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# dual trace oscilloscopes 

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Front cover shows a Thurlby OM358 eight-trace multiplexer in use with a Hitachi V121 dual-trace oscilloscope to introduce our oscilloscope survey on page 57. Picture supplied by Thurlby.

## NEXT MONTH

Bob Coates turns the Picotutor's 68705 microprocessor into a simple, low-cost interface for driving a teletypewriter from a microcomputer Centronics port.

As well as providing 5.5 and 6 MHz sound, a synthesized tv modulator can be accurately switched to any u.h.f. channel.

Testing microprocessor systems is not so simple for the first-time builder without access to logic analysers or emulators. Carson gives some simple procedures that highlight hardware and software problems.

Surface wave, charge transfer and digital v.l.s.i. devices have enabled complex and powerful matched filters to be made. Geoffrey Robinson describes some examples that illustrate their different forms and uses.

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# Wirelessworld 

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ty C. Portesque-Webh


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byD. C. M Reall
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## ELECTRONIC DEVICES FOR THE DISABLED

Wimers of the Wireless World compatitim


## DIFFERENTIAL TEMPERATURE INTEGRATOR

by 月. Everets

## CIRCUIT IDEAS

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## PARALLEL-FED VOLTAGE MULTIPLIER

by R. D. Purves ant C. Prescoll


## FREQUENCY RESPONSE ANALYSER

by R. Para, K. Sivasta and S. L. Sudhamurth


## DIGITAL FILTER DESIGN PROCEDURE-3

by d. T. R. Sytuester-bratley


## NEWS OF THE MONTH

TATB S ontical DSP alunithms compressellm.

## LETTERS TO THE EDITOR

Ratlo softwat Energy savimy
logic noise

## OSCILLOSCOPE SURVEY

Non-storage oscilloscopes un to thomhz
DESIGNING WITH THE 68008 MICROPROCESSOR
by A. J. Bath


## 16 LINE PABX WITH OPTIONS

by d. M. Kuiper

## NEW PRODUCTS

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## APPOINTMENTS

## ADVERTISERS INDEX

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REPEATER AMPLIFIERS
TSC3660 Repeater, Gain 16-36dB UHF, $10-30 \mathrm{~dB}$ VHF. Maximum output 60 dBmV . $\begin{array}{ll}\text { TSC3665 } & \text { Repeater. Gain } 16-36 \mathrm{~dB} \text { UHF', } 10-30 \mathrm{~dB} \text { VHF. Maximum output } 65 \mathrm{dBmV} . \\ \text { TSC3060 } & \text { Repeater. Gain } 10-30 \mathrm{~dB} \text { VHF. Maximum output } 60 \mathrm{dBmV} .\end{array}$


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## Software copyright and piracy

The issue of software copyright is a vexed and intractable one. On the one hand, there is the undoubted need to provide a living for programmers and maximum distribution of valuable software. On the other hand, one must consider that software is not an art form and can be derived independently from situation logic; furthermore, if a processor contains many equivalent registers, any change in the use of registers means a new program, therefore people desirous of stealing the work of a programmer for commercial gain and having the time to do it and the backup to pay lawyers, presumably can. As Dean Swift pointed out, that the lawyer is interested in "whether the said cow be black or white" not in what title the claimant has to the cow.
There are two alternatives to ensure a proper return. Either every user must pay a fee to the inventor of the program, or the state must use the award-to-inventor system. Attempts have been made to shame users into the former course by writing on software packages the fact that the programmer must live and asking all users to buy their own expensive copy, for the fact is that popular material will always tend to be expensive, providing quite unjustified returns, like a best-selling book, while the minority-interest material will with the greatest difficulty recover costs. A book or program concerned with sewage cannot sell more copies than there are sewage works, yet may affect the lives
of every citizen. Thus authorship of all kinds is grossly ill-rewarded by the commercial system.

This problem is entirely new, because in the past technical authors might be reasonably expected to have academic jobs and programs be published free. There is no way that the cottage industry of software production can protect its copyright. It must rely on honourable treatment. If it doesn't get it and if as a nation we want this industry to continue we will have to pay the workers from central funds.

This will distress the computer retail industry who naturally want to sell information in a physical object with a limited life and accident prone condition, like a paperback book.
Anyone who wants to pirate a very valuable program need only buy enough battery backed-up ram to hold it, for there is no way anyone can argue that software can't be copied into ram: similarly it would be very hard to argue that paper tape cannot be cut from this ram.
If one uses selective-bit inversion no one could ever prove a tape was their program; it is foolish to contemplate it. In the end people will pay for convenience if the software creators aren't greedy and shops take reasonable mark-ups. Blatant commercial pirates ought to be prosecuted, but talk of prosecuting friends for exchanging one's own copies is nonsense.

## History in the making

Apart from those few radio and television pioneers who are regarded by the public as the great inventors - Marconi, Armstrong, Baird, Watson-Watt etc. - the bulk of engineers and scientists who have followed in their wake and contributed enormously to the technology have remained virtually unrecognised. Few engineers, let alone the public, associate the coaxial cable with Franklyn, the waveguide with Southworth, the optical fibre pipe with Kao . . . etc. Very few engineers write readable autobiographies, fewer still form the subject of in-depth studies by historians who can appreciate the precise value of the contributions they made to the state-of-art.

Occasionally one comes across exhortations to technologists such as "It isn't enough in any science to do things. It is necessary to communicate what has been done . . . not only your scientific or engineering results but also talk about how they arose, who was involved, all those things that are too often unrecorded. People's memories are not precise. But that does not matter because the essence of historical scholarship is to use memoirs and other primary sources with discretion. A person who has participated shouldn't worry about that bias he has due to his participation. The historians will take care of that in due time by comparing sources and checking dates."
Excellent advice - provided always that those later historians actually start digging, and manage to produce books that can be read with interest!
These thoughts have been generated by reading two recent exceptions to the general rule: Dr George Brown's lively and outspoken recollections of his life as a research engineer "and part of which I was" (Angus Cupar Publishers) that covers not only his pioneer work on aerials, r.f. heating and colour television but the familiar problems of an engineer caught up in commercial and political struggles to gain acceptance for his ideas. The second book was Andrew Hodges' excellent 600 -page study of "Alan Turing - The Enigma" (Burnett Books, 1983) that provides a detailed study of the life and tragic early death of the brilliant mathematician who in 1936 first outlined the concept of the 'universal machine' from which was to spring the digital computer. He was a gifted member of that formidable team of cryptoanalysts who in the "creative anarchy" of Bletchley Park successfully tackled the difficult German naval enigma machine code; taught himself electronic and radio engineering in a couple of months at Hanslope Park; and struggled at NPL to get built the stored program computer ACE but found bureaucracy too strongly entrenched. In fairness to NPL, Turing was clearly not the easiest or most
diplomatic person to work in harness with, though capable of attracting intense loyalty from those who assisted him during wartime.

A few years ago I received a letter from a technician who had worked alongside Turing at Hanslope when, with Donald Bayley, he was developing the never-to-beused Delilah speech encryption system. Alan Turing was then advising the whole 'laboratory on circuit calculations, he had picked up practical radio engineering in less than three months, claiming "When I first looked at radio I could see it was $100 \%$ mathematics anyway so it was no problem."
Andrew Hodges has amassed an enormous amount of information on Turing, but the reason for his suicide in June 1954 remains a mystery. Hodges shows that the often-mentioned prosecution of Turing on homosexual charges was by then two years behind him. He speculates on the continued involvement of Turing with GCHQ in an era when the security investigations following the Burgess, MacLean, the third and fourth man scandals were still rumbling on, but provides no evidence of any link between these events and Turing's untimely death. Certainly there can be no evidence that Turing, patriot that he was, was ever a real security risk.

## NTSC, PAL and SECAM

Dr Brown is particularly revealing about the bitter struggle in the period 1945-1955 between RCA and CBS over the sequential and compatible colour television systems, and the subsequent struggle in Europe over NTSC (which was basically the RCA system), PAL and SECAM. He shows clearly, though from an American viewpoint, that politics rather than engineering dominated the CCIR meetings at Vienna and Oslo, and the similarity of Russian, American, French and British skulduggery in the form of overnight changes of policy, suppression of technical reports, rigging of delegations and the like. As one retired British television engineer put it to me, in recommending George Brown's lively account of his struggles with RCA's management, "Just change the name of the firm, and you have the story of my life". For any young engineer who wishes to understand how things really happen, this is essential reading - though I noted that even the politically-conscious Dr Brown apparently failed to note one of the most astonishing events of the Oslo CCIR meeting in 1966 . In April of that year, a member of the British delegation returned (unsuccessfully) to the UK during the event for the express purpose of trying to have the Post Office man in charge of the British delegation removed, leading later to an off-the-record press briefing in which the leader of the British team bitterly attacked the broadcasting delegates.

## Data security

Presumably we shall never know whether Turing was under pressure from the security people in 1954 though one has no doubt that, as a wartime member of the Government School of Codes and Ciphers, he would have figured in those secret files that will remain inviolate under both the 30-year rule and the Data Protection Bill. Yet there is plenty of evidence that such files frequently contain information confused by mistaken identification etc. This might not matter so much were it not for the evidence that the Security Service advise outside organizations, including commercial firms, when recruiting engineers for sensitive posts. With such information now fully computerized, the effects on people's careers can be farreaching. Unlike many other countries not even the registrar, who will administer the British Act, will have power of inspection or supervision of either security or police files.

## Clandestine war plans

Surprisingly one of the official files of 1953 now opened under the 30 -year-rule details plans then proposed for clandestine activities in the event of war. The 1982 Falklands campaign showed that such activities still form an important part of British military planning. The 1953 proposals covered "stay-behind", evader and coup-de-main activities. Sir John Sinclair, then head of the Special Intelligence Service, requested the use of 15 fast patrol boats, three trawlers, 42 fishing boats, 8 long-range aircraft, use of a submarine, and no less than 400 specially trained signals operators. Britain, France and the USA were each expected to provide 500 agents and 50 aircraft for the first three weeks following the outbreak of war. It was recognized that such activities were a gamble, possibly paying a high dividend or "next to none". One wonders if the agents knew that they were to be part of a high risk gamble.

## Costly clangers

Governments can and do make bad mistakes on their assessment of new electronics technology in addition to grossly underestimating the development costs. Now, the French Government and their nationalised Elf-Aquitaine oil company has been forced into revealing that they were "taken" to the tune of some $£ 60$ million by the so-called Omega and Delta oil-sniffing systems that purported to reveal deeply buried geological strata to aircraft flying overhead, but was eventually shown to depend on prepared sketches fed into the machine. By surrounding the invention with an air of mystery, the Panamanianregistered company, Fisalma, was able to block all attempts to examine the costly prototypes. But it is not only the French

Government that has been known to back the wrong horse in electronics and telecommunications.

Recently Americans have become increasing!y uneasy that the electronics equipment put into military aircraft, flight simulators etc can cost up to ten times its civilian counterpart. The electronics can cost many times more than basic aircraft. As one writer put it recently: "In the necessary secrecy that shrouds weapons development, a pipe dream can be pursued for years - and for billions of dollars before someone catches on to its futility." The solution, it is suggested, would be to introduce independent technical monitoring of projects by a watchdog committee of top-notch engineers. But, one wonders, who would watch the watch-dogs? Engineers, as well as administrators, have been known to get it wrong.

## The AM-stereo struggle

At the end of 1983 there was still no clear outcome to the "market-place" struggle in the USA between the four competing systems of a.m. stereo. In terms of transmitters, Harris had lost the lead to Kahn's independent sideband system used by some 80 stations including several major NBC music stations. Harris was stuck at about 65 stations, resulting from the FCC decision to restrain the company from marketing any more exciters until the type-acceptance dispute had been fully cleared up. Motorola was up to about 50 and their system has been endorsed by some large car radio firms. Trailing with single-figures was the Magnavox system, despite it being the original choice of FCC in 1979. Meanwhile Sony has marketed a $\$ 90$ combined a.m./f.m. portable that can receive any of the four a.m.-stereo systems and including a switch to widen the m.f. bandwidth to 12 kHz . A multimode set has also been marketed by Sansui.


## 50 MHz extension

The Department of Trade and Industry has agreed to a substantial extension of the special research permits for 50 MHz operation by British amateurs holding Class A licences. The number will go from 40 to 100. DTI have asked the RSGB to recommend additional names by March 31. With all British 405 -line television broadcasting in bands 1 and 3 now due to end in the first week of January 1985, British amateurs are hoping that the DTI will make an early announcement about any plans to implement the recommendation in the interim Merriman Report in 1982 that an alloca-
tion in this part of the spectrum should be made available to all British amateurs. There remains the problem that this part of the frequency spectrum (except channel 1) is likely to remain in use for television in virtually all other European countries.

