedance amplifier is chosen, the user can choose to include low-pass filtering. Signal polarity may be set to positive or negative. Last, the voltage threshold may by changed to any value between -0.5 and +2.5 volts.

The Calibrate dialog box appears when the Configuration menu item "Calibrate" is chosen. That dialog box allows the user to calibrate in software the time-base of the PC10 from an external frequency source. Before selecting this item, the user must first set up the Input Assignments dialog for the proper input. The user then enters the reference frequency and hits the OK push-button. The dialog box will disappear and a dialog box giving the measured reference frequency will appear after about 25 seconds. The user can confirm that measurement by hitting the OK button. The reference frequency will then be stored in the WIN.INI file in the Counter section.

The Units dialog box, which appears when the Units item is selected from the Configuration menu, allows the unit of measurement to be selected. For frequency measurement, Hz, kHz, MHz, GHz, and RPM/CPM (revolutions or cycles per minute) may be chosen. For period, interval and pulse-width measurements, seconds, milliseconds, microseconds, or nanoseconds may be selected.

The Fonts dialog box appears whenever the Fonts item is selected from the Configuration menu. That dialog box allows the user to select the font and its size to match the user's video configuration. The selected font is then stored in the WIN.INI file in the Counter section.

The Hardware dialog box appears the first time the program is run, or whenever the Hardware item on the Configuration menu is selected. That allows the user to inform the Windows program what DIP switches are set on the PC10 board. The user checks boxes on the menu to match the setting on the PC10 board.

The Logging dialog box, which appears when the To File item is
selected on the Logging menu, informs the Windows program of the file chosen to log measurements. The filename of the logging file is entered into an edit box. The user can also select if time, date, and units information is to be stored with each measurement.

The Radio Select dialog box appears when the Radio item is selected from the SetRadio menu. That allows the user to select which radio the frequency measurement will be sent. One radio from a list of more than 10 radios may be chosen, and the choice will be saved in the WIN.INI file in the Counter section.

Whenever the Threshold item is selected from the SetRadio menu, the SetRadio Threshold dialog box appears. That allows the user to filter frequency measurements so that only valid measurements from strong signals are sent to the radio. The user selects how close successive measurements must be to each other, and how many consecutive measurements must appear before sending the measurement to the radio.

The Enable menu item on the SetRadio menu enables the PC10 to send frequency measurements meeting the requirements set in the SetRadio Threshold dialog box to the selected radio. If sending measurements is enabled, the menu item will change to Disable, allowing the user to stop sending measurements.

The ManualSet menu item on the SetRadio menu sends the last frequency measurement value directly to the selected radio. It bypasses the filtering performed by the SetRadio Threshold dialog box.

The program icon (also displayed on the ABOUT dialog box) is the Optoelectronics, Inc. logo. The software is available as mentioned in the sources box, and will also be posted on the RE-BBS (516 293-2283) as COUNTER.EXE.

Assembly
The PC10 mostly contains socketed IC's and leaded parts conventionally mounted. However, there are also some surface-mount components in the RF section. Figure 8 shows the parts-placement diagram for the PC10 board.
FOIL PATTERN for the component side of the AP10H board.

FOIL PATTERN for the solder side of the AP10H board.

You will notice that, in Fig. 8, certain parts and groups of parts are labeled G1 and G2. This project can be built for several different applications and, depending on the application, certain parts can be left off the board for significant cost savings.

To build a 10-MHz-to-2.4-GHz RF frequency counter, all G1 parts must be installed, and G2 parts can be omitted. In that case, the AP10H amplifier is not needed. To build a 10-Hz-to-100-MHz universal counter, all G2 parts must be installed, and G1 parts can be omitted; the AP10H is required. Otherwise, for a 10-Hz-to-2.4-GHz universal counter, all G1 and G2 parts must be installed and the AP10H is also required.

Also note points E1, E2, and E3 as indicated in Fig. 8. Normally, for the G0 version (all G1 and G2 parts installed), you must jumper point E1 to point E2 using a short piece of shielded coaxial cable. For the G1 version (G2 parts left out), jumper E1 to E3. For the G2 version (G1 parts left out), no jumper is required.

Install the surface-mount resistors and capacitors first while the PC board is open. If you haven't tried chasing a 1206 sized component all over the place with your soldering iron then here is your chance. While it does require some expertise, you will quickly learn the technique.

Melt a small amount of solder on one of the PC-board pads where the part is to go. Use a small pick to hold the part in place while heating the solder. Continue holding the part in place while the solder cools. After you are satisfied, solder the other end of the part to the PC board. Do not attempt to move or push against the part after one end has been soldered or you will stress the part and may damage it.

The PIN diodes have "DO" on top and look like surface-mount transistors. Solder them in place with the side of a single leg pointing to the top of the PC board. The MMIC's must be installed with the input lead pointing toward the right (gold fingers down). The input lead is marked on the body (you may need a magnifier to see it). Trim the leads to fit on the PC lands between the capacitors. The two remaining leads are bent down to pass
FIG. 8—PARTS-PLACEMENT DIAGRAM for the PC10 board. See text concerning special instructions for G1 and G2 parts.

FIG. 9—HERE IS AN ACTUAL-SIZE template for a brass RF shield that goes over the surface-mount input section of the PC10 board.

through the PC board where they are soldered. Note that the body of the MMIC will fit in the hole drilled through the PC board. Solder the input and output leads first and then the two ground leads.

The three 100-μH chokes are soldered directly to the PC foil where indicated. Solder the two 8-pin prescaler chips into the PC board where indicated for the best possible high-frequency performance. Do not socket the 74HC157 because it will interfere with the BNC input connector.

FIG. 10—THE FINISHED PC10 BOARD. Notice how the brass RF shield goes in place over the input section of the board.

FIG. 11—PARTS-PLACEMENT DIAGRAM for the AP10H board.

Place and solder the 44-pin PLCC socket with the truncated continued on page 62
LAST MONTH WE DISCUSSED ALL OF the operating theory concerning the audio sweep/marker generator. Now let's build the unit.

**Construction and checkout**

There are two PC boards in this unit: the power-supply board, which includes the peak-hold circuit, and the main sweep/generator board. Etched and drilled PC boards are available from the source in the parts list. The prototype uses a Jameco enclosure type H2507, but any thermoplastic or metal enclosure with the proper openings for control shafts and jacks will serve the purpose. An internal view of the sweep/generator is shown in Fig. 10.

Assemble the power supply/peak-hold board according to the parts layout shown in Fig. 11 and mount near the rear of the enclosure. Three mounting holes in the board match the mounting bosses molded onto the enclosure's bottom half. Prior to mounting, solder the transformer leads and 6-inch leads to all the outputs. These leads can be cut to length later. Mount the transformer about an inch away from the power-supply section, leaving room for a line cord and fuseholder to pass through the plastic rear panel. If a three-conductor line cord is used, connect the ground wire to a closed-loop connector and connect it to the transformer mounting screw.

The type of capacitor, C93, used in the peak-hold circuit is critical, and must be a low-leakage type. Only a polystyrene or a polypropylene dielectric capacitor, rated .0033 µF to .005 µF, should be used in this application. The prototype uses a .0047 µF capacitor. You should also use a type 2N4401 transistor for Q11. Substituting an equivalent component for that transistor will cause unusual almost-peak-hold effects. Play it safe and use only recommended components.

All ICs, except IC5, use DIP sockets. Solder all DIP sockets, resistors and capacitors to the main PC board according to Fig. 12. The following instructions will prepare the board for connection of the display and six marker LEDs.

Cut away that portion of the board where the word “CUT” indicates so that the display may be recessed. Cut precisely up to the thirteen foil fingers that must mate with the connections on the display.

Three foil fingers are reserved for hookup wire to be looped through two pads. Press those three wires flat against their fingers and let them extend one-sixteenth inch beyond the board. Solder along the length of the fingers. Use the extending wire ends as indexing pins to mate with the holes in the display. Hold the display at a right angle to the board and form solder bridges between board and display to connect all fingers.

Hold the PC board with the display along the inside of the front panel to determine where the cut-out for the display should be. Mark points where each of the six LEDs must insert through the panel to be soldered to the wide fingers along the board's edge. Use low-current, high-efficiency LEDs or the CMOS circuitry will not be able to light them. Drill holes for the LEDs with a number 33 or 7/64-inch bit. Lay out the rest of the panel and cut all other necessary holes.

Make an "L"-shaped metal bracket to help hold the board in place before the LED's are inserted through the front panel and soldered in place. The letters L and S are etched on the board to indicate long and short leads from the LED's. The cathode is the short lead of the LED.

Attach the metal supporting bracket to the board with a 4-40 machine screw. A hole is provided between IC11 and IC12. Connect the other end of the bracket to the front panel and solder the LED's for additional support.

Add front-panel controls which are closest to the board first, and then complete the connections to the board. It is easier to bring the leads from the controls to the foil side rather than insert them through holes from the component side. The 8 volts peak-to-peak SWEEP output from the sweep/generator may be too much for some scopes to adequately handle. If that is the case, a voltage divider may be needed. A voltage divider can be made by soldering resistors to the SWEEP jack terminal. Solder a 1K resistor from the positive term-
minal to ground and a 4.7K resistor in series with the lead wire to the PC board.

A long jumper wire must be added to the board to make the connection between the counter input and one end of C16. Solder the leads from the power-supply board to the main board. Complete the connections to the on/off switch and insert a 0.5-amp fuse. Don't forget to drill a hole in the top enclosure, directly above R9, so that a trimming tool can be inserted after the enclosure is assembled.

Now it's time to install the IC's on the main board. The IC's are inserted in DIP sockets, and certain waveforms are monitored at test points in a sequence of stages. That way all circuits and components are properly adjusted before proceeding to the next step. Check the power-supply voltages before any IC's are installed. The right most pin of each voltage regulator chip is the output. When checked with a scope, any ripple should be less than 1 millivolt. Make sure you unplug the power-supply cord before proceeding to each subsequent step.

Insert IC17, IC18, and IC19 in the counter area and turn the power on. The on-board LED near the crystal should blink dimly at either 1- or 1-second intervals depending on the position of the SINE RANGE switch. If it does not blink, turn off the power and interchange IC17 and IC18. Troubleshoot the IC by checking the voltage on the appropriate pins first. If an IC is installed backwards and power is applied, the IC may be damaged.

When the LED blinks properly, the frequency display should dimly indicate 0000. The decimal will probably not be visible in any position of the SINE RANGE switch.

Clip a jumper lead from either end of any 10-ohm resistor in the power supply to the side of R26 closest to potentiometer R28. Turn the power on. The readout should be 0060. ± 1 Hz, on the two lowest positions of the SINE RANGE switch. There may be an occasional erratic readout such as 0067. On the two higher positions of the switch, the readout should be 0006 or 0007.

Insert IC14 and IC15 and keep the jumper between the power supply and R26 in place. Turn the power on. Select the lowest position of the SINE RANGE switch, then select the READ mode. Short pin 2 of IC14 to ground with one quick momentary touch. After three seconds the display should brighten and be easy to read. Select either of the two highest positions of the SINE RANGE switch. The decimal should be visible between the two middle digits. Set the SWEEP RATE switch to slow before proceeding.

Insert IC1 into the PC board. Disconnect only that end of the jumper that goes to the 10-ohm resistor in the power supply and connect it to either end of R2 (R2 is jumped to R26). Select the lowest position of the SINE RANGE switch and turn the power on. The counter should display the frequency of the pulses generated by IC1. Sample the three positions of the SWEEP RATE toggle switch and vary the SWEEP RATE adjustment. You should see the
Frequency vary from about 160 Hz to more than 80 kHz. Select a high position of the SINE RANGE switch to read any value above 9999 Hz. There may be small frequency gaps where the three ranges do not overlap. If the jumper wire is connected to the side of R2 closest to the DIP socket for IC2, the HOLD button may be pressed and held to reset the count to 0000. If troubleshooting must be done, pulses varying from zero to +11 volts should be seen at the end of R2 nearest IC1. The checkout waveform is shown in Fig. 13-a.

Remove the jumper wire between R2 and R26. Insert IC2, IC3, and IC4. Select the FAST position of the SWEEP RATE switch (middle position) and set the SWEEP RATE adjustment to the middle position. Turn the power on. Adjust the scope for DC input, 1 volt per division, and either 20 or 50 milliseconds per division. You should observe a linear ramp varying from near 0 to about 4.5 volts at either end of R58, between IC3 and IC4. That waveform is shown in Fig. 13-b.
All resistors are 1/4-watt, 5%, unless otherwise indicated.
R1—3900 ohms
R2, R5, R15, R19, R24, R25, R26, R39, R41, R58, R59, R77, R99—10,000 ohms
R3, R47—3300 ohms
R4, R28, R31—50,000-ohm potentiometer
R6—10,000-ohm multiturn potentiometer
R7—2000-ohm 10-turn potentiometer
R8—2200 ohms
R9—2000-ohm multiturn potentiometer
R10—6800 ohms
R11—10,000-ohm 10-turn potentiometer
R12, R13—1 megohm, 1%
R14, R17—47,000 ohms, 1%
R16—5000-ohm multiturn potentiometer
R18, R80, R90—100,000 ohms
R20, R79—1000 ohms
R21, R23—10,000-ohm potentiometer
R22—12,000 ohms
R27—500-ohm potentiometer
R29, R32, R33, R36, R49, R54, R56, R67—R71, R92, R102, R103—4700 ohms
R30, R34, R38, R48, R50, R51, R53, R73, R76, R78, R81, R82—47,000 ohms
R35, R40—68,000 ohms
R37—15,000 ohms
R42—1.5 megohms
R43, R83, R87—150 ohms
R44, R46, R51, R100, R101—1500 ohms
R45—50,000-ohm potentiometer with SPST switch
R52—270,000 ohms
R55—4.7 megohms
R60—R66, R94, R95—100 ohms
R72—68 ohms
R74—1 megohm
R75—10 megohms
R85, R86—10 ohms
R84, R87—R89—unused
R93, R97—4.7 ohms
R98—330 ohms

Capacitors
C1, C2, C17, C26, C29, C32, C66, C68, C69—10 μF, 25 volts, electrolytic
C3, C6, C7, C15, C30, C31, C36, C37, C65, C91, C94—0.001 μF, Mylar
C5, C9, C11, C14, C23, C28, C33, C61—0.01 μF, Mylar
C4, C13, C16, C25, C60, C73, C74, C75—0.1 μF, Mylar
C8, C64—22 pF, ceramic disc
C10—470 pF, ceramic disc
C12, C39-C59, C76-C89—unused
C18—100 μF, electrolytic
C19—0.006 μF, Mylar
C20—0.004 μF (four 0.001 μF 1% capacitors in parallel), Mylar
C21—0.8 μF (0.33μF and 0.47μF wired in parallel), Mylar
C22—0.033 μF, Mylar
C24, C27, C35—0.005 μF, Mylar
C34, C38, C62, C67—47 μF, 16 volts, electrolytic
C63, C95—100 μF, ceramic disc
C70—3300 μF, 25 volts, electrolytic
C71, C72—1000 μF, 25 volts, electrolytic
C90—10 μF nonpolar, electrolytic
C92—470 μF, 16 volts, electrolytic
C93—see text
C95—47 pF, ceramic disc
C96—0.05 μF, Mylar
C97—2200 μF, electrolytic

Semiconductors
IC1, IC14, IC15—XRL555 timer
IC2—CD4040, 12-stage binary ripple counter
IC3—DAC1222LCN D/A converter
IC4, IC6, IC7, IC8, IC9, IC23—IC25—CA3140E op-amp
IC5—LM336Z 2.5-volt reference diode
IC10, IC26—CA3130E op-amp
IC11—CD4066 8-input NAND gate
IC12—CD4538BCN/BCP or MM14538BCN dual-precision monostable multivibrator
IC13—CD4017 decade counter/divider
IC16—XR2206 monolithic function generator
IC17, IC18—RDD104 timebase
IC19—74C926 counter
IC20—7812 12-volt positive regulator
IC21—7912 12-volt negative regulator
IC22—7805, 5-volt positive regulator
Q1—Q13—2N4401 transistor
Q14—2N2219 transistor or VN0300M MOSFET (see text)
D1—D7—1N914 diode
D8, D9, D10—1N4001 diode
DSP1—NSB3884, 4-digit, 7-segment LED display
LED1—7—LN28CAL(US) Panasonic high-efficiency light emitting diodes

Other components
S1, S2—momentary contact push-button switch, SPST
S3—ON-OFF-ON toggle switch, SPDT
S4—SPST switch mounted on R45
S5—3PDT toggle switch
S6—3-pole, 4-position rotary switch
S7—SPST toggle switch, 1.0 amp, 125 volts AC
T1—120 volts primary, 12.6 volts secondary, 0.6 amps
J1—J6—RCA chassis mount phono jacks
XTAL1—5-MHz crystal
F1—0.5-amp fuse
Miscellaneous: Fuseholder, 3-conductor 18 AWG line cord, Jameco enclosure type H2507, DIP sockets and hardware.

Note: A set of 2 PC boards is available from John Wannamaker, Route 4, Box 550, Orangeburg, S.C. 29115: $43.00, postage paid, S.C. residents add 5% sales tax.
ramp-like waveform appears. Continue adjusting R16 until the positive peak is no more than +2.70 volts, as shown in the Fig. 13-d waveform. The positive peak may be flattened. The lower portion of the ramp may become flattened as the adjustment is made.

Adjust R9 clockwise until any flattened lower portion of the ramp disappears and the bottom has a sharp sawtooth-like transition at the 0-volt line. Adjust R6 clockwise until any flattened upper portion of the waveform disappears and the top has a sharp sawtooth transition. Adjust the sweep rate so that one ramp spans the entire CRT graticule from left to right with the scope adjusted for 5 milliseconds per division in preparation for the next step.

Insert IC11 and turn the power on. A positive 12 volts should be present at pin 13 of IC11 with four spike-like pulses that fall to zero during each ramp cycle. That waveform is shown in Fig. 13-e. The scope may show five such pulses, as one will be the first spike of a new cycle.

Insert IC12 and IC13. Make sure you use a 4538 IC with a BCN or BCP suffix, as others are...
not likely to work. Select the **RUN** mode, markers on, and in the **NARROW** position. Restore the power. The front-panel marker LEDs should flash in a fast sequence from left to right.

Select the narrowest markers, **RUN** mode, and the fastest possible sweep rate. Make sure the **START** adjustment is fully counter clockwise and the **STOP** is fully clockwise. Once the correct fast sequencing is noted, switch to the **READ** mode. Sequencing should be very slow as each LED remains lit for about 15 seconds.

As soon as the display brightens, press the **HOLD** button continually for about one minute to see that it extends the brightening time beyond the usual 12 seconds. The same LED should remain lit while the **HOLD** button is pressed.

Press the **SKIP** button several times at about one second intervals. A new LED should light as soon as **SKIP** is pressed. That will not happen at a slower sweep rate.

Connect a digital voltmeter, on the 20-volt scale, between TP1 and ground. Cycle with the **SKIP** button until the **STOP** LED lights. Press **HOLD** continually while adjusting R16 for a reading between 2.67 and 2.71 volts. Release the **HOLD** button. When the **START** LED lights, again press **HOLD** and adjust R9 to obtain 0.006 volts, using the 2-volt scale. There may be some interaction between R9 and R16. Repeat both adjustments as necessary for the proper readings of 0.006 volts (**START**) and 2.67 to 2.71 volts (**STOP**).

Insert IC16 and remove all test leads from TP1. Then turn on the power. Make sure the **START** adjustment is fully counter clockwise and the **STOP** is fully clockwise. Select the frequency readout position in the middle range of **SINE RANGE**. Select the **FAST SWEEP RATE**. Cycle for the **START** LED to light and press the **HOLD** button. Retrim R9 for a frequency readout between 0030 and 0035. Release the **HOLD** button. Resistor R9 may need adjustment from time to time, due to frequency drift.

Select the kilohertz readout position in the middle range of **SINE RANGE**. Cycle until the **STOP** LED lights. Press the **HOLD** button. If the readout is between 20.10 and
OPERATING INSTRUCTIONS

1. Plug the marker-sweep generator in and turn the power on. Allow one half to one full hour of warm-up time in the RUN mode to minimize frequency drift.