## RTTY

Ian Wade, G3NRW, the current editor of the British Amateur Radio Teleprinter Group newsletter, estimates that about one half of BARTG members are still using mechanical teleprinters but many are in process of adopting computer-based the electronic systems with over two-thirds of the membership owning home computers. Interest in the Amtor system with automatic correction of errors is also increasing rapidly and expected to really take off during 1984 with commercially manufactured units increasingly available. He also forecasts more amateur interest in digital data techniques including the"packet" systems. But there seems to be no end in sight to various problems of different technical standards, including the long standing problem of 45 versus 50 baud transmission, though some teleprinters, such as the Creed 444 will cope with both speeds. Bob Sayers, G8IYK is seeking contact with radio amateurs interested in adapting compact telephone-line facsimile equipments for h.f. transmission or for using such machines for other applications. He also points out that a special Met Office licence is needed to receive weather messages in r.t.t.y. format. Application forms for DTI licences can be obtained from Meterological Office (Licensing) London Road, Bracknell, Berks, RG12 2SZ. Full title of the licence is "Receiving licence for the reception of meterological information transmitted from special service stations"

During 1984 BARTG celebrates its Silver Jubilee having been founded in 1959. The group caters for those interested in most forms of data transmission, including r.t.t.y., Amtor, Fax, weather forecasting, satellites and telemetry. Current membership is about 1300. Membership details from John Beedie, G6MOK, 161 Tudor Road, Hayes, Middlesex UB3 2QG (telephone 01-561 0010). Apart from the quarterly newsletter BARTG publish "RTTY, the easy way".

## Low power activity

Although extreme low-power operation is not an activity I would recommend to newcomers to the h.f. bands, it holds much interest for those with the necessary experience and patience. Indeed on some h.f. bands signals can come in at good strength from transmitters using power inputs of less than 5 watts over many thousands of miles. Low-power (QRP) operation in the UK has for a number of years been en-
couraged by the "G-QRP Club", formed in late-1974, and now having almost 2500 members. Rev George Dobbs, G3RJV, editor of its quarterly journal "Sprat" admits to being concerned that the fall-off of conditions on the h.f. bands due to the declining sunspot activity may make it more difficult to achieve good contacts on the higher of the h.f. bands but urges more activity on the "low-power calling frequencies" of 3560 kHz and 7030 kHz . He notes that low-power operation on these bands has not kept pace with the increasing number of members. He reports, however, an increasing interest in home construction of low power transmitters and compact direct-conversion receivers.

## In brief

George Stratton Loughton, founder in the 1920s of Eddystone Radio, died during December 1983. Eddystone was one of the first British firms to cater specifically for short-wave enthusiasts and radio amateurs with their "All World" series of receivers and components for home construction.
. RSGB membership has exceeded 35,000 for the first time . . . The RSGB National VHF convention is being held on March 24 at Sandown Park Racecourse, Esher, Surrey . . . A mobile rally is being held at the Carelton Community Centre by the Pontefract society on March 18 ... An increasing number of amateurs in many parts of the world are now equipped for earth-moon-earth (moonbounce) contacts on the 1.3 and 2.3 GHz band but Z 25 JJ , representing Africa, is closed for the time being while his equipment, including a massive 32 ft dish reflector, is transported from Zimbabwe to South Africa . . . Much effort is being put into the rush building at the University of Surrey of its second spacecraft, UOSAT-B, which it hoped will be launched this Spring . . . Of the various Russian amateur satellites, RS6 and RS8 remain in operation. The problem on the L-band Oscar 10 transponder seems to have been successfully overcome . . . The IARU Region 1 Triennial Conference, bringing together the national IARU societies in Europe and Africa, is to be held in Sicily between April 7 and 14 . . . The installation of the RSGB's 50th President, R. G. Barrett, GW8HEZ, was at Cardiff Castle on January $14 \ldots$ A number of changes affecting the British CB licence were introduced on February 1. No further licences are being issued to persons under 14 years of age but they can operate CB equipment under supervision. There is now an explicit ban on the playing of music and the re-transmission of radio and television broadcast material (both of which have always been illegal) and DTI draw attention to the CB Code of Practice in particular highlighting the recommendation that Channel 9 should be used for emergencies and assistance only.

PAT HAWKER, G3VA

# Adaptable typewriter interface 


#### Abstract

Simple interface connects electronic typewriter to computer parallel output port. Selfdocumenting Pascal code facilitates translation into other languages that might be used in the target processor, and demonstrates how a printing routine is constructed rather than provides a rigid routine for only one situation.


Acquisition of a home-based computer requires a decision as to the type of printed output needed. The provision of a fullyformed letter printer allows a system to be used for word processing with a degree of professionalism that is absent from the usual low-definition dot-matrix machine. If an electronic typewriter is availble then the simple interface described here enables it to be driven from a Centronics or other parallel output port.
The interface is in principle applicable to any typewriter mechanism that uses electronic-style switches to complete a circuit when a key is depressed. Virtually all daisy wheel printers use this type of mechanism. Since the majority of small computer systems do not have printer spooling (i.e. the system is dedicated to driving the printer whilst the printer is active) the computer is used to provide as much as possible of the intelligence of the interface.

Although the interface itself is simple it is necessary to do some investigation to determine the correct connection points for the various wires - and then further work to find the correct data for each printed character. The interface was actually connected to an Olivetti Praxis 35 and the specific data as to connection points and character data refer to this machine. Enough information is included to enable adaption to any other machine.

## General considerations

In operation the printer sequentially grounds one of the lines marked A through H and reads the data appearing on all the lines a through h, Fig. 1. If no keys are closed then the data will be read as all high but otherwise the occurence of a low will allow the closed key to be detected and decoded. Two points about this - first, a number of reads must give the same data for the printer to register the key closure and to avoid errors due to contact bounce. Second, not all possible crossing points on the matrix are used and so there are a number of possible data codes that may have no meaning to the printer as they should not be generated by the keyboard. Also there are two connections outside the matrix (I to i and J to j ) used to tell the printer about keys that are pressed in conjunction with the main keyboard. Examples of this on the Praxis are Shift

## by <br> C. M. Fortescue-Webb M.Sc.

and Keyboard 1 or Keyboard 2.
To simulate a key closure the circuit of Fig. 2 could be used. When the select key line is true then the low-going pulse on the input line be coupled through to the output. By using open collector gates there will be no interaction between the various keys. The difficulty of such a scheme is that a key select line is needed for every key and this requires a lot of hardware. By using a multiplexer and demultiplexer coupled with open collector drivers the final arrangement shown in Fig. 3 is realised. Now three lines are used to select the input row and a further three to select the output column. The remaining two llines on the eight-line computer output are used for the shift and keyboard $1 / 2$ switches. Incidentally, if your computer will only output a seven-bit character on the parallel port then the keyboard $1 / 2$ or equivalent line will have to be operated manually.

It is also necessary to prevent the computer passing data to the printer at a rate in excess of that at which it can accept the data. The interface shown here uses a software delay loop in the driving routine to ensure that the character rate is within specifications. A longer delay is used for those functions on the typewriter that take longest - carriage return (up to two seconds on the Praxis), fast return (timing as carriage return) and tab. The alternative is to use hardware consisting of something like a 555 timer with a variable current source depending on the character being printed, with the output from the timer being the busy line and used for character separation. To achieve a maximum transmission rate it would be necessary to find an internal (to the printer processor system) status line that will show if the printer can accept a character and then use this line for the BUSY/ACKnowledge reply to the computer.

When the computer outputs data on a Centronics interface the strobe line is made low for a short time (a few microseconds) to tell the printer that data is available.


Fig. 1. Schematic of the mati:ix switching layout of typewriter keyboard. A keyswitch is present, normally open at intersections marked*. Pull-up resistors to $V_{c c}$ are connected to lines a to $j$ inclusive.

The printer responds by asserting BUSY and should pulse ACKnowledge low to signify that the character was accepted. When the printer is ready to accept another character it will drop BUSY. Many computer systems are content to ignore either BUSY or ACKnowledge but printers requiring line buffering (normally line printers) may use ACKnowledge to fill the line buffer and then assert BUSY whilst the characters are printing. Strictly the computer is not permitted to change the data on the Centronics port between the assertion of STROBE and the receipt



Fig. 2. Possible connection method to simulate a key switch connection when key-select is high. This circuit would be substituted at each * in Fig. 1, in which case a low on $X$ will be coupled through to $x$ via the open collector gate.
of an ACKnowledge, nor to assert STROBE whilst the printer is BUSY.

## Circuit details

The functioning of the actual circuit is straightforward and the full schematic is shown in Fig. 4. The layout corresponds to that used in Fig. 3. The monostable between the strobe and busy lines is used to separate a multiple sequence of the same character into separate 'key depressions' by enabling the LS138 for a set time after each strobe pulse. The period of the monstable must be adjusted to be sufficient for the printer to recognise the character yet less than the intercharacter delay and the shown values provide a good starting point. The maximum $R$ value is about $5 \mathrm{k} \Omega$ due to limitations of the LS t.t.l. inputs.

The original was constructed on Vero d.i.p. breadboard using ribbon cable to couple the inputs and outputs. If a small system is being used then it may be more convenient to add on a eight-bit latch to the computer address/data lines rather that construct or purchase a specific parallel port.

If the keyboard uses greater than five volts then a small 5 V supply will be needed for the logic and the inputs to the LS151 should be isolated using diodes connected in series with the lines to the LS151 from the keyboard with the anode connected to the interface. If a key is pressed on the keyboard whilst the interface is connected then the keyboard supply voltage can be coupled through to the multiplexer unless isolation from higher voltages is implemented.

The typewriter/printer lines are shown with the connection schematic for the Praxis. It is possible that your warranty on the typewriter could be effected by connecting this modification and so it is perhaps wise to wait until it is out of the warranty period. When making connections to this main board be aware that mos chips may be used internally and so static should be avoided (no nylon carpets, plastics worktops etc.). A soldering iron with low leakage or securely grounded would be a wise precaution if using soldered connections. If using a mains-powered wire-wrap tool then do not work on the interface whilst it is connected to the keyboard.

## Detective work

One of the first operations is to examine the keyboard connections of the selected machine to ensure that it is possible to


Fig. 3. Using a multiplexer and demultiplexer to replace a keyboard.
make the connections without having to, for instance, replace the complete case. First be quite sure that the mains cable is removed from the machine - a surprise jolt when you are probing inside the machine can do much damage to man and machine. On the Praxis after unscrewing the two platen knobs, without losing the small disc in the left hand one, four screws in the underneath of the case can be removed. Turning the case right side up again should enable the top section to be lifted off over the back of the machine. Be careful of the paper-holding bar. The keyboard can now be removed by undoing the two screws, one at either end, that hold the metal backing plate to the base of the typewriter case.

Lifting it off gently brings to light a number of connectors and these can be parted without putting any tension on the wires. At this stage the printer processor and electronics will be exposed to view along with three brass nuts positioned on the processor board that hold grounding straps and the processor board to the keyboard sub assembly. After noting the way in which the grounding straps are positioned the nuts can be undone and the keyboard and processor unfolded to show the printed circuit traces of the keyboard and processor connections. A drawing of the two boards opened out is shown at Fig. 5 with the connection points numbered to correspond with the schematic diagram Fig. 4.

Suppose that the typewriter is a different model from that used above. Then some investigation is necessary to find the connecting lines. Without the manufacturers service manual the best method is to follow the printed circuit traces to the various keys. Keyboard switches may have either three connections (with the outer two commoned-check with a meter) or just two. The key connection traces should either end up on a chip with open collector drivers (in which case they are being driven from the printer processor) or else be connected to pull-up resistors if an input to the processor. If the keyboard processor combination can be 'powered up' whilst access is retained to the keyboard traces then processor output wire should have no or small voltages on them whilst processor input traces should be at 5 V due to the pull-up resistors. In any event, provided that the keyboard is powered from five volts, an incorrect connection of the traces

to the interface will not cause damage but prevent the interface and/or the typewriter working properly. There is no need to assign specific assignments to each of the input/output connections on the interface since a software routine is used later to determine the actual data required to
simulate a specific key closure.
The next stage is to determine the output data required for each simulated key closure. Connect up the computer-in-terface-typewriter combination and then run a program to output characters (with data values in the range of 0 to 255) and see

List 1. Program to produce a file 'Trans. text' of ascii character and corresponding code to operate printer.

```
Program Decode; (* Pascal under UCSD Version 4 *)
var Translation_file : text; (* data and character file *)
        Printer
        j
            text; (* Treated as a file *)
            integer; (* loop variable *)
                            char ; (* character read from vdu *)
Begin; (* program from hereon *)
Rewrite( Translation_file,'Trans.text'); ("Open Output file*)
Rewrite( Printer,'Printer:'); ("Open Printer*)
For j:= 0 to 255 do begin; (* main loop *)
    Write(printer,chr(j));
    Write(' Enter (* data to printer *)
    Read(ch); (N for non printing)');
    writeln: (*ead character inputted from vdu *)
    writeln(Translation file,j:5,ord(ch) line on vdu*)
    end; (* end of main j loop *)
Close(Translation_file,Lock); (* keep the translation file *)
end,
```

List 2. Program to show how translation data can be used to run typewriter using codes from program in List 1.

```
Program Encode; (*Uses translation file to print on typewriter *
Const cr = 13; (* carriage return ascii value *)
Var Printer : text;
    Decode : Array(0..255) of 0..255; (* holds printer codes *)
        k : char; (" only used in demonstration program *)
Procedure PRINT INIT; (* Initialises for the Printer *)
Var Translation file : text; (* data setup in program DECODE *)
        data, code, }\mp@subsup{}{j}{j}\mathrm{ : integer;
```