2. Select the FAST position of the SWEEP RATE switch, and select the READ mode.

3. Select the proper frequency range with the SINE RANGE switch. The low range is from 3 Hz to 1 kHz. Both medium positions (M) cover the same range of 35 Hz to 20 kHz. The frequency display will be in Hz or kHz depending on which (M) position is selected. The high frequency range is 3 kHz to 100 kHz.

4. Wait until the unit automatically cycles so that the start LED is lit or manually cycle by pressing the SKIP button.

5. When the START LED lights and the frequency readout brightens, press the HOLD button continuously while adjusting the START frequency. When the START frequency control is fully counter clockwise, with the middle (M) Hz range selected, the frequency readout should be between 0030 and 0035 Hz. If it is not, adjust potentiometer R9 through the hole in the top of the enclosure. Now, adjust the START frequency as desired.

6. Manually cycle the LEDs with the SKIP button until the STOP LED is lit. When the frequency readout brightens, press the HOLD and adjust to the desired STOP frequency.

7. The START and STOP frequencies interact somewhat. Repeat both adjustments once, adjusting the START first and STOP last.

8. Connect the SWEEP output of the generator to the X input of the scope. Connect the SINE output of the generator to the Y input of the scope. Turn the SINE level down counter clockwise. Select the FAST SWEEP RATE, RUN mode and NARROW MARKERS. The CURSOR should be fully clockwise.

9. Adjust the scope for X-Y operation. A horizontal line with five equally spaced dots, or bright spots, should be seen. Adjust the scope's X gain and positioning so that the line-ends, with bright spots at each end, exactly match the left and right CRT graticule lines.

10. Adjust the SINE LEVEL control for the desired peak-to-peak output voltage de-

21.20, no adjustment is necessary. If the readout is only off slightly, adjust R6 and R16 just a little. Recheck to see that the low end still has a frequency reading of 0030 to 0035 Hz. Three potentiometers, R6, R9, and R16, all interact, and if a little adjustment cannot correct for proper readouts, all the steps after inserting IC6-IC9 may have to be repeated. If the .04 μF timing capacitor, C20 (four .01 μF's in parallel), is not within 1 percent, you may have to find your own adjustment values, or settle for a slightly different range span.

The low and high ranges of the SINE RANGE have no separate adjustment; only the timing capacitors C19 and C21 can change their ranges. Extra space is provided on the PC board for parallelizing capacitors in order to find a proper range more easily. Insert IC10, a CA3130E, and turn the power on. Select the RUN mode with a fast sweep, MARKER on NARROW and CURSOR turned fully clockwise. With the scope on DC input, observe the SWEEP waveform at J2. A ramp waveform is not upward smooth but will not operate properly with an input signal of more than 3.75 volts peak-to-peak. Inputs of 0.2 volts to 3.75 volts work best.

13. Adjust the SWEEP RATE, switch, and control for the desired sweep rate.

14. Adjust the scope's volts/division control (Y input) as required.

15. The scope's brightness should be turned down for a satisfactory contour-line display of the response curve. The peak-hold will not operate properly with an input signal of more than 3.75 volts peak-to-peak. Inputs of 0.2 volts to 3.75 volts work best.

THESE ARE SWEEP GENERATOR CONNECTIONS for a conventional, digital-memory or a storage scope.
in Fig. 13-g. With the cursor fully clockwise, there should be no extra marker.

Set the range of the SINE RANGE, SLOW SWEEP RATE, and SWEEP RATE adjustment at mid-position. Select WIDE MARKERS, place the cursor fully clockwise, and the SINE LEVEL at mid-position. Adjust the STOP fully counter clockwise. With the START control initially fully counter clockwise, turn it clockwise three turns. Select the RUN mode. The display will be dim, but it should indicate a frequency of about 6500 Hz. Set the scope for 0.5 volts per division and 20 microseconds per division. Observe the waveform at the SINE jack, J2, and adjust triggering for a steady waveform. Adjust the two on-board trimmer potentiometers, R27 and R28, for the best sine-wave shape. Those adjustments interact, so you should alternate between them until a good sine-wave shape is achieved.

Now, remain triggered on the sine wave but switch the scope's time base to 0.2 milliseconds per division. Turn the START control slowly counter clockwise. The frequency should become lower and may drop to less than 1 Hz, or stop oscillation altogether. Turn the STOP fully clockwise. The frequency should become higher while the STOP control is turning. The waveform should change in frequency from about 30 Hz to 20 Hz over a period of 12 seconds. Adjust R16 if necessary.

When the SWEEP RATE switch or control is changed, the sweep from 30 Hz to 20 kHz will either speed up or slow down accordingly. Adjust for the slowest possible SWEEP RATE. Connect the SINE output to the peak-hold IN jack, J6. Reduce the SINE LEVEL to about one-third the maximum output. Look at the peak-hold OUT jack, waveform at J5. It should look like Fig. 13-h. Figure 13-i shows the peak-hold output overdriven, causing a downward slope of the flat portion of the waveform.

A +11-volt synchronization pulse should be seen at the SYNC jack, J3, as shown in Fig. 13-j. The pulse will have an RC time constant-like rise and a fast fall, with a duration of about 70 microseconds. Use the fastest possible SWEEP RATE. Set the scope for 2 volts per division, 50 microseconds per division, and use (+) slope triggering.

To observe the output at the MARKER jack, J4, select the RUN mode. SWEEP RATE switch set to FAST. SWEEP RATE adjustment to mid-position and the markers set on and NARROW. Synchronize the scope with the output of the SYNC jack, J3. Adjust the scope's triggering for external input. (−) slope triggering, and use a 20 millisecond per division sweep rate. Four markers, consisting of positive pulses, should be seen with a peak value of 12 volts, and a duration of about 15 milliseconds each. That waveform is shown in Fig. 13-k. The marker control should increase the pulsewidth. That completes the checkout.

Alignment and calibration

Mechanical adjustment of the 10-MHz timebase is provided by trimming C9. One of the unique features of the PC10 is the software calibration which is available when the program is running. It is really not necessary to adjust C9 unless you have a desire to. Resistor R31 is the input-bias adjustment which can be set to the 4:00 position.

The two bias adjustment trimmers in the AP10H amplifier should be set for maximum sensitivity when counting a low-level signal. They can be initially set for mid-range.

Installation

The PC10 will work in any computer that has Windows 3.0 installed, and it requires one three-quarter length expansion slot. Copy the supplied software to your Hard Disk (you may wish to create a PC10 directory). While in Windows, select the Program Manager and click options under Windows Setup, Options, and Set Up Applications. Follow the instructions to locate and set up the program COUNTER.EXE as a Windows application. To run the PC10 counter, simply select the Counter.exe logo using the mouse and give it a double click.

The actual counter input sensitivity will vary somewhat depending upon the host computer. Grounding, shielding and place-
Recent breakthroughs in ferroelectronics technology promise nearly “ideal” nonvolatile semiconductor memories.

TJ BYERS

Ferroelectric IC’s—chips that remember

WHAT HAPPENS TO VOLATILE ELECTRONIC INFORMATION when the lights go out? Usually it vanishes into thin air, never to be found again. But an old technology with new advancements may make lost data a thing of the past.

Ferroelectric technology has long tantalized circuit designers by promising an easy and inexpensive way of preserving data. Although it’s been a long time coming, nonvolatile semiconductor memory using ferroelectric materials that store binary information can now be made for only pennies more than an equivalent dynamic RAM IC and considerably less than an equivalent static RAM IC.

Two leading manufacturers in the ferroelectric field, National Semiconductor and Ramtron Corp., have developed several ferroelectric semiconductor devices that retain their memory for up to a year without the aid of an external or internal auxiliary power source. Moreover, the devices are exact replacements for popular TTL and CMOS logic ICs, which means that no circuit design changes are required. It’s a simple matter of out with the old chip and in with the new.

Ferroelectric devices are considered to be nearly “ideal” because of such characteristics as:
- Total immunity to power failure.
- Resistance to radiation.
- Symmetrical read and write cycles.
- Low power consumption.
- Most operate from a single +5 volt power supply.

We will take a look at how ferroelectric technology has overcome its traditional problems to become a viable solution to battery-free, nonvolatile semiconductor memory.

How ferroelectrics work

Ferroelectric technology is based on the fact that different insulating materials have different dielectric characteristics. Most of us think of a dielectric material as the stuff used in capacitors, such as polycarbonate film or mica, where the electric field, or flux density between the plates of the capacitor is a linear function of the applied voltage.

Certain materials, however, exhibit nonlinear dielectric characteristics, and a few of those leave a residual polarization under the influence of an externally applied electric field. The latter are classi-
fied as ferroelectric materials. If the electric field is reversed, spontaneous polarization in the opposite direction occurs. Ferroelectric materials, therefore have two stable polarization states, which can be designed into a "bistable capacitor" with two distinct voltage thresholds.

What sets ferroelectric compounds apart from other dielectrics is a hysteresis function, or magnetic "memory," that is also characteristic of magnetic devices, such as those used in a coil or a transformer. The name ferroelectric is somewhat of a misnomer because those compounds are in no way connected with iron-based materials. The term ferroelectric was derived from their analogy to the hysteresis function of magnetic devices, which can be used to store information.

Figure 1 shows the hysteresis loop of a typical ferroelectric dielectric material. That curve is generated by placing a ferroelectric substance between two metal plates and applying a voltage. Notice that as the voltage across the material increases, a threshold point is reached where the permittivity of the dielectric suddenly changes.

Once the ferroelectric dielectric density threshold has been exceeded, a residual polarization charge remains in the dielectric even after the source voltage is removed. It is that residual polarization effect that makes the ferroelectric material effective as a data storage device because the only way to change its state is to apply a reverse voltage across the ferroelectric material of sufficient strength to reverse the polarity of the ferroelectric charge.

Because no external electric field is needed for the ferroelectric material to remain polarized in either state, a true nonvolatile digital memory capacitor can be designed for storing logical "1s" and "0s," according to the polarization state of the material. The stored information can be written to or read from a ferroelectric cell by applying an electric field greater than the threshold (coercive) field to each memory element.

Although the process seems simple enough in theory, it took more than 30 years to make ferroelectrics practical. The problems are many, and not all are yet completely resolved.

Some of the frustrating problems encountered in the development of ferroelectric technology include:

- A ferroelectric memory array can be prone to disturbance problems because the coercive voltage is not well defined for different compounds.
- Thick film ferroelectric compounds used in earlier designs required coercive voltages ranging from tens to hundreds of volts, which was far in excess of the +5 volt DC supply used in modern day microelectronics. Also, their slow switching speed made thick film ferroelectronics impractical for high-speed read/write memories (<100 ns).
- Many ferroelectric materials exhibit the phenomenon of fatigue, in which the residual polarization reduces as the total number of polarization reversals increases.
- Some ferroelectric materials exhibit the tendency to return to a preferred polarization after reversal following a long waiting time at the initial polarization. That reaction is known as the "waiting time effect."

The biggest problem is that ferroelectricity is structure-sensitive. The crystalline shape, thickness, and resistivity of the material have to be perfect every time for predictable results. Until recently, standard production methods were not available to manufacture reliable, high-quality and inexpensive ferroelectric ICs.

Ferroelectric chemistry is also very critical because there's a trade-off between long-term data storage and the number of times the dielectric can be cycled. Ferroelectric compounds with a long storage time (10 years or more) have very short life cycles (about 1000 cycles), whereas compounds with a shorter storage time, such as a year, have a life span that approaches a trillion cycles. Those properties are a function of the ferroelectric blend, and can be changed by varying the proportions of the mixture.

As in magnetic materials, once a ferroelectric material reaches a certain temperature, its residual polarization cannot be maintained, and thus its ferroelectric effects are lost. The temperature above which ferroelectric effects disappear is known as the Curie temperature. Upon cooling, the ferroelectric effect returns, but the data is lost forever. Unfortunately, most ferroelectric materials have a Curie temperature that's below the boiling point of...
FIG. 3—LOGIC DIAGRAM of the 74CF374 IC.

FIG. 4—FRAM’s “USE A FOUR TRANSISTOR SRAM based cell with PZT capacitors to "shadow" the RAM, thereby eliminating the traditional problem of fatigue.

Finally, it's ferroelectric

The first devices to roll off the National Semiconductor ferroelectric assembly line are ferroelectric versions of the 74LS374 IC, an octal D-type flip-flop with tri-state outputs. More complex devices, including a 2K static RAM IC, are working their way through National's research and development labs, and should surface soon.

The 74LS374 contains eight D-type flip-flops that behave like memory latches. The output of the flip-flops is controlled by the clock. A rising clock pulse transfers the data on the input lines to the output lines, where it remains fixed until changed by another clock pulse. The non-transparent nature of the flip-flops make this IC useful as a buffer latch in counter displays and bidirectional bus interfaces. But when the power is lost, so is the data.

In the ferroelectric version of the 74LS374, designated the 74CF374, a ferroelectric capacitor is added to the flip-flop. In normal operation, the flip-flop output follows the input with each occurrence of the clock pulse, charging and discharging the ferroelectric capacitor as the logic level changes. When the power is removed, the ferroelectric capacitor remains in the last state of operation. When power is applied to the IC, the ferroelectric cell forces the flip-flop into the last recorded state, thus preserving the data. The 74CF374's ferroelectric cells can retain data for up to a year, and the one-year clock begins again each time the data in the cells is updated through normal IC operation.

The ferroelectric material used in the fabrication of the 74CF374 is based on a perovskite crys-
Ferroelectric material is deposited on the wafer using a three-step masking procedure about halfway through the fabrication process, as shown in Fig. 2. The internal circuit of the 74CF374 IC is shown in Fig. 3.

The ferroelectric layer serves as the basis for the IC's nonvolatile memory. As ferroelectric processing techniques improve, however, the three added steps will be reduced to one, decreasing the cost of adding ferroelectric to a device. The procedure is also currently done using economical 2.0-micron CMOS processing, but that's also expected to improve as techniques advance. Nonetheless, the 74CF374 still displays excellent 25-ns propagation times with a clock speed of 30 MHz—specs equal to those of the device it mimics.

A major concern with any data protection scheme is maintaining the integrity of the data during uncertain power conditions. The 74CF374 has an added circuit that reduces the chances of losing data during power transitions. The circuit has a voltage detector that monitors the voltage of the $V_{cc}$ supply line. If the supply voltage falls below 3.6 volts, the device is immediately disabled, preventing unwanted glitches from changing the status of the output lines.

If you're interested in obtaining app notes from National Semiconductor Corp., they can be reached at:

2900 Semiconductor Dr.
P.O. Box 58090
Santa Clara, CA 95052-8090
Phone: (408) 721-5000

On the other side of the fence, Ramtron Corp., specializing in ferroelectronic research, development, and design, has produced a line of ferroelectric random access memories (FRAM's™). Ramtron's FRAM™ IC's use PZT capacitors to store digital information. Those digital memory capacitors are integrated into a read/write RAM circuit.
Figure 4 shows a “shadow” RAM cell which uses four transistor SRAM cells interconnected with two PZT capacitors. That circuit is unique because C1 and C2 are activated to store data only when power is lost, and restores data when power is regained. Compared to EEPROM's, Ramtron's shadow RAM architecture can store data without power for 10 years, has the capability of >10⁹ store/recall cycles, and has a life expectancy of >11,000 years at one power loss per hour.

Ramtron's demonstration IC, the FMx 801, is a 256 x 1 bit non-volatile SRAM. Nonvolatility is accomplished by storing complementary polarization states on pairs of PZT capacitors in each SRAM cell. Those polarization states are retained when power is removed from the device, preserving the information. Information is recovered after power-up by reading those states from the ferroelectric portion of the shadow RAM cell.

A block diagram of the FMx 801 is shown in Fig. 5. The FMx 801 is packaged in a 24 pin DIP Fourteen of the 24 pins are used to operate the IC as a conventional SRAM. Three of the remaining 10 pins connect to separate ferroelectric devices to distinguish between individual PZT capacitors. The remaining seven pins are used with SRAM pins to achieve nonvolatility by store and recall timing sequences. Two of the seven ferroelectric pins, CRA and CRB, provide power and ground, respectively, to the SRAM cell during the read/write and store operations. The remaining five pins, CTA, CTB, CPA, CTB, and CPRE are control signals that connect or isolate the shadow portion of RAM (ferroelectric portion) to the static RAM cell. The timing parameters and voltage levels of the seven ferroelectric pins are critical for data retention.

For more information on Ramtron's ferroelectric IC's, you can contact them at: 1873 Austin Bluffs Pkwy. Colorado Springs, CO 80918 Phone: (719) 594-4455

Although FRAMS™ focus on dedicated memory applications, ferroelectric technology can also be applied to logic devices, microprocessors, application-specific integrated circuits (ASICs), and enhancements for linear circuits. Let's look at some other markets in which ferroelectric devices can be used and where they may replace other components.

The future of ferroelectronics

In the short term, ferroelectric devices should find applications in programmable logic ICs, replacing EPROM's, and DIP switches. Mechanical controllers, such as event counters and utility meters, automotive electronics, robotics, instrumentation, satellites, communication systems, and programmable appliances are other prime sources for ferroelectric foray.

Provided that ferroelectric manufacturing techniques keep pace with burgeoning PC speeds, you'll see more use of ferroelectric memory devices and less use of battery-backed shadow RAM caches. It's even conceivable that all logic IC's may eventually be replaced with ferroelectric counterparts.

Military applications will find ferroelectric devices particularly attractive because of their radiation hardness. In situations where a rad-hardened CMOS memory array would fail, a ferroelectric array could come through unscathed.

Ultimately, ferroelectrics may replace magnetic tapes and drives as the primary source of data storage—something both bubble memory and CD drives have tried but failed to do because of such things as cost and technology limitations.

R E

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Storage and retrieval of digital information has sparked an exciting revolution in computers and consumer electronics. You find semiconductor memories in nearly all "intelligent" electronic systems, including car radios, televisions, VCR's, compact-disc players, and computers. Without the on-going advances in memory technology, the high-tech revolution would rapidly grind to a halt.

In this article, we will examine several important concepts behind semiconductor memory devices, including basic technologies, memory organization and configuration, design considerations, and applications.

**Memory types**

Semiconductor memory devices can be classified in one of two ways: permanent or temporary. Although basic operating principles of both are similar, each plays a different role, and each has unique advantages and disadvantages. We will discuss both types in detail.

As the name suggests, information in permanent memory is retained at all times, even after removal of system power. Permanent memory is also called non-volatile and read-only memory. Permanent memory is most often used to store fixed program instructions or numerical constants that do not change during the life of a product. For example, personal computers use permanent memory to hold the basic input/output system (BIOS) that initializes the computer and provides it with a core of low-level functions. There are four basic types of permanent memory: ROM, PROM, EPROM, and EEPROM. Let's discuss each type.

**ROM**

The read only memory (ROM) is the oldest and most straightforward type of permanent semiconductor memory. The information that's programmed into a ROM is specified by the buyer, but the ROM itself must be built by the manufacturer.

A ROM is relatively inflexible—after it's been programmed, it can never be altered. If the information in a ROM must change, a whole new device must be manufactured and substituted for the old ROM, and that is an expensive, time-consuming process. Hence the ROM is economically feasible only when used in great volumes for thoroughly debugged applications.

One advantage of the ROM is its ruggedness. Since the program is an actual physical part of the device itself, it can withstand relatively large amounts of electrical and physical abuse, yet still maintain its contents. The automobile industry uses ROM's extensively in on-board computers.

**PROM**

The programmable read only memory (PROM) offers a tremendous advantage over the ROM in that it can be programmed by the end user, who is then less dependent on manufacturers' lead times. A PROM can be "burned," or programmed, only once because it cannot be erased.

The term burn comes from the method used to program a PROM. A factory-fresh PROM consists of a matrix of fusible links. An intact link produces a binary 0 at the selected location; a burned (open-circuit) link produces a binary 1, as shown in Fig. 1. (We'll discuss how to get at a particular location in a PROM later in this article.)

To burn a PROM, a special piece of equipment called a PROM burner generates high-energy pulses which destroy the desired links to match the contents of a user data file.

PROM's are slightly more expensive than ROM's on a per-unit basis, but their flexibility often justifies higher cost. Many PROM's are available through retail electronics outlets.

**SEMICONDUCTOR MEMORIES**

An overview of today's revolutionary memory technology—and a peek at tomorrow's.