    Begin; (*procedure Print_init *)
    Reset (Translation_file, Trans.text'); (*Open file *)
    For \(j:=0\) to 255 do Decode ( \(j\) ) \(:=0\); (*initialise Decode array *)
    For \(j:=0\) to 255 do begin; (* file data to decode *)
        Read (translation_file, data, code ); (* read a line from file *)
        Decode(code) := Data; ( and put to decode *)
    End;
    Close(Translation_file); (* no further need for this *)
    Rewrite(Printer,'printer:'); (*open printer for output *)
    end; (*of procedure Print_init *)
    procedure delay(ticks:integer); (gives a 'ticks' milliseconds delay )
    var \(i, j, k\) :integer;
    begin;
        For \(i:=1\) to ticks do
        For \(j:=1\) to 8 do \(k:=k+i(1 \mathrm{~ms}\) delay \()\)
    end;
    Procedure PRINT (ch: Char ); (* accepts a character for printing *)
Var $i$ : integer;
Begin; (* Procedure PRINT *)
i := ord(ch); (* find integer value of ascii character *)
$i:=$ decode(i); (* and use to get printer data *)
write(Printer, chr(i)); (* and output to Printer *)
if ch $=\operatorname{chr}(\mathrm{cr})$ then delay (1000) else delay(90); (* $11 \mathrm{c} / \mathrm{sec} *$ )
if ch = Chrlcr) then delay(
End; (* of Procedure Print *)
Procedure PRINT_EXIT; (* called after finished with printer *)

```
Begin; (* start of Print_exit *)
    print(chr(cr)); (*Carriage return to Printer *)
    Write(Printer,chr(255)); (* Holds interface out of action to
                            enable all typewriter functions *)
```

close(Printer); (*No further use for printer *)
End; (* of Procedure Print_Exit *)
BEGIN;

```
(* This is where your main routine would be. The following
    is a short sample Program that can be used to test the
    interface, and would not be present for normal use *)
    Print_init; (* initalise the printer channel *)
    For k :='A' to 'z' do begin;
        write( k ): (* put out the character on vdu *)
        print (k); (* and on the printer to check correct action *)
        end;
        Print_Exit; (* and close up the channels *)
END.
```



Fig. 5. Connection points on the opened out Praxis processor and keyboard.
what the response is from the typewriter. Be aware that some of the unused code can cause the typewriter to 'lock out' and not accept any more input. If this should happen the easiest way to recover is to turn the typewriter off then on again to reset the internal mechanism. Also some software driving parallel output ports will only output seven bits, the most significant bit being masked off as it is not used by many printers. If this is the case with your system then either the driving software can be altered or alternatively one of the dedicated lines (I . . . i, J . . . j in Fig. 1) can be deleted.
In the case of the Praxis this would mean that keyboard 2 was not available but for many applications this would be quite acceptable. The program in Fig. 6 which is written in Pascal will provide you with a file of the data and corresponding characters printed. If you find that the interface is behaving badly, for instance by not printing all characters then check both the interface and connections to the keyboard traces. It is easy to have $95 \%$ functionality even though the shift line say is not connected.

## Operation

The final step is to generate a small program that takes any character that you wish to output to the printer, translates this to the appropriate data code, and then outputs it on the parallel interface. The best method of implementing such a routine is in assembly language and then to incorporate it into the bios (basic inputoutput system) so that the operation is transparent to the host program. To give an idea of what is required and to provide a basis for further experimentation the small routine shown in Fig. 7 is written in Pascal and can be incorporated into an applications routine. The routine is broken up into three procedures: Print-init to open the printer channel, Print to actually translate and output the characters and Print-over to perform any closing tasks. Note that the main translation array TRANS must be declared in the main routine since Pascal cannot hold local variables from call to call of a sub routine. If you wish to use the printer for word processing then you will probably want to extend this program to enable such things as underlining and printing both $£, \mathrm{p}$ and \$, c.
continued on page 39

# Improving colour television decoding 

4 - Simple one-line comb decoder on a small single board can be added to existing receivers

Much of the background material and illustrations in these articles derives from the author's BBC work and that of his colleagues in the Research and Designs Departments. The particular proposal for a domestic receiver decoder described here is the author's own rather than a BBC concept.

Considering now the actual electronics, Fig. 34 shows a circuit diagram of the video path built to incorporate the

The full extent of picture improvement can only be achieved if the suggested modifications are incorporated into a receiver in which attention has been paid to a number of other aspects of performance, a similar experience to improving high quality audio. These would include the use of a 26 in tube (preferably high resolution), an efficient aerial (possibly with a down-lead amplifier), a tuner and i.f. amplifier response flat to 5.5 MHz and with the demodulated video group-delay equalized to give minimum phase errors. It would also be beneficial to receive the incoming r.f. signal from a transmitter of good performance.
The performance of the modifier used to comb chroma from the composite signal (to provide clean furninance) is degraded in the presence of phase errors. These errors are largely introduced by the video signal modulation and demodulation processes and mainly comprise poor group delay response across the chroma bandwidth ( $\mathrm{f}_{\mathrm{cc}} \pm 1.3 \mathrm{MHz}$ ) and by differential phase (chroma phase shift with the change of luminance level).
Further information on transmitter performance and alternative circuits to place between the i.f. output and the PAL decoder will be given in a later article. These alternative circuits would be preferable for smaller screen sizes (assuming the standard iv receiver tube).

Some other developments which will be of relevance if the time delay for their introduction and cost are not too great are ITT's digital tv i.cs and the Philips n-mos memory chips. Philips also make a high resolution 2 in twbe (which will probably double the standard tube price) that can be operated at twice the normal line and field scanning rate. Memory chips store the incoming signal over a field or picture period; video information is thus available for scanning twice in the period of one input picture. This double scanning removes flicker and enables other decoding methods to be used, as outlined in the December and January articles. (See also the German Radio Show report, November 1983 issue pages 74, 75.)

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foregoing principles (part 2, January issue). Composite video ( $1 \mathrm{~V} \mathrm{pk}-\mathrm{pk}$ ) is applied to the circuit to produce outputs that are suitable for the various decoder chips now readily available. Output pins can directly feed the decoder chips TDA35 16A or 3560 from Mullard.

Transistors $\mathrm{Tr}_{1}$ and $\mathrm{Tr}_{2}$ are complementary emitter followers providing low-impedance drives, appropriate resistors being fitted to match the delay-line characteristic impedance and the chroma bandpass filter impedance. Also, a low-impedance feed is available for the sync filter which is an optional extra. The three coils and capacitors ( $\mathrm{L}_{1-3}, \mathrm{C}_{5-7}$ ) form a symmetrical gaussian bandpass filter (described later) set up by adjusting all three inductors so that maximum subcarrier level occurs at the output, also with minimum 7.8 kHz at chroma transitions.

The filtered chroma signal is fed out via $\mathrm{Tr}_{18}$ to provide low-impedance drive to the chroma input pin of the demodulator chip or chips. PAL decoding i.cs normally use a


Fig. 35. Modifier comb-circuit waveforms. Top trace is the input composite PAL video signal, middle trace shows the chroma envelope after the $\operatorname{Tr}_{1}, \operatorname{Tr}_{2}$ buffer and gaussian bandpass filter. After a further buffer this signal is fed out to pin 3 of the decoder TDA 3561A (or 3560) (if the onechip decoder is used). Minimum 7.8 kHz twitter at chroma transition indicates good group delay symmetry in the gaussian filter. Bottom trace is the luminance signal as fed to pin 10 of the one chip decoder.
chroma-length line ( $64 \mu \mathrm{~s}-56 \mathrm{~ns}$ ) to provide delay-line PAL decoding for enhanced U/V separation in the chroma circuits. Colour prints 7, 8 and 9 are screen photographs with luminance off, showing, in print 7 , the chroma demodulation performance using the field sweep skew test waveform for line-by-line decoding. Print 8 shows one chroma line in use i.e. combing the chroma over two lines; this is the standard method in most television sets. Using two-line delays, print 9 shows threeline combing in the ratio $1 / 4: 1 / 2: 1 / 4$. The third line has no offset whereas the centre line has a 56 ns offset. No further chroma work was felt necessary on this add-on card and this design will use one chroma line. This is a reasonable compromise which provides some comb filtering of the luminance, a $3-\mathrm{dB}$ reduction of fine crosscolour, and, by adding and subtracting equal amplitude from the two lines, a 3 dB reduction of random noise occurs. The slight loss of vertical resolution is only apparent when viewing computer graphics. Spatially, on horizontal transitions, the luminance and chroma are displaced by half a line in the field, but this is only seen on electronically generated signals.

In the circuit of Fig. 34, $\mathrm{Tr}_{3}$ amplifies the signal from the chroma bandpass filter to provide a high level input for the DL60 delay line, which has a typical insertion loss of 11 dB . The output transducer of this delay line is floating and can therefore provide a balanced push-pull drive to the MC1596 balanced modulator input with the d.c. supply bias provided by resistors


Fig. 37. Signal waveforms for the complete decoder. Top trace is 1 V composite video input. The lower three traces are red, green and blue outputs from the modifier comb and TDA3516A (or TDA 3560) chroma chip.

$\mathrm{R}_{29}$ and $\mathrm{R}_{30}$. The gain of this modulator, acting as a PAL modifier, is set by the resistance between the emitters of the transistors being driven from the chroma delay line. Pins 7 and 8 have suitably phased and d.c. balanced ( $\mathrm{R}_{42}, 5 \mathrm{k} \Omega$ pot.) drives of 8.8 MHz (twice colour subcarrier) taken from the chroma demodulator chips via buffer stages $\mathrm{Tr}_{8}, \mathrm{Tr}_{9}$ which also provides phase shift. The two phase shifters plus the changeover shown adjacent to $\mathrm{C}_{28}$ and $\mathrm{C}_{29}$ mean that the change in phase setting available to the modulator is in excess of $360^{\circ}$. Thus a setting will always be found, regardless of the decoder chips being used, to obtain the correct phase in the overall system. Pin 9, the demodulator output is fed directly to a grounded base stage via 10 nF blocking capacitor ( $\mathrm{C}_{21}$ ). Therefore no signal can be seen at pin 9. Also summed at the grounded base stage is the composite PAL video from the luminance delay line. The delay of this, compared with the delay time through the gaussian bandpass filter plus the DL60 delay line and the modifier, is such that the two signals summing at the grounded-base stage are exactly $64 \mu \mathrm{~s}$ apart.

The collector load of $\mathrm{Tr}_{4}, \mathrm{R}_{20}$, gives sufficient gain to provide a suitable level to the output filter, this being buffered by emitter follower $\mathrm{Tr}_{6}$ and $\mathrm{R}_{23}(150 \Omega)$ representing the characteristic impedance to the output filter.
The first sections $L_{8}$ and $L_{9}$, form a
phase/group delay equalizer as is $\mathrm{L}_{10}$. The filter itself is formed by $L_{11}$ and $L_{12}$; the last element in the filter $\mathrm{L}_{12}$ has an additional capacitor switched in by the f.e.t. to bring it to resonance at subcarrier frequency when the notch is needed, such as at a horizontal colour transition. As the notch switches in and $\mathrm{L}_{12}$ becomes resonant, the input impedance to the filter rises. The small resulting increase in voltage available at $\mathrm{Tr}_{6}$ emitter therefore drives $\mathrm{Tr}_{5}$ harder and the notch 'snaps in' with a positive-feedback effect. Components $L_{6}$ and $C_{13}$, with variable resistor $R_{24}$ are in series resonance at subcarrier frequency; $\mathrm{R}_{24}$ is adjusted to set the threshold of the notch. The notch will switch in very quickly with Tr s bottoming on the peaks of the 4.43 MHz oscillations developed across $\mathrm{L}_{6}$. With $\mathrm{R}_{25}$ of $10 \mathrm{M} \Omega$ the decay is slow, switching the f.e.t. off about half a line later.

If the voltage supplied to the gate of this f.e.t. is displayed on a black and white receiver with an external sync feed and viewed adjacent to the colour receiver, the amount of time the notch is in is shown to represent a very small proportion of the total picture area. The loss of resolution
can therefore be considered slight. It is also statistically unlikely that fine luminance detail will occur on horizontal colour transitions when the notch is switched in.
If luminance detail is continually present at 4.43 MHz , the notch will be introduced and detail lost; it is as if the notch were always present. But the delay in operation of the adaptive notch switch will allow luminance edges through unscathed and this gives subjective improvement to the picture resolution.
It has been found in practice that with an input of test card $F$ from a slide scanner, the threshold control resistor is best set so that the 4.5 MHz gratings pass through with minimal degradation. Subcarrier from horizontal coloured edges will then cause the notch to switch in if the amplitude increases above the equivalent amplitude of this 4.5 MHz grating. The 4.5 MHz grating on the analogue test card (about to be replaced by a digital one) is well below the 0.7 V black-to-white amplitude. However, switching to the electronically generated signal Channel 4 test card, the notch is permanently in during the 4.5 MHz grating. But on pictures, the notch switches in when horizontal dot


PAL modifier

Notes
(1) L5 and $R_{21}$ can provide 1 to $3 d \mathrm{~B}$ h.f. lift, normally shorted by link.
(2) $R_{25} 10 \mathrm{M} \Omega$ for slow turn-off of adaptive notch, $100 \mathrm{k} \Omega$ for fast turn-off
(3) $C_{14}, R_{27}$ slightly speed-up switch-on but need not befitted Setfor best 2 T lobes
(4) $C_{11}$ not fitted but can be used to trim phase
(5) Poly $\equiv 2 \%$ polystyrene Cer $\equiv$ ceramic disc or Redcap/Bluecap
(6) $\mathrm{C}_{30} 100 \mu \mathrm{H} 2 \mathrm{~V}$ Mullord for three-chip decoder. Lum. input has 2 k 7 in series \& 22 K to 12 V . Remove R 40
(7) Refer to next installiment for filter adjustments
(8) Inductors are wound with 5 or 6 -strand $48 \mathrm{sw.g}$. Litz or 38 s w. $(0.16$ or 0.14 mm dia.) enamelled copper wire
crawl becomes just visible at normal viewing distance, assuming $\leqslant 3.5 \times$ screen diameter. This seems a suitable criterion for determining the threshold of the notch. It may be considered that a slightly lower threshold which degrades 4.5 MHz gratings on the test card will further reduce visibility of horizontal dot crawl. This is a setting which will be made subjectively to suit the individual.