Stephen J. Bigelow

Radio-Electronics
FIG. 1—A PROM BEFORE PROGRAMMING consists of a matrix of fused links joining each row-column intersection. Programming blows desired links.

**EPROM**

The erasable programmable read-only memory (EPROM) overcomes one of the main disadvantages of the PROM: its inability to be reused. After a link has been burned, it can never be restored. By contrast, typical EPROMs can be reliably burned and erased thousands of times.

The PROM is built around traditional bipolar transistor technology, which uses both a great deal of power and occupies a lot of space. The EPROM, on the other hand, uses newer metal-oxide semiconductor (MOS) technology, which requires little current and occupies little space. In an EPROM, information is stored as small packets of charge buried deep within the substrate of the IC, as shown in Fig. 2.

An EPROM is programmed much like a PROM. A special EPROM programmer selects an address in the device, places the desired binary information on the data lines, and then pulses the EPROM's **PROGRAM** pin. That pulse is what locks the bit pattern into the substrate of the chip.

To erase an EPROM, it's necessary to remove the charges in the IC's substrate. That's accomplished by exposing the circuit (the die itself) to short-wavelength ultraviolet (UV) light for a prescribed period of time. The excitation created by the UV light allows stored charge to dissipate, so the IC gradually returns to its pre-programmed state. The UV light is introduced into the EPROM through a transparent quartz window in the top of the IC package.

Use caution when working with EPROMs. Even though it takes about 20 minutes of exposure to a concentrated UV light source to erase an EPROM, some common sources of light, such as sunlight, fluorescent light and "black-light", may contain enough UV to trigger random charge dissipation and introduce errors in the device. So be sure to cover the quartz window with a piece of opaque material.

EPROM's cost more than PROMs, but cost-per-bit is actually lower because MOS technology allows the designer to squeeze several times more information in the same amount of space. One disadvantage of the EPROM is that it must be physically removed from the system to be erased and re-programmed.

**EEPROM's**

The electrically erasable programmable read only memory (EEPROM) is similar to the EPROM, but overcomes its main disadvantage: the inability to program it in-circuit. That feature offers exciting possibilities in applications where software must adapt to changes in the operating environment.

The EEPROM is no panacea, however. It's slower than other types of memory, and it requires a relatively long time to update the altered data. As a result, EEPROMs are best suited for holding information that changes infrequently. Information that changes often is best left to the work of temporary memory, the other broad class of semiconductor memory.

**Temporary memory**

Information held in a temporary semiconductor memory device can be altered and updated frequently, but will be maintained only as long as power is supplied to the device. If power fails, memory contents will be lost. That type of memory is usually referred to as volatile memory. It is also known as random access memory (RAM). The name refers to the fact that any location may be accessed as quickly as any other. By contrast, in a sequential device like a tape drive, access speed depends on the location of the desired information. However, random locations in ROMs, PROMs, EPROMs, and EEPROMs can be accessed with equal speed. Nonetheless, when people speak of RAM, they almost invariably are referring to temporary memory.
DATA
ROW SELECT
01 MOS TRANSISTOR
STORAGE CAPACITANCE

FIG. 4—CAPACITANCE is the basic unit of storage in the DRAM.

Static RAM (SRAM) is the oldest and most straightforward form of temporary semiconductor memory. A typical SRAM consists of several flip-flops, or cells, as shown in Fig. 3. Each cell stores one bit of information: multiple cells are arranged in a two-dimensional array. To access a particular cell, row and column addresses must be set up, and then several control signals must be pulsed.

Since data is always available from the flip-flop matrix, the SRAM tends to be a fast device. Its primary disadvantage is limited capacity. Each flip-flop occupies a relatively large area on the IC, so the maximum number of cells is limited.

Dynamic RAM

Dynamic RAM (DRAM) uses a different technology to accomplish data storage. The key difference lies in the design of the cell itself. As shown in Fig. 4, each cell in a DRAM stores information as a packet of charge across a MOS transistor, similar in principle to the EPROM works, but it is unlike the SRAM, which uses a flip-flop to hold one bit of data.

To allow frequent updates, each cell must be capable of changing state almost instantly. To allow rapid change, the storage capacitance must be extremely low, so low in fact that it cannot sustain its charge for more than a few milliseconds. Therefore each DRAM location must be refreshed about every two milliseconds. If a cell is not refreshed, it will simply lose its data. However, refresh cannot happen by itself; external circuitry is required, as well as additional circuitry within the DRAM itself. Fig. 5 shows a block diagram of the internal structure of a DRAM. The added complexity and cost of refresh circuitry is the main disadvantage of DRAM.

On the other hand, DRAM offers several distinct advantages over SRAM. Storage capacity is much greater. Common DRAM's provide one megabit ($2^{20}$) of storage, and four-megabit IC's are just over the horizon. In addition, 16-megabit memories are being developed, and 64-megabit DRAM's are on the drawing board.

Power is another consideration. DRAM's require less current to operate; there are far fewer components per cell to dissipate power. The power savings can be substantial in applications that need a great deal of memory. DRAM's also have a standby mode that essentially disables all functions except refresh. In standby mode, a DRAM requires just a few milliwatts of power to maintain its information. In some cases, the low power requirement makes battery backup practical. SRAM's also have a standby mode, but they typically need more than 100 milliwatts of power. Now let's examine some of

Most electronic processing systems require at least some RAM. The amount that's required depends on the application. A simple system, such as a programmable digital thermostat, may require only a few bytes of RAM. But a computer may require millions of bytes of RAM.

There are two basic types of RAM: static and dynamic. Each type has particular benefits and drawbacks.

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the technologies used to fabricate semiconductor memory devices.

Fabrication technologies

Every semiconductor memory chip houses sophisticated, sensitive microcircuitry. Each minute component must be integrated deep into the substrate of the chip (or die), which itself rests within a hermetically sealed case of plastic or ceramic. The process of circuit integration involves a complex combination of optical and chemical processes to form a working IC. Memory devices manufactured today are typically made using either bipolar or MOS fabrication technologies. In addition, a new hybrid of the two technologies, called Bi-MOS, has begun to appear. Although the actual manufacturing processes of these kinds of devices are too involved to cover here, we can review the characteristics and uses of those technologies.

Bipolar technology

The bipolar transistor (with emitter, base, and collector) was the first component successfully integrated into a semiconductor wafer in the form of the TTL IC. Many simple logic functions could thus be synthesized easily and efficiently. The resulting low cost and high availability made TTL a mainstay of digital logic design through the 60's and early 70's. Even to this day, TTL remains a cornerstone of basic logic design. When memories were needed, TTL was the obvious choice.

Although there are several SRAM chips in the TTL family (notably the 74S200 and 74S201), TTL suffers from several major drawbacks that severely restrict the capacity of bipolar SRAM. First, bipolar logic requires a relatively large area on the chip for each logic gate. Many gates are needed to build a SRAM, so space is depleted rapidly. In addition, bipolar logic requires significant operating current per gate. Since current ultimately translates into heat, the number of cells is limited even further. Size and power restraints usually limit the number of bipolar memory cells to fewer than 1000 bits.

MOS technology

The development of MOS technology is largely responsible for the incredible advances in high-tech electronics since the late 1970's. The materials and chemicals used in MOS fabrication are different from those used for bipolar fabrication, but the process is fundamentally the same. The most familiar MOS family is complementary MOS (CMOS), but there are many variations, including PMOS, NMOS, VMOS, DMOS, and HMOS.

CMOS, NMOS, and HMOST devices are the most widespread variations of MOS technology in use today. CMOS has been used extensively in memories, and to produce a family of devices that is functionally similar to the TTL family. CMOS dissipates far less power than TTL and can run on a much wider range of supply voltage (3–15 volts DC). N-channel MOS (NMOS) technology is used to produce memories that are fast, dissipate little power, and can fit many components on a chip. Although early devices required several supply voltages, modern NMOS ICs operate from a single 5-volt supply. High-performance MOS (HMOS) is an NMOS variation that's used in modern high-speed low-power microprocessors.

In spite of their obvious advantages, all MOS devices suffer from one key weakness: they're extremely sensitive to static electricity. There are important precautions that should be taken. Be sure to follow manufacturers' guidelines for handling MOS devices.

Memory operations

To the external world, the organization of a semiconductor memory device appears as a sequence of locations. Each location may have 1, 4, 8, or some other number of bits, but regardless of the number of bits per location, each location has a unique address. The number of unique addresses depends on the number of address lines. If there are 8 address lines, then there are $2^8$ or 256 addresses. Although externally a semiconductor device appears to have a sequential organization, internally the cells are arranged in a square.

The relationship between the number of physical cells (bits) and the number of logical locations (addresses) depends on the number of bits per address. For example, a memory IC could have 1 megabit of cells arranged as $1 \times 1$ megabit, as $4 \times 256$K, or even as $8 \times 128$K. Internal decoding circuitry varies depending on how the organization is to appear externally.

For example, Fig. 6 represents a simple ROM. The format of the ROM is 256 addresses with four bits per address. The memory array is a $32 \times 32$ square, giving 256 addresses. And for 256 addresses the chip requires eight address lines ($2^8 = 256$) to identify each location uniquely. The lower five address lines (A0–A4) select one of 32 possible rows ($2^5 = 32$). The upper three (A5–A7) select one of eight columns ($2^3 = 8$). There are four 1-of-8 decoders, so four columns (one from each group of eight) will be active for each selection.

After a valid address is presented to the address lines, the data bits at the intersections of the selected row and columns will be sent through the respective 1-of-8 decoders to several three-state buffers. If the READ ENABLE signal is brought low, the data present at the buffers will be delivered to the ROM's output. But when READ ENABLE is high, the high impedance of the three-state buffer will simply disconnect the ROM's outputs from the circuit.

SRAM's, along with PROMs, EPROMs, and EEPROMs, are more sophisticated. Figure 7 shows a simple SRAM organized.
as 4096 x 1. Addressing is similar to the ROM in the previous example but, in this case, there are 12 address lines that provide $2^{12} = 4096$ (4K) addresses. One bit of data is available at each address location.

A **READ/WRITE** control signal determines whether data will be read from or written to the IC. If **R/W** is logic 1, data will be read from the cell. If **R/W** is logic 0, data will be written to the cell.