At the output of the filter the signal is terminated ( $\mathrm{R}_{37}, 150 \Omega$ ) and buffered. Transistor $\mathrm{Tr}_{7}$ provides a low-impedance drive output as many clamps in decoder
chips require a low-impedance point. The coupling capacitor may have to be changed to suit the time constant of such clamps, depending on whether the extra circuit board is fitted to a three, two or one-chip decoder.

## Setting-up procedure (luminance)

In the first place, it is required to obtain a timing difference between the two signals summed at $\mathrm{Tr}_{4}$ emitter of exactly $64 \mu \mathrm{~s}$. $100 \%$ colour bars are used as the test signal, although $95 \%, 75 \%$ or EBU bars would be suitable.

Fig. 34. Diagram of circuit that processes chroma and luminance signals.

| No. | Volue <br> $(\mu \mathrm{H})$ | _ ___ Turns ___ |  |
| :---: | :---: | :---: | :---: |
|  |  | Neosid E2 | Toko 10K |
| 1 | 33 | 37 | 55 |
| 2 | 23 | 34 | 42 |
| 3 | 54 | 15 | 18 |
| 4 | 10.5 | 21 | 27 |
| 5 |  | Painton or Sigma | chake |
| 6 | 6 | 16 | 21 |
| 7 | $\begin{aligned} & 9.7 \\ & \text { or } 10 \mathrm{P} \end{aligned}$ | $\begin{array}{r} 20.5 \\ \text { Painton or Sigma } \end{array}$ | 26 choke |
| 8 | 14.3 | $13+13$ | 1616 |
| 9 | 2.4 | 10 | 13 |
| 10 | 16.6 | $14+14$ | 17+17 |
| 11 | 3.8 | 13.5 | 16 |
| 12 | 5.1 | 15 | 18 |
| 15 | 150 P | Painton or Sigma | choke |



1. Disconnect either the input or output end of $\mathrm{DL}_{1}$, and with the $2 \mathrm{f}_{\mathrm{sc}}$ feed also disconnected (by removing the links adjacent to $\mathrm{C}_{28}$ and $\mathrm{C}_{29}$ ) unbalance the modifier pins 7 and $8\left(\mathrm{R}_{42}\right.$ turned to an end-stop).
2. With the output of the modifier linked to $\mathrm{R}_{12}, \mathrm{~T} \mathrm{P}_{1}$, the chrominance passing through the gaussian filter and DL60 delay line can be displayed on an oscilloscope and the signal path checked.
3. Reconnect the modifier $\mathrm{Tr}_{4}$ emitter so that the chroma envelope can be seen at the output test point $\mathrm{TP}_{4}$ (Fig. 34). The waveform appearance should be as shown in Fig. 35, middle trace. The green/magenta centre transition, will need to be expanded on the oscilloscope so that the signal is resolved down to 50 ns (see Fig. 24, January).
4. The link at $T P_{1}$ is switched so that the modifier output is across $\mathrm{R}_{12}$ and is not fed into $\mathrm{Tr}_{4}$ emitter. Reconnect $2 \mathrm{f}_{\mathrm{sc}}$, put the oscilloscope probe on $\mathrm{TP}_{1}$ and rebalance pins 7 and 8 on the modifier so that the carrier ( $2 \mathrm{f}_{\mathrm{sc}}$ ) is nulled to zero. This represents carrier balance of the modulator/modifier.
5. Again feed the direct composite PAL

The normal functions expected of a PAL decoder are adequately provided by the Mullard one-chip decoder TDA3561A. The chip requires separate chroma and luminance inputs - the circuit of Fig. 34 provides these in enhanced form. Pin 25 feeds PAL modifier via Tr $_{15}$ in Fig. 34.
signal to $\mathrm{Tr}_{4}$ emitter by reconnecting $\mathrm{DL}_{1}$. This results in the colour bar signal being seen at the output test point $\mathrm{TP}_{4}$ (Fig. 35 top trace); the delay line must now be adjusted so that the green/magenta transition occurs exactly at the same timing as it would in the gaussian/DL60/modifier route. The aim should be to get a timing coincidence of better than 50 ns and as good as 20 ns if possible (top trace, Fig. 24 January). Note the amplitude.
6. Disconnect either the input or output lead of $\mathrm{DL}_{1}$ as before, re-connect the modifier (link at $\mathrm{Tr}_{4}$ emitter), adjust the gain of the modifier with $R_{32}(1 \mathrm{k} \Omega$ pot.) to obtain the same chrominance amplitude as in preceding step.
7. Reconnect the luminance (link at $\mathrm{DL}_{1}$ ), with the chrominance from the modifier also being summed at $\mathrm{Tr}_{4}$ emitter, it only remains to adjust the phase of
the modifier output. Using $\mathrm{R}_{86}$ ( 10 k pot.) and $R_{89}$ ( 5 k pot.), the coarse and fine phase adjustments in the $2 \mathrm{f}_{\mathrm{sc}}$ feed (and, possibly, the links adjacent to $\mathrm{C}_{28}$ and $\mathrm{C}_{29}$ for $180^{\circ}$ change), a point will be reached where the phase of the chroma from the modifier will cancel the chroma of the composite PAL signal.
8. The amplitude of the $2 \mathrm{f}_{\mathrm{sc}}$ feed from the phase shifting stages $\mathrm{Tr}_{8,9,10}$ can be from 0.3 to $1.3 \mathrm{~V} \mathrm{pk}-\mathrm{pk}$ and it may be necessary to adjust $\mathrm{C}_{34}$ and/or $\mathrm{C}_{35}$ to obtain reasonably constant amplitude as the appropriate 'set phase' controls are taken between end stops. Check at $\mathrm{Tr}_{9}$ emitter first and adjust $\mathrm{C}_{34}$ on test for constant amplitude over the full range of $\mathrm{R}_{86}$. Repeat for $\mathrm{C}_{35}$ and $\mathrm{R}_{89}$.
9. Finally to achieve the best null and to optimise the chroma cancellation on all levels (steps) of the resulting luminance, a small adjustment on the gain will be required. It is as well to use the gain pot ( $\mathbf{R}_{32} 1 \mathrm{k}$ ) the phase pot ( $\mathbf{R}_{89} 5 \mathrm{k}$ ) with the modifier balance pot ( $\mathrm{R}_{42} 10 \mathrm{k}$ ) in a converging sequence to minimize residual subcarrier for all the steps in the luminance signal.
The trace in Fig. 35 shows the composite PAL signal as measured across $\mathrm{R}_{2}$ (input

terminating resistor), the middle trace is the chrominance at $\mathrm{TP}_{2}$ which is being fed out to the chroma circuits of the demodulator (external to this additional circuitry), and the lower trace at $\mathrm{TP}_{4}$ shows that the chroma from the modifier output is cancelling the composite PAL chroma to leave a clean luminance signal.

Fig. 36 shows some optional additional circuitry that may be used depending on the receiver to be modified. Point X is taken from the emitter of the input buffering pair in Fig. 34, $\mathrm{Tr}_{2}$. This feeds a filter with a characteristic impedance of $1 \mathrm{k} \Omega$ provided by $\mathrm{R}_{46}$. The high-impedance terminated filter has a low-pass linear amplitude response which removes all the subcarrier and highband luminance energy but retains the sync risetimes with optimum shape. The filter design will be detailed later with group delay/phase and amplitude responses. Transistor $\mathrm{Tr}_{11}$ amplifies the signal and $\mathrm{Tr}_{12}$ emitter follower drives the sync separator chip $\mathrm{IC}_{1}$, (TDA2590). There are other versions i.e. 2591, 2592, 2593 but in this application the available alternatives are not important. All the chips are capable of driving line output stages and field scan i.cs directly.

The chip has a sync-slicing system which is self-adjusting, according to the video amplitude, to maintain a $50 \%$ slice on sync edges. The line frequency can be set to approximately 15.625 kHz using $\mathrm{R}_{71}$ ( $50 \mathrm{k} \Omega$ pot) with the input signal shorted at the points shown adjacent to $\mathrm{C}_{52}, \mathrm{R}_{60}$.

Fig. 36. Diagram of circuit of sync
processor chip providing field blanking and other pulses.

When the short is removed, the phase locked loop is centralized. This chip also provides field triggers and line triggers. By feeding the line trigger output pulse back into the chip (on pin 6 via $R_{58}$ ) a 'sandcastle' pulse is generated which, if necessary, is then available for the chroma decoder chip. In most of the receivers, however a sandcastle pulse is already available and this circuitry would not be required.

The line and field trigger pulse trains could both be used to drive line and frame time bases if the whole receiver is being engineered. There is another optional circuit available. This widens field trigger pulses via the monostable ( $\mathrm{Tr}_{15} / \mathrm{Tr}_{16}$ ) and thus provides blanking of the ITS (insertion test signal), and teletext (Ceefax and Oracle) and other data signals in the field block. See Fig. 38.

On the author's attic workroom receiver, the picture is underscanned so that all four corners can be seen and the 'business' at the top of the picture becomes unacceptable without widened blanking The extra blanking circuit ensures that only active picture lines are displayed. The other optional extra, formed by $\mathrm{Tr}_{13}$ and $\mathrm{Tr}_{14}$, is solely used to drive test gear which needs to be locked to mixed syncs.

The luminance output of the board from $\mathrm{Tr}_{7}$ can be coupled into the Mullard one-


Fig. 36(b). Some of the waveforms occurring in Fig. 36 circuit. Trace (i) is video signial fed to pre-sync separator filter $C_{37,} L_{15}$ and $C_{36}$. (iii) is field trigger from pin 8 of TDA2592 and (iii) line trigger from pin 2. (iv) shows RGB clamping (top), output picture blanked (middle) and active picture - line and field blanking off (bottom).
chip TDA3561A (or 3560) which is mainly used as a colour decoder (see Fig. 20, January issue pages 54,55 ). The coupling component feeding the luminance input, on pin 10 can be a $0.47 \mu \mathrm{~F}$ non-polarized ceramic/polyester capacitor. The chrominance input on pin 3 fed from $\mathrm{Tr}_{18}$ also requires d.c. blocking; 10 nF is suitable. The d.c. on both pins 3 and 10 of the decoder chip are typically 2.2 V and the output on $\mathrm{Tr}_{7}$ is typically 3.5 V . If a small tantalum capacitor is used, check for polarization particularly where other chips are employed.

Full amplitude levels in I T.S. and the high levels of teletext plus IC.E signals (internal communications equipment) need to be fully blanked


Output from pulse-widening circuit $T_{15}, T_{16}$ in Fig. 36 to blank all the active lines in the
field block, important if the tube is underscanned or subject to internal reflection



Fig. 38(b). Off-air video signal and extra blanking to prevent any adverse visibility at the picture top. Top trace shows some lines in use in the field blanking period. Bottom trace is final green drive to display tube, indicating line blanking and extra field blanking provided by the circuit of Fig. 36 .

Provision was at one time made to adjust the chroma level output with a pair of resistors attenuating the feed to $\mathrm{Tr}_{18}$ base. When adjusting the level feeding the decoder chip TDA3561A or the equivalent two and three-chip versions, it was found to be difficult to determine which chroma level suited the decoder to obtain maximum chroma linearity (the linearity being somewhat poor). Also the matrix which produces the red, green and blue signals

Fig. 38. Vertical synchronizing and blanking waveforms. As shown, field blanking interval lines are also used for teletext, ICE (internal communications equipment), ITS (insertion test signals), and clear lines for noise measurement. TDA2562A also uses lines 21, 22, 23 for RGB tube black-level stabilizing.
from the luminance and colour-difference signals can have up to $10 \%$ and amplitude errors. By optimizing the chroma level and averaging out the matrix errors across the RGB outputs a fairly good compromise can be achieved as is shown in the photograph, Fig. 37.
The blanking as generated by the extra circuitry $\mathrm{Tr}_{16}, \mathrm{Tr}_{17}$ and $\mathrm{IC}_{1}$ (TDA 2590/1/2/3) is applied to the blanking input of the TDA3561A chroma demodulator chip. A line-rate trace of the blanking component is shown in Fig. 37 in which the fainter line represents the field blanking. Using this trace and with the oscilloscope timebase switched to field lock, the pot $\mathrm{R}_{76}$ is adjusted so that the field blanking ends at the beginning of the first line in the active picture. The blanking should end half way through line 23 in the first (even) field, and at the beginning of line 336 on the second (odd) field; see Fig. 38. The
insertion test signal (two lines per field), teletext information (four lines per field or six lines on some channels), and the ICE signal (internal communications equipment coding line), will then all be blanked by the widened field pulse.