To read a bit of data, a valid address must be supplied. **R/W** must be high, and the **CHIP SELECT** input must be low. To write a bit of data, the same conditions apply except that **R/W** must be low. The timing relationships between the signals at various pins can be critical, depending on the circuit.

**Timing considerations**

Today's generation of RAM IC's has been designed to operate at high speeds, so timing characteristics for address, data, and control lines are important. There are several important parameters that we will discuss.

**Access time** specifies how long it takes after addressing a specific location before valid data appears at the IC's output. A slow memory device may have an access time of as much as 450 nanoseconds, while a fast device might access data in as little as 25 nanoseconds. Common memory devices today have access times of about 100-150 ns. As a rule of thumb, the faster a memory device is, the more expensive it will be.

**Settle time** specifies the amount of time that must pass after setting up the address, data, and **CHIP SELECT** signals, before the **R/W** may be pulsed low to write data into the IC.

In addition, the **write** pulse must be held low for a minimum amount of time to ensure that the data is accepted into memory. That is the duration of the **write pulse**. The address, data, and enable signals must be held steady for a minimum time after the write pulse; that period is called the **hold time**.

Those timing parameters apply to SRAM's; DRAM's have even more intricate timing requirements. Although the basic principles of reading and writing are similar to those for the SRAM, there are some extra features and parameters that must also be considered.

The first involves memory addressing. As discussed earlier, DRAMs can provide millions of bits on one device. For example, addressing 1 megabit ($2^{20}$) would require 20 address lines. It's possible to build an IC with 20 or more pins, but to save space and reduce pin count, several address lines are multiplexed on a single pin.

Figure 8 shows the block diagram of a 1-megabit x 1-bit DRAM. Note that only ten address lines enter the IC, so you might think that you could access only $2^{10} = 1024$ locations. In fact the 20-bit address is broken up into two parts, each of which is supplied separately. The lower ten bits select the desired row in the memory array, and the upper ten
bits select the desired column. The row-address lines are strobed into the IC by pulsing the row-address strobe (RAS) input, and the column-address lines by pulsing the column-address strobe (CAS) input. External circuitry must ensure that the proper set of address lines is applied to the IC before pulsing a strobe input.

After the IC receives the full address, CHIP SELECT and ROW may be set up, as with an SRAM, to read or write data. The access, setup, and hold times apply to DRAMs as well.

Refresh

As mentioned earlier, DRAMs require periodic refreshing, otherwise their stored charge will dissipate. There are several ways of refreshing a DRAM system, all of which use the RAS and CAS inputs. The simplest method is called RAS-only refresh. It involves holding CAS high, which in turn holds the output in a high-impedance, or disconnected, state. The refresh circuitry then selects each row in turn, pulsing RAS low for each row as it is addressed. It does not matter whether all rows are refreshed in one sustained burst, or one row between, for example, read or write operations. As long as a cell is refreshed in time, its data will remain intact.

Hidden refresh is a variation on RAS-only refresh in which CAS is held at logic 0 (for example, valid data is maintained on the output) while rows are selected and refreshed. Depending on system timing, CAS may be held low for several microseconds, during which several rows may be refreshed.

There are other variations, but all refresh circuits add a fair amount of complexity to a circuit. Fortunately, however, there are refresh-controller IC’s for many different DRAM sizes and configurations. Those IC’s reduce cost, increase reliability, and decrease required PC board space.

EPROM emulator

You can easily assemble your own hand-made “EPROM” using two common TTL IC’s and several Germanium diodes. Figure 9 shows the schematic for a 16x4 memory circuit. It’s loosely called an EPROM because it can be reprogrammed at any time by rearranging the diodes in the matrix. Although the circuit is unsuitable for high-performance or microprocessor-based applications, it can be used to supply pre-programmed bit patterns to discrete logic circuits. It also provides an excellent demonstration of basic memory operation.

Parallel memory

Semiconductor memories (both temporary and permanent) can be placed in parallel to increase the number of data bits available per address, as shown in Fig. 10. The circuit is built from several 2147 SRAM’s (4096 x 1). By connecting the address and control lines in parallel, the same address in all IC’s will be selected simultaneously. The data bits, of course, are kept separate. You could just as easily place 8, 16, or 32 IC’s in parallel to create 4K x 8, 4K x 16, or 4K x 32 memory blocks.

Conclusion

Memory is an integral part of the high-tech revolution. Even the most basic processing circuit would be useless without some sort of memory to store variable data.

As you can see from our comparison of the many different permanent memory devices, there are distinct advantages and limitations to each type. What you choose depends on your individual needs—the ROM is inflexible but rugged, while the PROM can be programmed by the user, but only once because it can’t be erased. The EPROM can be programmed and erased over and over again but uses a lot of power and space, while the EEPROM can be programmed while in circuit, but is slow.
As someone who doesn’t even like to fish, I seem to spend an awful lot of time opening cans of worms. My most recent foray into decanting annelids was my discussion of transfer-functions and Bob Carver’s misadventures with Stereophile magazine. In a letter to this magazine, Stereophile editor John Atkinson took exception to several of my remarks. (See this month’s Letters column.)

I questioned Bob Carver on some of the disputed facts of the case. It is a “case” because Stereophile originally sued Carver for unauthorized reprinting of a negative review of one of his amplifiers—even with several laudatory reviews of the same amplifier. Carver’s idea was to invalidate Stereophile’s negative evaluation by contrasting it with several other very positive reviews from other publications. When Stereophile sued Carver, he countersued, claiming, in effect, that for several years Stereophile had continuously and unfairly disparaged him and his amplifier products.

Since I had not been involved in the chain of events and my knowledge of what occurred was based on a few conversations with Bob Carver and an incomplete collection of Stereophile, Atkinson’s letter led me to wonder if I had gone factually astray in some areas. I faxed a copy of Atkinson’s letter to Carver asking for his comments. At the major points where Atkinson “corrected” me, Carver commented that Atkinson’s versions of the events were “simply not true.” Who to believe?

The straight facts

One of the things that I didn’t learn in kindergarten is that people—in all honesty—tend to remember and/or interpret events in a way that fits into their preexisting world view. So when I’m forced to choose between alternate views of an event, I tend to support the one that makes objective sense to me and whose advocate has the same way of looking at the world as I do.

I’ve known John Atkinson since the days when he worked for the British publication Hi-Fi News. I watched the publication under his direction abandon rationality and take its readers on an audio “Magical Mystery Tour,” frequently promoting products and technologies that lacked any rational technical basis. An example: HFN unashamedly promoted a metal brick “Flux Dumper” that purported to improve the sound of an amplifier when simply placed upon the amplifier’s metal cage. For me this casts doubt on their overall good sense and seriousness.

When Atkinson came to Stereophile, his approach dovetailed neatly with that of its publisher. So although he can talk a good scientific line, his editorial approach and product evaluations at Stereophile reflect a basically mystical approach to the world of audio.

I won’t say that I haven’t had disagreements with Bob Carver. But our arguments have involved his use of technically inappropriate names for his usually innovative circuits, his sensitive ego, and his sometimes self-defeating promotional efforts. Nevertheless, I’ve always been terribly impressed by Carver’s design genius and technical rationality. For those reasons, I tend to accept Carver’s point of view rather than Atkinson’s in regard to the facts in question. Some of the truth of the

FIG. 1—THE CARVER SILVER SEVEN POWER AMPLIFIER can deliver 375 watts into an 8-ohm speaker load from 20 Hz to 20 kHz with less than 0.5% total harmonic distortion.
Flawed evaluations
I may have misrepresented the exact nature of Stereophile’s reevaluation of the Carver Challenge. Their position seems to be that Carver in 1985 did accomplish what he originally claimed he would—make his $700 M-1.0 solid-state amplifier sound identical to Stereophile’s $5,000 Conrad-Johnson mono tube amplifier. However, in 1987 Stereophile proved to their own satisfaction that Carver could not duplicate his hand-tweaked prototype in production, despite his ads that claimed he had. They did try to compare a production-line M-1.0t (“t” for transfer) amplifier with their original tube reference unit.

The flaw in that procedure is obvious to anyone familiar with tube technology. There’s a very high probability that in the years between the two comparisons, the parameters of the reference amplifier’s output tubes shifted sufficiently to produce an audible difference during critical A-B listening tests.

The correct testing approach would have been to compare Carver’s production-line amplifier with his original hand-modified unit. Although Stereophile had access to the original unit, they somehow, for some reason, did not get around to making that critical comparison test.

A final word
I stand by my original comments on the cause of the controversy. If by making essentially minor modifications on a $700 transistor power amplifier Bob Carver can cause it to sound indistinguishable from a $10,000 (for stereo) audiophile tube amplifier, then the whole rationale for esoteric high-end audio is obviously called into question. And when a magazine’s editorial content (and advertising revenues) are based on high-end mystique, there seems to be sufficient reason for them to have second thoughts on the Carver Challenge.

But aside from the motivations of all the parties involved, we still have the problem of how to determine the objective facts of the case. I don’t know the answer to that one, except to say that I trust Carver’s motivation (and science) over Stereophile’s.

There’s one aspect of the matter that, I must say, leaves me flabbergasted. I won’t directly quote Stereophile’s publisher (for fear that he’ll sue for copyright infringement) but his final editorial words on the controversy bemoan the fact that Carver’s best design effort was nothing more than a sonic copy of some other manufacturer’s amplifier. And in the Letters column, some of the magazine’s readers were outraged that Carver could mimic the sound of another designer’s amplifier without permission. The implication was that the sound was the result of some engineer’s hard work and careful listening, and Carver was stealing

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Carver has written a 30-page “white paper” explaining his thinking on transfer function-modifications and other technical matters. Priced at $2.00, it is available postpaid and free of charge to readers of this magazine. Send your name and address to: Carver Corporation, Dept. R-E, P.O. Box 1237, Lynwood, WA 98046-1237.

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a valuable property.

I look at the matter somewhat differently. Carver's original design before modification was essentially distortion-free and linear. And its frequency response remained flat with virtually any speaker load it was likely to be connected to. The tube amplifier that Stereophile supplied had input and output impedances that varied with frequency, which resulted in small (±1 dB) frequency-response variations. The specific locations of those variations were somewhat determined by the impedance characteristics of the particular speakers it was connected to.