With the extra board (modifier etc.), set up, the picture will attain a horizontal resolution which is close to the vertical resolution. The equivalent vertical and horizontal resolutions can be calculated as follows. There are 625 lines transmitted in each picture period ( 40 ms ) but as 25 lines are blanked in each field $(20 \mathrm{~ms})$ there are only 575 active lines in each picture or 287.5 active lines per field. These 287.5 lines determine the vertical resolution, i.e. the maximum number of cycles that can occur within the picture height. The transmitted pictures has a horizontal to vertical aspect ratio of $4: 3$, so 287.5 vertical cycles are equivalent to 383.3 horizontal cycles. Given that the active line period is $52 \mu \mathrm{~s}$ ( $64 \mu \mathrm{~s}$ less $12 \mu \mathrm{~s}$ blanking), the period for each cycle of this maximum equivalent horizontal resolution then is $135.62 \mathrm{~ns}(52 / 383.3)$. The frequency is to equivalent to 7.37 MHz . This is the justification for improving the horizontal resolution.

MaN


Left to right: Bill Bond (judge), David Gemmell (judge), Philip Darrington, H.R.H. Princess Anne, Sir Keith Sxinner (cheirman of Susmess P-ess international), Heinz Wolff (judge), Richard Lambley, Elizabeth Fanshawe (judge), Meredith Thring (judge).

# Electronic devices for the disabled 

First prize in Wireless World's recent competition was won by Tony Heyes of Nottingham University for his Sonic Pathfinder, a navigation aid for the blind. Dr Heyes received his award of $£ 2,500$ from Princess Anne at a presentation on January 30. Second prize, £1,500, went to Phil Pickersgill and Nic Stewart of Wokingham for a speech training device which they named Pausaid.

The four $£ 1,000$ prizes for runners-up went to

- David Battison and David Palmer of Cambridge, for their Miaphone, a speakback facility for blind, disabled typists.
- Michael Bolton and Alastair Taylor of Aberbeen, for their computer interface for the disabled.
- William McCarthy of Edinburgh, for his depth gauge for the visually handicapped.
- Ian Mitchell of Hull, for his Talking Box, a communication aid designed initially for speech-impaired children.

Judging and presentation of the awards took place on January 30th at the Institution of Electrical Engineers in London. Twelve entries selected for the final stage of the competition were demonstrated to the judges by their authors, who were Elizabeth Fanshawe of the Disabled Living Foundation, David Gemmell of Possum Controls Ltd, Bill Bond of the Polytechnic of the South Bank, Professor Heinz Wolff of the Brunel Institute for Bioengineering and Professor Meridith Thring, Queen Mary College, London University.
Princess Anne spent more than half an hour examining the devices and discussing them with their designers. In an address afterwards, she spoke of the ingenuity and inventiveness of those who had entered the competition. She said "Your enthusiasm and your efforts may not make you household names, but will certainly earn
you the sincere gratitude of a highly individual and progressively independent group of people". Princess Anne spoke also of those who had not reached the finals, whose entries might still warrant development and possible future production. "If they do that", she said, "they will have their own reward".

Speaking on behalf of the judges, Professor Wolff praised the designers for their cost-consciousness. They recognised that technical aids had to be paid for by someone. "A competition of this kind as a stimulus for technically knowledgeable people to exercise their compassion and think about people less fortunate than themselves is itself very valuable".
An article by Dr Heyes describing his prize-winning entry will appear in Wireless World shortly, and we plan to include details of other interesting entries during the next few months.
 editor, with Dr Heyes and a Sonic Pathfinder. Left is Richard Lambley, projects editor.

Dr Michael Bolton (right) shows Princess A.7าe his compuier interface.


# Differential temperature integrator 

Battery-powered remote-reading integrating thermometer has application in energyconservation schemes

As much as $25 \%$ of the UK's primary energy consumption is in domestic buildings, yet relatively little is known about the details of its use. Individual tastes vary wildly and variations of annual energy consumption of $3: 1$ or more between identical houses are quite common. Because of this, testing out some new insulation measure or heating system requires monitoring a large number of houses. This can be a very expensive business.

The traditional instrument for temperature recording has been the thermograph, a kind of clockwork chart recorder, still to be seen ticking away in the corners of art galleries and museums. More recently memory-based electronic recorders have appeared that can be read out into a computer.

For most housing work all that is re-


Fig. 1. Three-wire bridge circuit puts equal lead resistance in each arm, with one lead in common.

## R. Everett

quired are weekly or monthly averages of temperature plus the opportunity to sample spot values, such as the evening living-room temperature. Most importantly, this must be done without disturbing the house occupants and without spending vast sums on cabling back to a central datalogger. The differential temperature integrator was specifically developed for the Pennyland field trial in Milton Keynes, one of many sponsored by the UK Departments of Environment and Energy in recent years, and involved monitoring 80 houses of varying insulation level and south-facing window area ${ }^{1}$.

## Why a 'differential' integrator?

The heating energy consumption of a house is roughly proportional to the average inside-outside temperature difference $(\Delta \mathrm{T})$, the constant of proportionality being an indication of the insulation level of the house. To evaluate the effectiveness of insulation, weekly heating energy consumption needs to be correlated with weekly $\Delta T$. We can extend the process to include solar radiation to make an estimate of the 'passive' solar gains into a house. ('Passive' as opposed to the 'active' solar energy that you get from solar panels.)

As various zones of a house are at different temperatures, a weighted average of


Fig. 2. Battery-saving circuitry samples temperatures every few minutes - the
amplifier and $v$. to $f$. converter are multiplexed between sensors.
the different temperatures of different rooms is required. Thus the job of the d.t.i. is simply to generate cumulative integrals of the difference in temperature between each of three sensors inside the house, two downstairs and one upstairs, and a fourth on the outside, preferably on the north side out of the sun's rays. The temperatures are sampled every 8 minutes and the cumulative integrals are clocked up on three liquid-crystal displays, in units of degree-days (i.e. 1 degC for one day, commonly used in building work). For the Pennyland field trial the integrator was mounted alongside the gas and electricity meters in an external meter cupboard where it could be read by the researchers without entering the house. The d.t.i. also has a hold mode allowing any of the four temperatures to be sampled on a test point with a d.v.m.
This device is a logical solution to a monitoring problem; I was not surprised therefore to find a paper proposing such a device after completing the prototype ${ }^{2}$.

## Circuit design

The temperature sensors used are thinfilm platinum resistance types (such as RS 158-238), effectively precalibrated to $\pm 0.3 \mathrm{degC}$. This type of sensor has a resis-

Designed for temperature monitoring in energy conservation field trials as Milton Keynes this thermometer provides weekly average temperature dif. ferences between each of three zones of a house and the outside air cemperature. Put crudely, heating energy consumption to a house is proportional to the temperature difference and the constant of proportionality is a meawure of the quality of house insulation. The device requires three platinum rocisrance thermometers installed bo the house, nominally one each in living room, kitchen and a bedroom, and an outside air temperature seasm. These four sensors are wired to the integrator box located in some convenient place, such as a meter or bin cupboard on the outside of the house, where ir can be read weekly along with gas and eleciricity meters without disturbing the house occupants.

Fig. 3. Temperature integrator is mounted in the house external meter cupboard with other meters - the sensors are up to 10 metres away.



TOTAL GAS

tance of 100 ohms at $0^{\circ} \mathrm{C}$ rising to 138.5 ohms at $100^{\circ} \mathrm{C}$.

Because lead resistances are likely to be significant it is usual to use them in a bridge arrangement, as in Fig. 1. Here the p.r.t. is compared with a precision 100 ohm resistor (e.g. RS158-086) and the bridge ensures that equal lead resistances appear in each arm, with one resistance in common.
I wouldn't recommend the use of i.c.
constant-current sources in this type of bridge. Many have large temperature coefficients (read the fine print for long-term drift characteristics!) and more than one is sold as a dual-purpose constant-current source/temperature sensor! More recently, precalibrated thermistors have become available cheaply and these are now a better choice for temperature measurement than p.r.ts because of their higher output.
The temperature integration process is

achieved by feeding the difference between the inside and outside temperatures to a voltage-to-frequency converter and then counting and displaying the resulting pulses. To minimize drift, the bridge amplifiers are ICL7600 commutating autozero types. To keep the component-count down the internal temperatures are mutiplexed into a single bridge amplifier and v -to-f converter (see block diagram).

Much of the circuitry is devoted to battery saving. This allows four D -size and six AA-size alkaline cells to last up to six months.
The 32.768 kHz crystal oscillator is counted down by 4040 counters and decoded with the 4068 and gate to wake up the sleeping system for two seconds in 512 (about eight minutes). In the off state, battery consumption is essentially that of the three liquid crystal displays (about $300 \mu \mathrm{~A})$. The circuit cycles through four phases of 500 ms each, starting with a settling period with the amplifier inputs grounded. Then each of the sensors in turn is routed through the input multiplexer and the bridge amplifier to the v -to-f converter. The resulting pulse train is routed to the appropriate 4040 counter and 7224 counter/display driver.

The v-to-f converter (Teledyne 7400 or RS307-070) requires a stabilized negative voltage rail as a reference, the stability of



To separate displays
as above


Fig. 4. Light-emitting diode and associated switches were included for production testing and could be omitted. The l.e.d. was an idea to set the $v$. to $f$. converter gain without an oscilloscope by beating the output against the crystal clock, but the 'scope is a lot easier in practice.
the positive rail being not nearly so critical. Hence the use of a 9 V battery regulated to 5 V to drive v-to-f converter, bridge amplifiers and the bridge.

Pressing any one of the individual hold buttons powers the system. The 4532 priority encoder selects the appropriate two-bit address and also allows the normal integration mode priority should the counter time out. The bridge amplifiers are powered and the appropriate temperature can be sampled on the two test points with a d.v.m. ( 1 volt $\equiv 10 \operatorname{deg} C$ ).

## Setting up

The design contains a rather confusing array of switch settings for testing and setting up, most of which turned out to be unnecessary. The bridge amplifier gains
and offsets can easily be set up in the hold mode using standard resistors ( $100 \Omega=0^{\circ} \mathrm{C}$ and $110 \Omega \equiv 26.0^{\circ} \mathrm{C}$ ). The v-to-f offset is set to give a 5 Hz tickover at zero $\Delta \mathrm{T}$ (visible on the l.e.d. in the set-zero switch position). The v-to-f gain is set by adjusting the output to 8.192 kHz at a $\Delta \mathrm{T}$ of $16.9^{\circ} \mathrm{C}$. The beat between the v-to-f output and the reference signal from the clock chain should be visible on the l.e.d. with the test switches set to set-gain. Alas, in practice it is far more visible on a 'scope.

One vital ingredient missing from the design is a way of detecting leaky c-mos chips. With complex battery powered equipment, one leaky chip or a floating gate can mean the difference between microamps and milliamps of battery consumption. But which chip is it? Desoldering them at random from a double-sided printed circuit board is a recipe for disaster, and yet a few 100 ohm resistors in the power rails to localize the fault could have saved many boards from the bin.

This design dates from 1980. A production run of 100 were made in 1981 and have performed reliably since then. With
the close of the Pennyland field trial they are likely to be passed on to further trials. Although the design is a little dated, it is still difficult to get the same performance at the price from a micro design (the components excluding board and box come to about $£ 120$ ), but it it is only a matter of time.

Members of the Open University Electronics Common Facility transformed the scruffy prototype into a production device. Funding for the Pennyland project came from the Department of Energy, through their Passive Solar Energy Programme, and the Department of Environment as an extension of their 'Better Insulated House' programme.

## References

1. Energy Projects in Milton Keynes, S. Fuller, J. Doggart \& R. Everett, 1982. Available from Milton Keynes Development Corporation.
2. Simple data-logging instrumentation for monitoring the thermal performance of buildings, Charles Newcomb, Proc. Sth Passive Solar Conference, University of Massachusetts, 1980.

## Adaptable typewriter interface coninued form poge 28

Table 1. Small sample of the output of program of List 1.

| Data <br> to <br> printer | Ascii <br> decimal <br> equivalent |
| :--- | :--- |
| 12 | 82 |
| 13 | 77 |
| 14 | 64 |
| 15 | 75 |
| 16 | 94 |
| 17 | 94 |
| 18 | 80 |
| 19 | 83 |
| 20 | 87 |

## Notes and limitations

Some residual problems exist such as the fact that the ascii code does not allow for characters such as half-space or $\div$ which are available from the typewriter keyboard. One possible solution to this is to define characters in the code range 128 to 255 and then to use software to substitute these special codes when the alternate character set is required. A decision to include or discard such codes will have a bearing on the complexity of your final program as will, for instance, forcing your non-proportional spacing typewriter to right-margin justify text.

Note that the Praxis does not seem to read the keyboard $1 /$ keyboard 2 status unless the character buffer is empty and so it is necessary to delay before changing the keyboard status if the printing rate is above about ten characters per second.