In my view, the reference amplifier's performance was mildly flawed—but in a way that appealed to Stereophile's critical listeners. Carver's modification of his amplifier consisted of accurately duplicating those existing flaws.

When I originally questioned Carver on this, he said somewhat ruefully that the sonic differences were essentially trivial, and implied that this was his chance to gain credibility with the high-end crowd. I predicted that it wouldn't work because his amplifier wasn't expensive enough to appeal to devout audiophiles. When this turned out to be true, Carver designed his own amplifier reference standard—the super-audiophile Silver Seven, shown in Fig. 1.

A no-hold-barred, cost-no-object exercise, the $8,750 two-chassis (but single channel) 350-watt tube amplifier is replete with a plethora of audiophile excesses such as the result of 14 output tubes, audiophile-approved capacitors and resistors, granite-base shock mounting, solid silver internal wiring, oxygen-free power in the power transformer primary, silver in the secondary, and so forth. A Silver Seven stereo setup will cost you $17,500. Needless to say, the Silver Seven garnered rave reviews.

Carver duplicated the Silver Seven's transfer function in a 550-watt solid-state mono amp available for a mere $1,000 and, subsequently, in a series of lower-priced stereo units. I'm sure that the $17,500 "Silver Seven, shown in Fig. 1.

Seven's transfer function in a 550 watt solid-state mono amp available for a mere $1,000 and, subsequently, in a series of lower-priced stereo units. I'm sure that the $17,500 "Silver Seven" amplifier (and its lower priced brethren) sound great, but I wonder if they sound any better than Carver's original unmodified M-1.0?
O
ver the years, I’ve made a lot of noise about what you need to do to work on the
bench. Just because I haven’t talked about it in a while doesn’t mean that
my opinion has changed—it’s just that other things have come up that are more interesting. I don’t like writing the same thing over and over any
more than you like reading the same thing over and over.

I spent a lot of time last month talking about how you have to be systematic when you’re working on a design if you want to be able to produce something that works. Not everybody with an understanding of scientific facts has an understanding of scientific method, and all the understanding in the world isn’t going to be much good if you don’t work in a
logically manner. But we’ve already been through that together.

Now we all know that working your way through an original circuit design is a complex business. Even at the best of times, the hassles that pop up can be unexpected, mysterious, and apparently unrelated to the job at hand. While a healthy dose of scientific method can direct you to the source of the problem, even someone who’s logical to the point of being obsessive needs a certain amount of hardware to work things out.

As you probably realized, I’m talking about test equipment. If you’ve got a bank book to finance your work, you probably already have a good supply of test equipment. However, if you’re like most of the people I know, the shelf above your bench, while not absolutely bare, is missing some useful stuff.

Test equipment can be divided into two groups—things that should be purchased and things that you can make. Deciding which items to put in which category depends on the kind of work you’re doing, the size of your bank account, and your frame of mind. If you like to experiment with multi-zero frequencies or voltages, both safety and sanity should point you toward store-bought equipment. For most of us, however, home-made test equipment can be a reasonable alternative.

Over the next several months, we’re going to go through the design of some basic equipment for your bench. It won’t be the world’s most sophisticated stuff but, then again, you’re not always designing the world’s most sophisticated circuitry.

Before we get into designing some hardware, let’s spend a minute or so on practicalities. The most common piece of test equipment has got to be a multimeter. There’s no reason why you can’t build one of your own, but this is a good example of a waste of time. If you don’t have a meter that can be bought quite inexpensively. If you’re willing to look at used equipment, the same amount of money will undoubt-
edly get you a meter that, a few years before, was the best one you could buy.

Just as some stuff is so cheap that it pays to buy, some test equipment is so complex it pays to buy as well. I’m talking primarily about an oscilloscope. There are ways to convert TV’s and monitors to work as oscilloscopes but every one I’ve seen is more than a one evening’s project and

the result is, quite frankly, not worth the time spent on the conversion. If you’re interested in building something like that, some companies have kits for scopes that end up being good pieces of test equipment.

Before you go out and spend money, however, be aware that all those kits are complex, costly, and if you screw up it takes a lot of time to
get them working properly. When we get further into this, we’ll take a look at alternatives to commercial oscilloscopes but there’s no way
the stuff we’ll design will be the functional equivalent of a commercial scope in either bandwidth or features. But you’ll see what I mean when we get there.

One of the most basic things to have on your test bench is a good power-supply and that’s one of the things you can easily make on your own in just one evening. Since the job of a power-supply is to provide clean power, many good designs can be built around easily available parts. A few years ago, I went through the design of a variable 5-amp power-supply based on the standard 78-series of voltage regulators. If you’re interested in all the details, you’ll find them in the May to August, 1983 issues of Radio Electronics.

FIG. 1—IN THIS 5-VOLT, 5-AMP POWER-SUPPLY, IC1 is a 7805 voltage regulator; C1, C3 and C4 filter voltage spikes; D1 is a "swamp diode;" Q1 is a pass transistor; and Q2 is a limit transistor.
The final design is shown in Fig. 1. While there's not enough room here to go into a complete analysis of how the circuit was designed, we'll explain how it works. Even though this is a home-built supply, it can supply just as much power as a lot of the commercial ones and should be treated with just as much respect. Five volts may not sound like a lot to you, but at five amps, it can vaporize metal and do all sorts of nasty things.

If you want to get all the power that this supply is designed to deliver, you'll need an input transformer that can put out at least 25 volts and 8 amps. If you can't find one and are forced to settle for something with less muscle, just remember that your output power will be reduced. An 18-volt transformer is going to give you a maximum supply output voltage of about 15 volts.

Your choice of transformer will determine how hefty a part you need for the full-wave bridge rectifier, BR1. Make sure it can handle the voltage from the transformer and can stand a current draw of at least 5 amps. Multiply your voltage and current numbers by 2 and add fifty percent to give yourself a good safety margin for the wattage of the rectifier.

If you've used any of the 78XX regulators before, you'll recognize the basic regulator circuit in the schematic. Capacitors C1, C3, and C4 are used as filters to suppress voltage surges that appear on either the input or output of the supply. Every regulator design has parts to take care of AC ripple and transient voltage spikes.

The shortcoming of the basic regulator design is that whenever you add capacitors to keep the output clean, you're also adding potential problems. One of the most common screwups that has to be handled by a bench power-supply is a short circuit. Since the work area is always littered with clip leads and small pieces of wire (even the ones used on the breadboard), there's always the possibility for shorts to occur.

Output shorts are no problem since the 7805 will rapidly reach its thermal overload point and shut itself down. It may get a bit hot but that's about all. An input short, however, can be a real disaster. When the input of the 7805 is shorted, the output of the regulator will be at a higher voltage than the input. Capacitor C4 will discharge into the regulator's output and current will flow into the output of the regulator. That means the chip's internal pass transistor will be reverse-biased and the only thing you'll be able to do with the 7805 is gold plate it and wear it on your ear.

The problem of an input short is handled by D1—usually known as the "swamp diode." When everything is working properly, the voltage at the regulator's input will be greater than the voltage at its output and D1 will be reverse biased. If the 7805 input is shorted to ground, however, the output voltage will be higher than the input and D1 will be forward biased. Most of C4's current will be shunted by D1 and passed to ground through the input short, which will save the 7805 and whatever happens to be powered by the supply.

When the regulator's current supply limit is reached (about one amp for a heatsinked 7805), Q1 will work as a pass transistor and take up the extra current demands of the circuit being driven by the supply. Transistor Q1 is set up as a simple switch and is controlled by R5. All the supply current passes through R5 and, as it increases, it will reach a point where the voltage across it is high enough to turn on Q1 and the transistor will start supplying current at the output of the power-supply.

No matter how hefty a transistor you pick for Q1 (the MJ2955 can easily handle 10 amps) the potential is there for the same sort of disaster we saw earlier at the output of the 7805. We can guard against that by putting Q2 in the circuit. Transistor Q2 is also used as a...
switch but its job is to shut everything down if the current draw exceeds a preset limit, hence the name “limit transistor.” The turn-on point of Q2 is controlled by R3-R4 in exactly the same way. R5 controlled the turn-on point of Q1. When Q2 turns on, however, it will lower the voltage across R5, turn off Q1, and shut down the supply.

The supply’s voltage can be varied because of op-amp IC2. The op-amp is set up as a non-inverting buffer to isolate the output stage of the circuit from the regulator’s ground leg. When you use R2 to change the voltage at the op-amp’s input, you’ll also change the voltage at the ground leg of the 7805 and force the supply to vary its output voltage as well.

You won’t be able to get 0 volts out of the supply but since there aren’t a lot of circuits that run on 0 volts, that shouldn’t be much of a drawback. A value of 100 ohms for R1 means you’ll have a minimum voltage of about 5.15 volts for the supply.

There’s a good deal of math involved in calculating the resistor values so don’t stray from them unless you’re sure you know what you’re doing. The values for R3, R4, and R5 are all linked together so just remember that changing one means changing all of them.

The supply can be built with any technique you want. Just remember to sink the 7805 and all the transistors as well. Put everything in a plastic box and be certain that the whole thing is properly wired together and make sure that all wires are properly covered. If you want to do some experimenting with the current and trip settings, you’re going to have to understand the way the values are calculated. It’s not difficult since it’s really nothing more than an application of Ohm’s law.

The value for R5 can be figured out in two ways: the easy way and the hard way. Even though there’s a difference in the assumptions made for each method, the practical results are just about the same. If you take a good look at the circuit, you’ll see that the emitter-base junction of Q1, along with R3 and R4, should be considered as you calculate R5 since they sit in the circuit with the emitter-collector junction of Q2. That makes things a bit hairy since the impedance of the transistor is going to change with current flow, voltage, and the other circuit parameters. Speaking practically, however, the effect of Q1’s emitter-base junction is minimal compared to the voltage drop across R5 so we can safely do things the easy way and ignore Q1.

With that in mind, we can calculate the value of R5 by a straight application of Ohm’s law. The 7805 can easily handle half an amp but let’s play it safe and have Q1 turn on when the current flow in the regulator exceeds 250 milliamperes. The turn-on voltage for Q1, as it is for any silicon transistor, is 0.65 volts. Since we want it to turn on when the current flow is 250 milliamperes, we can get the value for R5 from Ohm’s law.

\[
R5 = \frac{E}{I} \\
R5 = 0.65 \text{ V}/0.250 \text{ A} \\
R5 = 2.6 \text{ ohms}
\]

Since R3 and R4 are in series with R5, the value of 2.6 ohms is therefore the total for all three resistors. In order to find the correct value for R5, we have to work out the value for the parallel combination of R3 and R4.