A more serious limitation is the amount of time that the printer can run continu-

Table 2 shows the ascii code in binary for a character (written in left hand side of column) and decimal data representation of the binary code to be sent to the printer (right hand side). For example ascii code 1100100 is found from intersection of column 100 and row 1100 giving character 'd' translated to decimal code 123 for the printer. Non-printing characters are shown by blank entries.

| Bits 7654 | 321 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 000 | 001 |  | 010 |  | 011 |  | 100 |  | 101 |  | 110 |  | 111 |
| 0000 | nul |  |  |  |  |  |  |  |  |  |  |  | b |  |
| 0001 | bs 114 | ht 70 | uf |  | vt |  | ff |  | cr | 48 | so | 71 |  | 98 |
| 0010 |  | dc1 68 | $\mathrm{dc} 2$ | 67 |  | 65 | $\mathrm{dc} 4$ |  |  |  |  |  |  |  |
| 0011 |  |  |  |  | esc | 96 |  |  |  |  | rs |  |  |  |
| 0100 | sp 113 | ! 154 | " | 22 | \# | 158 | £ | 54 | \% | 29 | \& | 52 |  | 40 |
| 0101 | 18 | ) 56 | * | 30 | + | 26 |  | 125 | - | 80 |  | 85 |  | 62 |
| 0110 | 0120 | 194 | 2 | 86 | 3 | 126 | 4 | 78 | 5 | 118 | 6 | 110 | 7 | 116 |
| 0111 | 8104 | 972 | + | 23 | ; | 87 |  | - 8 | = | 90 | ) | 56 |  | 144 |
| 1000 | @ 14 | A 27 | B | 53 | C | 57 | D | 59 | E | 60 | F | 11 | G | 41 |
| 1001 | H 55 | 110 | $J$ | 47 | K | 15 | L | 63 | M | 13 | N | 45 | 0 | 58 |
| 1010 | P 18 | Q 28 | R | 12 | S | 19 | T | 44 | U | 42 | V | 9 | W | 20 |
| 1011 | $\times 17$ | Y 43 | Z | 25 | 1 | 8 |  |  | ) | 56 |  |  |  | 46 |
| 1100 | Y 40 | a 91 | b | 117 | c | 121 | d | 123 | 2 | 124 |  | 75 | g | 105 |
| 1101 | H 119 | i 74 | i | 111 | k | 79 |  | 127 | m | 77 | n | 109 | 0 | 122 |
| 1110 | p 82 | q 92 | r | 76 | s |  | t | 108 | $u$ | 106 | $\checkmark$ | 73 | w |  |
| 1111 | - 81 | y 107 | $z$ | 89 |  | 8 |  | 157 |  | 56 |  |  |  |  |

ously until it needs a cooling off period. Typewriters are seldom driven by people who type virtually continuously and so they tend to overheat with this kind of use. For example the Praxis is not really up to printing more than 40 minutes continuously without say a 20 minute rest for the mechanism to cool down a bit. If the printer does get overheated it tends to skip characters and generally mess up the text, thus necessitating a reprint. A lot of printing can be done in 40 minutes but for really long and hard use it is probably more effective to purchase a heavy-duty daisy wheel printer in the first instance.
The problem of feeding single sheets of paper into the printer can be overcome
either by forcing a software delay (the simplest method) at the start of each new page or else detecting the form feed character, then setting a latch to hold BUSY high until manually reset.
There are of course plenty of hardware options to add on if desired. A uart can be added to accept serial input but be careful about drawing too much current from the printer power supply. A preprogrammed eprom inserted into the data lines will enable the printer to accept straight ascii character data rather than the modified set used here. By this stage you are probably considering one of those single-chip eprom-based processors to produce an interface with all the 'bells and whistles'.

## Optical-fibre measurements

Used with an optical-fibre directional coupler, these circuits allow backscatter measurements on fibres with $>10 \mathrm{~dB}$ oneway insertion loss. Light pulses of 50 ns are used in the avalanche photodiode preamplifier which, when carefully constructed, has a $10-40 \mathrm{MHz}$ bandwidth. Small-signal Schottky diode D stops $\mathrm{Tr}_{1,2}$ saturating when strong optical reflections occur. Resistor R should be as high as possible, depending on the required bandwidth. When displaying fibre backscatter curves on an oscilloscope, the second amplifier circuit may be useful (b). Oscilloscope bandwidth should be equal to or greater than 40 MHz .
In the GaAs laser-diode pulse circuit, (c) capacitor C charges through the transistors and is discharged through the Siemens fast-recovery thyristor and the RCA SG2004/5/6 laser diode. These 904 nm laser devices suit the C30921 avalanche photodiode. Capacitor C, chosen to give 50\% light-on time, depends on the laser diode and supply voltage and is typically around 8 nF . Pulse repetition rates higher than 10 kHz are possible. Using a ferrite pulse transformer to drive the thyristor provides isolation (shown separately).


As an aid to optical-fibre bandwidth measurement, final circuit (d) can produce light pulses as short as 200ps with capacitor C at 45 pF and using selected transistors in avalanche mode. Input pulse-repetition frequencies between 100 Hz and 100 kHz

are possible. Siemens BC549s showed avalanche effect at $V_{C E O}>70 \mathrm{~V}$ and $\mathrm{V}_{(\mathrm{BR}) \mathrm{CES}}>140 \mathrm{~V}$ d.c. Each of the transistors must be above these limits and only small-signal devices may be used. Wiring within the boxed section should be as short as possible.

## Chopped-light amplifier

Filtering the output of this amplifier to within 100 Hz of the chopping frequency of say 1 kHz allows light levels down to 10 pW to be detected when $R=10 \mathrm{M} \Omega$. A bipolar transistor fixes the fet drain voltage so

selection is not required; drain current may be altered by adjusting the source resistor. Voltage gain of the fet is high through inclusion of capacitor $C$ which provides a high dynamic-load impedance. Amplifier noise is 0.04 pA r.m.s. $/ \sqrt{\mathrm{Hz}}$ and noise of the RCA C30920 p-i-n diode is 0.06 pA r.m.s. $/ \sqrt{\mathrm{Hz}}$.

## Schmitt-trigger opto-coupler



[^2]
## Aligning four frequencies

Four a.c. signals may be compared on a four-channel oscilloscope, but a more graphic representation can be obtained using an oscilloscope in XY mode and adding pseudo- Z and Z modulation signals. This is particularly useful when testing phase-locked loops or tuning several signals simultaneously.

This arrangement, originally devised for a Telequipment D83 oscilloscope, was used to set up two 50 Hz sinewaves in quadrature (at $x$ and $y$ ) by means of a Lissajous circle. A 2.5 kHz signal introduced at $z$ causes the circle to take on a crown shape; this signal appears stationary when its frequency is an exact multiple of the


## Programmable pulses with delay

On triggering, this programmable circuit produces a pulse after a delay. Accuracy of the pulse and delay periods is determined by the accuracy of the clock so the design doesn't suffer from drift associated with monostable circuits and works reliably at high frequencies.

The first counter determines delay and the second one pulse width. Counter $\mathrm{QD}_{\mathrm{D}}$ outputs are used as these change synchronously with the clock and don't produce glitches at the output but it means that the maximum count is half of that possible using the ripple-carry output. Eight-bit counters are shown but any number of bits may be used by cascading more or fewer 74 S163 i.cs. Delay D for a load value L is given by

$$
D=\left(2^{n}-1\right)-L
$$

where n is the number of counter bits. In this case, $n$ is seven.
A. D. Hacket

Salisbury
Wiltshire
fundamental signal. The highest frequency, 5 kHz in this instance, is applied at m to modulate brightness and results in a stationary stripe when synchronized.

With practice, z and m can be adjusted simultaneously. For lower multiples applied to z characteristic shapes are obtained, i.e., three lobes at $2 f$ and four lobes at $3 f$. If frequencies at $x$ and $y$ are not the same, as usual, Lissajous figures are stationary when the frequencies are exact multiples of each other. For digital signals, sensitivity may be increased by reducing series-resistor values.
C. J. D. Catto

Cambridge

## Simplified battery timeout

This contribution is a cheap and simple means of conserving battery power using only six components. After the touch switch is activated, power is applied to the

load for a period equal to $0.69 \mathrm{CR}_{1}$. Resistor $\mathrm{R}_{2}$ determines current limiting and may be changed. Quiescent leakage current is less than 100 nA and with values shown, the power-on period is 13 s and current limiting is at about 450 mA . At 200 mA , voltage drop is only 200 mV .
S. Whitt

Ipswich
Suffolk



## Moving-coil amplifier

I find that this moving-coil cartridge amplifier using valves gives a more natural sound than many circuits using transistors and it is easy to construct. Anode voltage rating of the ECC88 dual triode is only 90 V but it may be taken as low as 10 V so
power-supply design is simplified. The two sections of each ECC88 are connected in series and low-noise transistors connected as constant-current sources form anode loads for the two stages. Gain of each stage is about 30 .

A 723 regulator is used for the main supply because signal-to-noise ratio of the

amplifier depends on noise, output impedance and ripple rejection of the supply. Popular 78 -series regulators are not good enough. Valve heater supply must be regulated for the same reasons but in this case a 7806 suffices. Overall closed-loop gain of 100 is determined by the $33 \mathrm{k} \Omega$ resistor, which may be lowered to reduce gain. Open-loop gain is 600. Loading required for different makes of cartridge varies but is usually between 10 and $100 \Omega$. Capacitors are critical and high-quality polycarbonate or polypropylene types should be used throughout, except for power-supply smoothing.
Per Hojlev
Copenhagen
Denmark

## 15-bit d-to-a using ZN425 converters

Two cheap eight-bit d-to-a converters are combined to form a 15 -bit converter in this circuit. Output of the left-hand converter is calibrated for all input values ( 0 to 255) and a correction value is programmed into the 28 L 22 prom with 00 corresponding to $-511 / 512$ 1.s.b. and $\mathrm{FF}_{16}$ corresponding to $+511 / 512$ l.s.b. This correction is added to the seven least-significant bits of the input data to provide an eight-bit input to the second converter. Reference voltage for both converters is derived from one i.c. to reduce errors due to ageing and temperature fluctuations.

Resistors $\mathrm{R}_{3,5}$ are adjusted to give correct scaling factors for the two d-to-a converter outputs and $\mathrm{R}_{7}$ corrects for output offset. Component values are not shown since these will depend on the application and output voltage range required. Temperature compensation can be applied through $\mathrm{R}_{9}$ and by using an external reference voltage.
S. W. Beet

Merseyside

# The parallel-fed voltage multiplier 


#### Abstract

Although any desired voltage may be obtained by stringing together a sufficient number of cells, a voltage converter has many advantages. Battery testing and replacement are simpler, and there is the option of using a single rechargeable device to power the whole of the circuitry.


Our particular need arose during the design of a portable muscle stimulator for biomedical use. The initial specification called for a unit to give output pulses at 10 Hz , of $200 \mu$ s duration and amplitude 15 mA maximum into a load of approximately $8 \mathrm{k} \Omega$, representing the resistance of electrodes placed on skin over the muscle. The stimulator was to be carried about in a pocket or on a belt, and would be used for 6 to 12 hours per day. The power source was to be a single PP3 9V battery, and we hoped to keep the current drain below 1 mA to ensure long battery life-

The specification evidently requires a voltage supply of at least 120 V . As the output energy per pulse is 0.36 mJ , the average power drawn from the supply is 3.6 mW . If voltage conversion could be achieved with $100 \%$ efficiency, the current drain from the battery would be only 0.4 mA . Thus the target value of 1 mA seemed approachable. However at power levels below 10 mW a conversion efficiency of even $50 \%$ is hard to achieve, as we found by examining a commercial stimulator with broadly similar specifications. It employed the conventional oscillator and step-up transformer, rectifier approach to voltage conversion, and its current drain was several milliamps. This poor efficiency, less than $20 \%$, encouraged us to consider an alternative method.

Fig. 1 shows the well-known CockroftWalton cascade voltage multiplier in the form commonly used when an alternating voltage is available to drive it. A minor modification at (b) enables it to be driven by antiphase square waves which do not have to swing below 0 V . These circuits are series-fed: the a.c. or square-wave driving voltage is applied to the end of a chain of capacitors in series. Design and analysis are notoriously difficult, because the current and voltage waveforms for each stage are different. It is known that with optimal allocation of resources the capacitor values should not all be equal, but should increase from C at the output end to NC at the driven end. Another disadvantage is that the additional output voltage per stage is not constant, but diminishes by one diode drop $V_{f}$ for each stage in the circuit.

[^3]

Fig. 1. In the Cockroft-Walton series-fed voltage muitiplier the output reservoir capacitor $C_{\text {res }}$ is chosen to have a reactance, that is much less than the load impedance at the working frequency. (a) is the single-ended version, while ( $b$ ) is a modification for push-pull input where antiphase square waves do not have to swing below OV.

Thus in Fig. 1 (b) with a driving swing from 0 to $\mathrm{V}_{\mathrm{dd}}$ of 9 V and $\mathrm{V}_{\mathrm{f}}$ taken as 0.6 V , one stage provides $9+8.4=17.4 \mathrm{~V}$, two stages provide $9+8.4+7.8=25.2 \mathrm{~V}$, and so on up to 14 stages which provide 72 V Beyond this limit extra stages contribute nothing.

While pondering these deficiencies we discovered that some remarkable improvements result if the configuration is changed to the parallel-driven form of Fig. 2. The N capacitors now all take the same

[^4]value, which simplifies construction. The open-circuit output voltage per stage has the constant value $V_{d d}-V_{f}$ and so the total output voltage $(\mathrm{N}+1)\left(\mathrm{V}_{\mathrm{dd}}-\mathrm{V}_{\mathrm{f}}\right)$ can be increased without limit. Finally, the analysis is facilitated by the fact that apart from a step-wise increase in d.c. level, the current and voltage waveforms for each stage are identical (this is strictly true only if N is even, so that points X and Y see the same total capacitance).
The most important design parameter of a power supply, after its open-circuit output voltage, is the equivalent output resistance. The parallel-fed multiplier's output resistance can be derived directly as the ratio of open-circuit output voltage to short-circuit output current. For calculation only, it is convenient to return point $Z$ of Fig. 2 to earth instead of to $V_{d d}$ and to treat the diodes as having zero forward voltage drop. With these assumptions the output voltage becomes $\mathrm{NV}_{\mathrm{dd}}$. A further assumption, which will later be relaxed, is that square wave sources X and Y have negligible internal resistance and thus provide a full swing from 0 to $V_{d d}$ regardless of the load. Now if the output terminal is earthed the diodes and capacitors act in 'bucket brigade' fashion to transfer a charge $\mathrm{CV}_{\mathrm{dd}}$ from one stage to the next in each cycle. The average short-circuit current is therefore $\mathrm{CV}_{\mathrm{dd}} / \mathrm{T}$ where T is the square-wave period; it follows that the multiplier output resistance is NT/C.
A more general expression for output resistance, derived in the appendix, is
(NT/C) $\operatorname{coth}(T / 2 N R C)$
in which the hyperbolic term corrects for the finite resistance $R$ of the square-wave


Fig. 2. Parallel-fed voltage multiplier. Resistors $R$ represent the equivalent resistance of the square wave sources.

# Frequency response analyser 

## Using an oscilloscope to display response, this educational aid to understanding frequency response of amplifiers and tuned circuits covers the band 40 Hz to 400 kHz .

The heart of the analyser is a voltagecontrolled oscillator, Fig. 1, whose ramp voltage varies the frequency. The v.c.o. used, the Intersil 8038, has a linear relationship between control voltage and frequency with the required range of $1: 10,000$ covered in four sweeps, each sweep causing a decade change in frequency. A given frequency range depends on external resistances and a capacitor. In our scheme, four different timing capacitors are used, one for each sweep range, switched in a repetitive sequence. The switching circuit shown in Fig. 1 is also used for providing retrace pulses for the bootstrap ramp generator and external trigger input for stabilized oscilloscope display. For a large frequency sweep, the v.c.o. requires a control voltage decreasing from $V_{m a x}$ to $V_{\min }$ of $V_{c c}$ to $2 \mathrm{~V}_{c c} / 3+2$. The level shifter with inversion after the ramp generator shown in Fig. 1 solves this problem.

The v.c.o. output is attenuated and fed to the input of the device under test (d.u.t.), say an RC-coupled amplifier. The frequency-dependent output of the device under test is passed to the oscilloscope $Y$ input.
K. Srivatsa, with a B.E. and M.Tech. in electronics, lectured at the University Visvesraraya College of Engineering, Bangalore, before becoming senior engineer (software) at Processor Systems Pty Ltd, Bangalore. His co-authors graduated from UVCE in 1982 with B. E. (Electronics) and have taken up jobs in power electronics (Sridhara Murthy) and digital microwave communication (R. Partha).

## by K. Srivatsa, R. Partha and S. L. Sridharmurthy

Figure (2a) shows the clock input to the switching circuit, with a duty cycle of about $10 \%$. Waveform (b) is derived from (a) with a period equal to four times the clock period. These pulses are passed to the bootstrap ramp generator circuit causing retrace.

The ramp at (c) has a frequency of

Fig. 2. Waveforms (a) to (f) are found at the nodes 1 to 6 in Fig. 1.


Fig. 1. 8038 v.c.o. covers four frequency ranges, and uses a switching circuit that also provides retrace pulses for the ramp generator and external trigger input. Numbered nodes have waveforms shown in Fig. 2.



Fig. 3. Full range of analyser is shown at (a), with an expansion at (b). Lower trace shows typical output from a tuned amplifier.

400 Hz . This waveform is inverted and level shifted before the v.c.o., whose output is shown in (d). Waveform at (e) has a period of four times the ramp period used for external sweep triggering to give a flicker-free display. Waveforms (f) to (i) switch the required capacitor into the v.c.o.

The performance of the analyser is demonstrated in Fig. 3. Photograph (a) shows the full range of v.c.o. and (b) is an expanded partial range. With this was the input to a tuned amplifier, the resulting output was as shown in (c). The detailed circuit is shown in Fig. 4. Design procedure is easily obtained from the data sheets ${ }^{1}$.

## Improvements

For higher resolution, as in a tuned amplifier which requires a part of the frequency


Fig. 4. Regulated power supply is essential for this simple response analyser.
range, it must be possible to divide the entire sweep range into programmable sub ranges, and the above multisweep technique repeated within each sub range.

In the analyser, the sinewave output of the d.u.t. is fed directly to the Y input. For a proper plot a direct voltage must be
given to the Y input. It will be necessary to use a wideband average detector with a switched filter for a d.c. output. Switching of filter capacitors is done using the waveforms for switching the v.c.o. capacitors. Other techniques for improving the display can be found in reference 2.

## References

1 Intersil application note ICL 8038.
2 Logarithmic audio sweep generator, by A. C. Ainslie. Wireless World Sept. 1979.

## Parallel-fed voltage multiplier



Fig. 3. A simple low power square wave source, using a CMOS hex Schmitt inverter (40106B or 74C14).
sources. For fixed R the output resistance falls with decreasing T or increasing C until $T \ll N C R$, when a limiting minimum value $2 \mathrm{~N}^{2} \mathrm{R}$ is reached. The actual value of capacitance used is largely immaterial, as a compensatory change in $T$ can always be made.
In low power operation c-mos gates have sufficiently low output resistance (a few hundred ohms) to act as drivers, espe-
cially if two or more gates are parallelled, Fig. 3. More effective buffering is needed at power levels greater than about 10 mW . A 15 -stage multiplier driven by this circuit with $\mathrm{T}=50 \mu \mathrm{~s}$ and $\mathrm{C}=10 \mathrm{nF}$ provided an open-circuit voltage of 137 V with a battery drain of 0.27 mA . The measured output resistance was $130 \mathrm{k} \Omega$. With $30 \mu \mathrm{~A}$ drawn from the output, total battery drain was 0.72 mA . Overall conversion efficiency (load power/battery power) is $60 \%$, a very satisfactory result in view of the low power level. If miniature polyester layer capacitors are used in the multiplier chain the entire circuit occupies little more volume than the 9V PP3 battery supplying it.

## Appendix

When the resistance $R$ of the square-wave sources is not negligible, the waveform at X or Y with the multiplier output short-circuited takes the shape indicated in Fig. 4, in which the amplitude of the swing $\mathrm{V}_{2}-\mathrm{V}_{1}$ is less than its maximum value $V_{d d}$, owing to incomplete charging and discharging of the capacitors in


Fig. 4. The waveform seen at point $X$ or $Y$ of Fig 2 when $R$ is not negligible.
each half cycle. The charge transferred from stage to stage in one cycle is $C\left(V_{2}-V_{1}\right)$ and the average short-circuit current is therefore $C\left(V_{2}-V_{1}\right) / T$. By inspection of Fig. 4:

$$
\begin{aligned}
& V_{1}=V_{2} e^{-1 / N R C} \\
& V_{1}=V^{2}
\end{aligned}
$$

$$
V_{2}=V_{d d}=V_{1}
$$

Hence $\mathrm{V}_{2}-\mathrm{V}_{1}=\mathrm{V}_{\mathrm{dd}}\left(1-\mathrm{e}^{-\mathrm{T} / \mathrm{NRC}}\right) /\left(\mathrm{i}+\mathrm{e}^{-\mathrm{T} / \mathrm{NRC}}\right)$

$$
=\mathrm{V}_{\mathrm{dd}} \tanh (\mathrm{~T} / 2 \mathrm{NRC})
$$

With ideal diodes the open-circuit output voltage is $N V_{d d}$ and so the output resistance is given by
$N V_{d d} T / C\left(V_{2}-V_{1}\right)=(N T / C) \operatorname{coth}(T / 2 N R C)$.

# Digital filter design procedure - 3 

Despite its limitations a high-pass digital filter is easily designed by 'inverting' its equivalent low-pass version (July issue). Except for sign changes, pole and zero parameters are the same.

Previous articles with this title were in the May and July 1983 issues, the first outlining how to design the digital equivalent of an analogue filter where the transfer function can be simply formulated. As an example, the article derived in detail the digital equivalent of a parallel tuned circuit, and one case had pole positions chosen with a simple microprocessor in mind. The second article covered the case where the $z$ plane transfer function had to be derived from an analogue filter using a bilinear transformation, and a fourthorder low-pass Butterworth filter was used as an example.

One can argue that even in the analogue world a high-pass filter cannot really exist as it is not possible for a circuit to pass signals of an infinite frequency. The Butterworth low-pass filter has a flat response from zero up to its cut-off, but the flat response of the equivalent highpass filter cannot possibly extend from

(b)

Fig. 1. Spectra of ideal analogue and digital low-pass filters compare as at top diagram (a), while ideal analogue and digital highpass filters compare at bottom (b).
Frequency $f_{\text {max }}$ is the digital equivalent to an infinite analogue frequency.

## by J. T. R. <br> Sylvester-Bradley M.A.

cut-off to infinity. However, as explained in the previous article, with the digital version of the Butterworth low-pass filter, the digital equivalent to an infinite frequency is the maximum frequency that the digital filter can handle, that is half the sampling frequency.

The same applies to the high-pass digital filter, and within this limitation it can have a flat response from its cut-off frequency up to the digital equivalent of an infinite frequency ( $f_{\text {max }}$ ), see Fig. 1, where the spectra (or more precisely, the Fourier transforms of the impulse responses) of both low-pass and highpass ideal analogue filters are compared with their digital equivalents. In the last mentioned the spectra are repeated at multiples (harmonics) of the sampling frequency.

Once the limitations of the high-pass filter are recognized, a filter which is the precise equivalent to its low-pass version is easily designed by inverting the position of the low-pass poles and zeros on the Z plane.

Figure 2 shows the spectrum and Zplane diagram of the high-pass filter designed in this way to be an exact
equivalent of the low-pass filter designed in the previous article (Fig. 10 of that article).

## Pole and zero positions

The pole positions for the low-pass filter were

$$
\begin{array}{ll}
\text { pole 1 } & \mathrm{r}_{1} / \omega_{1} \mathrm{~T}=0.758 \angle 137.2^{\circ} \\
\text { pole } 2 & \mathrm{r}_{2} / \omega_{2} \mathrm{~T}=0.458 \angle 159.1^{\circ},
\end{array}
$$

with poles $3 \& 4$ as their conjugates. The four zeros were all located at $1.0 \angle 180^{\circ}$.

The pole and zero positions for the high-pass filter are found by adding $180^{\circ}$ to the above positions, giving

$$
\begin{array}{ll}
\text { pole 1 } & \mathrm{r}_{1} / \omega_{1} \mathrm{~T}=0.758<42.8^{\circ} \\
\text { pole } 2 & \mathrm{r}_{2} / \omega_{2} \mathrm{~T}=0.458<20.9^{\circ},
\end{array}
$$



Fig. 2. Spectrum and Z-plane diagram and $|H(j \omega)|$ of digital equivalent of high-pass Butterworth filter.
with poles $3 \& 4$ as their conjugates, and with the four zeros located at $1.0 \angle 0^{\circ}$.
The spectrum of Fig. 2 shows a flat response from just above the cut-off frequency $\left(f_{c}\right)$ up to $f_{\text {max }}$ and

$$
\mathrm{f}_{\mathrm{c}}=1 / 8 \mathrm{f}_{\mathrm{s}}=1 / 4 \mathrm{f}_{\max } .
$$

## Transfer function

For the high-pass filter $\mathrm{H}(\mathrm{z})=$
$\frac{(z-1)^{4}}{\left(z-r_{1} e^{j \omega}{ }^{T}\right)\left(z-r_{1} e^{-j \omega_{1}}{ }^{T}\right)\left(z-r_{2} e^{j \omega_{2}^{T}}\right)\left(z-r_{2} e^{-i \omega_{2} T}\right)}$
multiply the denominator to evaluate the pole parameters:
$\left(\mathrm{z}^{2}-2 \mathrm{zr}_{1} \cos \omega_{1} \mathrm{~T}+\mathrm{r}_{1}^{2}\right)\left(\mathrm{z}^{2}-2 \mathrm{zr}_{2} \cos \omega_{2} \mathrm{~T}+\mathrm{r}_{2}^{2}\right)$ $=z^{4}-2 z^{3} r_{1} \cos \omega_{1} T+z^{2} r_{1}^{2}-2 z^{3} r_{2} \cos \omega_{2} T+$
$4 z^{2} \mathrm{r}_{1} \mathrm{r}_{2} \cos \omega_{1} \mathrm{~T} \cos \omega_{2} \mathrm{~T}-2 \mathrm{zr} \mathrm{r}_{2} \cos \omega_{2} \mathrm{~T}+$ $\mathrm{z}^{2} \mathrm{r}_{2}^{2}-2 \mathrm{zr} \mathrm{r}_{1} \mathrm{r}_{2}^{2} \cos \omega_{1} \mathrm{~T}+\mathrm{r}_{1}^{2} \mathrm{r}^{2}$.