The problem can be simplified by ignoring the emitter-base junction of Q2. The practical effect is minimal and the value we get without considering it is, as they say, “close enough for government work.”

\[
R3/R4 = \frac{E}{I} \\
R3/R4 = 0.65 \text{ V}/5.0 \text{ A} \\
R3/R4 = 0.13 \text{ ohms}
\]

The final value for R5 is simply

\[
R5 = R_{\text{TOTAL}} - (R3/R4) \\
R5 = 2.6 - 0.13 \\
R5 = 2.47 \text{ ohms}
\]

Since a 2.47-ohm resistor isn’t exactly a common thing, I’ve used a standard 2-ohm value instead. That changes the circuit trip points a bit but makes building it much easier. You can use several resistors in combination to get 2.47 ohms but it’s not really worth the trouble.

When we get together next time, we’ll look at some test equipment to build. We’ll start out with some standard digital stuff and see where we can go from there. You’ll begin to see that, even though some test equipment is too complex to build, there are other items that can be built quite easily. You’ll not only save money by building certain items, but you’ll also gain a complete understanding of how the device works, and have the fun of building it yourself.

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Eventually, even small offices like mine have to face up to the fact that a bunch of standalone PCs is not as powerful as a bunch of networked PCs. But networks are notorious for being expensive, difficult to administer, and time-consuming. In fact, cost is not a major problem; there are numerous low-cost packages designed for networking a small office. Initial installation of most low-cost packages is fairly simple, but depending on the complexity of your setup, administrative requirements increase rapidly, as does the requisite amount of time.

During the past few years, I've installed and tried to work with several low-cost LAN solutions, including DeskLink, LANLink, PrinterLAN, ReadyNet, and most recently, LANtastic. In each of the first four cases, a brief trial period was enough to convince me that networking would have to wait. LANtastic, however, looks like it's going to stay—at least in my system, that is.

**Why bother?**

One problem I had to solve was a lack of expansion slots. In my main PC I simply don't have enough interface slots for modem, fax, video, serial/parallel ports, memory, scanner, tape backup, floppy and hard disk drives. Rather than finding a special motherboard with 16 slots, I can use off-the-shelf hardware, simply add another PC to the net, and gain several additional slots. So, in a very real sense, a network becomes a kind of bus extender. And doing it that way makes the overall system more reliable, because if a machine goes down, the system as a whole remains operational. If I stuffed everything in just one PC, and it died, I'd surely be in deep trouble.

Another problem is printer sharing. Laser printers still aren't cheap enough to dedicate one per machine unless, that is, if you have a tremendous bank account. There are inexpensive ways to share a printer, but doing it via a network provides a great deal more flexibility, not to mention speed. By letting a PC other than your main one function as a print spooler, printing from your main machine returns you to your task quicker, meanwhile letting the spooler dump your job to the printer as fast as possible.

Another problem concerns system backups. You can carry an external tape drive from machine to machine, backing up each in turn. Or a much easier solution is that you can connect all machines via the network and back each one up from a central location, depending on your network architecture.

The downside to those benefits is the expense of buying, installing, and maintaining a network. Over the long haul, the initial purchase and installation will be a fraction of the overall cost of a network. So one measure of the appeal of a network for a small office is the difficulty of the path from simplicity to sophistication. In other words, can you start out simple and increase sophistication gradually? Of course, there are numerous technical concerns that you must think about before installing a network system: network architecture, speed, compatibility, cabling, and so on.

**LANtastic**

LANtastic has a great reputation. After playing with it over the past several months, it's easy to say that its reputation is well deserved. LANtastic is inexpensive, easy to install, and easy to grow with. It lets you start simple and get as sophisticated as you need. LANtastic is truly frugal in its use of RAM, and its drivers can be loaded in the twilight zone between 640K and 1MB, thereby leaving you with a large chunk of conventional memory. In this day of multi-megabyte software, it's really amazing what LANtastic can do. Figure 1 shows a photograph of a populated LANtastic board.

If you know anything about networks, you know that there are two basic architectures: server and peer-to-peer. LANtastic provides features of both types of architectures. A LANtastic network consists of at least one server and one workstation. Resources on a server are available to other machines across the network, subject to security constraints; resources on a workstation are available only to that workstation. Some network operating systems require a dedicated server, but under LANtastic, a server can function simultaneously as a workstation. It will run slower than a plain workstation, but by running non-demanding software, you can get away with a non-dedicated server until your business can really justify one. Running a PC as a server requires more memory than a simple workstation.

LANtastic can run on several varieties of hardware, including plain serial ports, proprietary two-megabit/second adapter cards ($249 each), or standard 10MBPS Ethernet cards ($349 each). Artisoft sells two-station starter kits for $199, $525, and $725, respectively. The 2MBPS card is interesting because it contains its own on-board CPU and RAM, so conventional memory usage is cut to just a few K. However, for performance reasons, I've been playing with the Ethernet kit. In my case, LANtastic requires about 27K on a ...
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SECRET OF THE COMMODORE 64

LaserJets are wonderful. I've had a Series II for about two years, and can’t imagine going back to a clanking, clattering dot-matrix printer. However, dealing with soft fonts is, to say the least, a major headache. In addition, some types of software produce much better output on PostScript devices than they do on LaserJets.

Until now, there was no clean way of getting PostScript output on a LaserJet. Yes, there are software emulators, but they’re buggy and drain system resources faster than a Teenage Mutant Ninja Turtle can down a slice of pizza. Several companies have released PostScript cartridges for the LaserJet II, but past efforts have been plagued by performance and compatibility problems.

That’s all changed with the release of the Adobe PostScript Cartridge (APC). Adobe invented the PostScript language and appears to have mastered LaserJet internals as well. For years, Adobe concentrated exclusively on the Macintosh market, but with the high popularity of Win3, the company has been showing more

and more interest in the PC world. Based on the products I’ve seen so far, it’s too bad Adobe didn’t come over to our corner sooner.

Using the APC is admirably simple. Just plug it into the left cartridge slot of your LJII, reconfigure your software, and you’ve got a low-cost PostScript engine with good performance and built-in LJII compatibility.

You can switch between LJ and PS modes by pressing keys on the front panel or via software. Adobe includes a 10K TSR that switches modes for you automatically. Mode switching is useful because you can’t normally dump READ.ME and other text files to a PostScript printer; nor can a PostScript printer print native LaserJet files. You can declare either LJII or PostScript as default; whenever the software detects a stream of printer data in the other mode, it reverts the printer and puts it in that mode. The software also provides templates for printing raw text files in small fonts, sideways, two or four sheets to a page.

Mode switching works fairly well, but you must wait for one print job to finish before sending another job in a different mode. For example, I sent a PostScript job immediately followed by a straight text file. While the last page of the PostScript job was still rolling out of the printer, the printer switched modes, causing the partially ejected paper to stop moving momentarily. After mode switching was complete, the sheet ejected, but it had a big black smudge where it rested against a toner roller.

As long as print jobs are kept separate, the mode-switching software works fine on a LANtastic print server. Any station on the network can arbitrarily print LJII or PS files across the network, and the print server will put the printer in the appropriate mode for that file.

Adobe is quickly becoming one of my favorite companies, because its products allow me to work better. By handling fonts and printer emulations automatically, the software lets you think about the real problem, not the tool being used to solve it. And that’s how it should be. P.S. Mail order prices for Adobe products typically range from 40% to 60% list prices.

AE-2 can run in 8- or 16-bit mode. In my initial installation in an old 16-MHz Dell 386, I had to run in 8-bit mode. However, after upgrading the mother-

386 workstation (loading nothing "high"), and about 40K on a 286 server (loading low-level drivers "high").
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against a standard value. Any differences produce an error voltage that’s used to control the speed of the cassette recorder. That type of circuitry usually uses a small potentialmeter as a voltage divider to provide the reference voltage to the speed control circuit. Changing the speed of the recorder is simply a matter of adjusting the pot.

The hook here is that, while it might be easy to adjust a potentiometer, you can’t do that until you first know where it is—and that’s where the need for the service manual comes in. If your cassette recorder doesn’t use that method to control the speed, you’ll have to locate the power leads—and that’s where the reference voltage is.

You can’t do that until you first know where it is—and that’s where the need for the service manual comes in. If your cassette recorder doesn’t use that method to control the speed, you’ll have to locate the power leads and add a bit of circuitry to control the motor voltage. That’s not hard to do and only requires, as you suggested, a few components.

There are several small circuits you can use to control the speed of a small DC motor and one of them is shown in Fig. 1. Before you start modifying the cassette recorder however,

**BASIC DIFFERENCES**

I recently became the owner of an IBM computer and, after setting it up, I noticed that there are two BASIC programs included with the DOS disk. One is called BASIC and the other is called BASICA. Could you explain the difference between them? — G. Benjamin, Fischer, NY

There are actually three versions of BASIC but the differences between them are really only of historical interest since each succeeding one is a superset of the previous ones.

The simplest BASIC was cassette BASIC, which was originally burned in EPROM’s (or their equivalents) on the motherboard. That practice ended with the introduction of the AT-class machines. If you have a real XT made by IBM, chances are that cassette basic is sitting in chips on your motherboard. XT clone machines provided sockets for EPROM’s but, since BASIC was protected by an IBM copyright, the sockets were never filled. That was left up to you.

The intermediate version of the language contained commands to use the disk drives and was referred to as Disk BASIC. That’s the BASIC file you found on your DOS disk.

The most advanced of the three versions is BASICA—the "A" stands for "Advanced." It has all the commands available in the other versions as well as other commands related to trig, math, and graphics.

I believe that IBM has finally stopped including both BASIC and BASICA on their DOS distribution disks but that was even after the introduction of DOS 3.2. Current versions of DOS only include the more advanced BASICA.

I hope you don’t expect me to give you a reason why IBM kept both versions of the language on their distribution disks for so long. Quite frankly, I don’t have any idea whatsoever and was hoping that either you or some other reader knew why.
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**DYNAMIC RAMS**

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