Collect like terms:

| $z^{4}$ | $z^{3}$ | $z^{2}$ | $z^{1}$ | $z^{0}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | $-2 \mathrm{r}_{1} \cos \omega_{1} \mathrm{~T}$ | $\mathrm{r}_{1}^{2}$ |  |  |
|  | $-2 \mathrm{r}_{2} \cos \omega_{2} \mathrm{~T}$ | $4 \mathrm{r}_{1} \mathrm{r}_{2} \cos \omega_{1} \mathrm{~T} \cos \omega_{2} \mathrm{~T}$ |  |  |
|  |  | $\mathrm{r}_{2}^{2}$ | $-2 \mathrm{r}_{2}^{2} \mathrm{r}_{2} \cos \omega_{2} \mathrm{~T}$ |  |
|  |  |  | $-2 \mathrm{r}_{1} \mathrm{r}_{2} \cos \omega_{1} \mathrm{~T}$ | $\mathrm{r}_{1}^{2} \mathrm{r}_{2}^{2}$ |

From the pole positions,
$\mathrm{r}_{1}=0.758$
$\omega_{1} \mathrm{~T}=42.8^{\circ} \quad \cos \omega_{1} \mathrm{~T}=0.7337$
$\mathrm{r}_{2}=0.458$
$\omega_{2} \mathrm{~T}=20.9^{\circ} \quad \cos \omega_{2} \mathrm{~T}=0.9342$.
Therefore the pole parameters are

| $z^{4}$ | $z^{3}$ | $z^{2}$ | $z$ | $z^{0}$ |
| :---: | :---: | :---: | :---: | :---: |
| $a_{0}$ | $a_{1}$ | $a_{2}$ | $a_{3}$ | $a_{4}$ |
| 1 | -1.1123 | 0.5746 |  |  |
|  | -0.8557 | 0.9518 | -0.4917 |  |
|  |  | 0.2098 | -0.2333 | 0.1205 |
| $\Sigma 1$ | -1.968 | 1.7362 | -0.725 | 0.1205 |

The pole parameters, $a_{n}(n=0$ to 4$)$ for the high-pass filter above are the same, except for sign changes, as for the lowpass filter designed in the previous article. Some paperwork would therefore be avoidable if the high-pass filter is designed as the inverse of low-pass filter already designed.
The transfer function can now be written to include the pole parameters, and assuming unity gain, $\mathrm{H}(\mathrm{z})=$

$$
\begin{align*}
& \frac{(z-1)^{4}}{z^{4}-1.968 z^{3}+1.736 z^{2}-0.725 z+0.1205} \\
&=\frac{Y(z)}{X(z)}
\end{align*}
$$

In the numerator the zero parameters $b_{0}$ to $b_{4}$ can be found by expanding $(z-1)^{4}$ (or from Pascal's triangle):

$$
(z-1)^{4}=z^{4}-4 z^{3}+6 z^{2}-4 z+1 .
$$

Values for $b_{n}$ are the same as for the lowpass filter, except for sign changes in $b_{1}$




Fig. 6. After the switching transient, pulses are transmitted but with no d.c. component. input is at $f_{\text {max }}$.


Fig. 7. In spite of being a "high-pass" filter, it cannot pass frequencies above $f_{\text {max }}$. Here the input is zero (after switching transient) with an input at the sampling frequency.

Fig. 8. Pulse train within the passband of the filter passed without distortion but with no d.c. component.

and $b_{3}$. Cross multiplying in the equation for $\mathrm{H}(\mathrm{z})$ and dividing by $\mathrm{z}^{4}$ gives the expression for $\mathrm{Y}(\mathrm{z})$ :

$$
\begin{aligned}
Y(z)= & 1.968 Y(z) z^{-1}-1.734 Y(z) z^{-2}+ \\
& 0.725 Y(z) z^{-3}+0.1205 Y(z) z^{-4}+ \\
& X(z)-4 X(z) z^{-1}+ \\
& 6 X(z) z^{-2}-4 X(z) z^{-3}+z^{-4}
\end{aligned}
$$

The recurrence formula is therefore

$$
\begin{aligned}
y(n)= & 1.968 y(n-1)-1.734 y(n-2)+ \\
& 0.725 y(n-3)-0.1205 y(n-4)+ \\
& x(n)-4 x(n-1)+6 x(n-2)- \\
& 4 x(n-3)+x(n-4)
\end{aligned}
$$

which can be written directly into a computer program to realize the filter. The realization diagram and impulse response are shown in Figs 3 and 4.

The output with a long rectangular input pulse, as in Fig. 5, clearly shows the differentiating effect of the filter, together with some ringing at the cut-off frequency.

With an input at $f_{\max }$, (in Fig. 6 the on/off pulses are at half the sampling frequency) the output soon settles down to passing the pulses, but with their d.c. component removed. The output settles down after the ringing effect of the switching transient is over.

The filter is unable to pass a frequency equal to $f_{s}$, Fig. 7.

With a series of rectangular pulses three samples long their frequencies are well within the pass-band of the filter, and at Fig. 8 the pulse train is passed without much distortion (after the switching transient) but with the d.c. component removed.

In the fuly 1983 article, a slip occured on page 43, in which $X(z)$ was inadvertently repeated in the penultimate line.

If you read that article you will no doubt have spotted that the last two lines of text in column one on page 44 should have followed the recurrence formula. - dep. ed.

## Who was Fessenden?

When J. D. Parker received the Fessenden Award from the National Marine Electronic Association, he had to confess that he did not know of Fessenden. So the NMEA provided him with an article from the January 1930 issue of Radio-Craft. Reginald A. Fessenden, it turned out, worked with Edison as an electrical engineer and as chief chemist. He later became professor of electrical engineering at Western University, Pittsburg and as early as 1895 began experimental work with radio waves. Through his knowledge of sound waves he conceived the idea of modulating a continuously oscillating radio wave and his was the first voice ever to be heard on radio. He invented the rectifying electrolytic detector, the successor to the coherer, and his other inventions included the r.f. alternator and the rotary spark-gap. He suggested the principle of heterodyning but was unable to go further until the development of suitable ocillator valves. He also spent a considerable time working on navigation and signalling at sea.

## DSP, the next big step

Digital signal processing does the same things that are familiar to computer users. It executes algorithms. However in most computer applications relatively small batches of data are processed and they often do not require immediate processing. Many are familiar with the 'printout will be available next Tuesday' system. D.s.p. offers the ability to process great volumes of data with no observable delay, in 'real time'

The technique is not particularly new. It has been used in specialized military and aerospace programmes where ultra-fast real-time computation is said to be needed, and used very expensive array processors. What is new is the production of integrated circuits that make it feasible to perform tasks previously too expensive for general use or only possible on analogue equipment

An example of the use of d.s.p. is spectrum analysis of the vibrations in an engine on test. A. d.s.p. spectrum analyser receives signals from transducers attached to the engine. It converts the analogue signals to digital signals, processed through filters to analyse the frequency content of the vibrations and provide an instant printout or display on the current state-of-health of the engine. Such equipment might now be the size of a personal computer but the new integrated circuits will reduce this to a handful of chips. A car, for example, might be fitted with a self-diagnosed module and a collision-avoidance system. Similarly small packages could be used for speech analysis, speech synthesis or for helping to compensate for hearing, speech or sight impairments.

All d.s.p. algorithms have similar structures. They typically require the multiplication and totalling of strings of numbers. This structure is similar to the totalling of a bill where data (e.g. quantities) and coefficients (e.g. prices) are multiplied together to give subtotals which are, in turn, all added to give a grand total.

Such multiplication of data and coefficients is known as array processing. Typical algorithms are digital filtering, which may be used for improving the sig-nal-to-noise ratio; spectral analysis, which uses fast Fourier transforms to determine the frequency content of a signal; correlation, to compare signals; estimation, to decide on the validity of a signal that is incomplete or obscured by noise; and control.

A typical d.s.p. multiplier can complete a multiplication in 150 ns , about 1000 times faster than a standard microprocessor. Multipliers are typical building blocks for d.s.p. hardware, others are arithmetic logic units and sequencers.

Belying their name, Analog Devices have launched a 16 by 16 -bit multiplier accumulator (mac), the ADSP-1110. This c.mos device provides a 40 -bit internal accumulator and yet fits onto a standard 28 -pin cual in-line package. This is because it uses only a single port but operating from a 10 MHz clock, the mac can alternately load x and y operands and, when instructed, output the result.

The mac can be used as a low-cost computational accelerator in graphics systems where matrix multiplications are used in image manipulation to translate, rotate or zoom the image. Under control of the system's processor, the mac can multiply a four-by-four matrix and a four-by-one vector, requiring 16 operations in less than $4 \mu \mathrm{~s}$. It operates on six-bit instruction words, there are two control lines and an overflow flag. In the event of an overflow there is an eight-bit accumulator overflow register. The ceramic version of the ADSP-1110 is available in sample quantities. It can operate over the temperature range -55 to $125^{\circ} \mathrm{C}$. A plastics-housed version with a more modest temperature range, 0 to $75^{\circ} \mathrm{C}$ will be available soon. Prices are thought to be about $£ 75$ each if bought in quantities over 100. Analog Devices Ltd, East Molesey, Surrey KT8 OSN.

## Electronic potato

If you have noticed that the potatoes you buy are less battered than before, this may be due to research carried out by the Scottish Institute for Agricultural Engineering (SIAE). They developed an electronic potato made out of plastic foam enclosing an Entran accelerometer, a transmitter and small rechargeable batteries. The transmitter sends out a v.h.f. radio signal, modulated when the transducer is activated. This potato is handled during harvesting and pototo grading along with a batch of real potatoes and the stages when the is at
most risk from damage can be monitored. A battery operated receiver and tape recorder are used to record the signals transmitted from the potato and 'voiceover' commentary may be recorded at the same time to identify the stages actually taking place. Machine adjustments, modifications or alterations to the operating speed can all be assessed with the electronic spud. Moreover it can also disguise itself as an apple or an onion which are also subject to mechanical handling. A similar technique has been used to monitor raspberry harvesting with electronic raspberries.

## Do you remember Baird tv?

If you do, the Royal Television Society would like to get in touch with you. They are planning an event to mark the 50 years that have passed since the 30 -line service was terminated. They would like to identify as many of those 'pioneer viewers' as possible. The honorary secretary of the midland centre of the RTS is John Grantham, at BBC Network Production Centre, Pebble Mill Road, Birmingham, B5 7QQ.

## Briton honoured

The tenth Marconi International Fellowship has been awarded to Professor Eric Ash. Dr Ash, Professor of Electronics at University College, London, has been made "in recognition of his outstanding leadership and pioneering work in the emerging technologies of acoustic surface wave device, optical fibre-based communications, acoustic optics and acoustic imaging".
Marconi International Fellowships were founded by Guglielmo Marconi's family and are awarded each year to further research by "a leading world scientist who has made a distinguished contribution to those areas of science and technology that improve the quality of life". Readers may recall that in 1982 the fellowship was awarded to Dr Arthur C. Clarke for first specifying the potentialities and technical requirements for the use of synchronous orbiting satellites for global communications.

## High-Com stereo radio

A three month public trial of compressed f.m. broadcasts is under way in Federal Germany. The system had to offer no reduction in quality to the listener without an expander in the receiver and yet when an expander fitted there should be a noticeable difference. Not surprisingly, ARD chose a home-grown product -AEG-Telefunken's High-Com compander system. The system had to be modified to fit the requirements (see German radio show report, November 1983, page 75). After modification only two out of 13 'guinea pigs' could tell any difference between the compressed and uncompressed signal and then only in direct comparisons. Moreover, tests in cars showed that there was an audible improvement in v.h.f. reception of the compressed but unexpanded signals. It is thought that this was because the compressed signal increased the volume of quieter passages which were then more easily heard above the noise background.

## Interface to be made in bulk

Swamped by the orders for the IEEE488 Procyon interface for the Acorn/BBC microcomputer, Cambridge Systems Technology have been forced to award an assembly contract for the unit to an outside manufacturer. The contract has gone to CVO Electronics of Stevenage.
The device has found a considerable number of customers in professional, scientific and educational users. A high proportion of scientific test instruments use 488 interfacing especially from such manufacturers as Hewlett Packard, CBM, Philips, and Tektronix, and therefore can be monitored or controlled through a BBC computer fitted with the Procyon unit.

## TAT-8 will be optical

International agreement between 28 telecommunications authorities has given the go-ahead for TAT-8, which will use hairthin glass fibres. Two pairs of fibres will be incorporated in the cable. Each pair will operate digitally at $280 \mathrm{Mbit} / \mathrm{s}$ to give a total capacity of 8000 telephone circuits. This basic capacity can be increased by digital circuit multiplying equipment up to 40000 , although initially only a small proportion of this potential capacity will be used. Monomode transmission will give the cable this high capacity and allow a long spacing, 30 to 55 km , between light regenerators, the equivalent of repeaters on wire cables which are needed every 5 km .
The American end of the cable will start at Tuckerton, New Jersey and the main part, 5800 km will be provided by AT\&T Communications. Near the European continental shelf, a junction box will allow the cable to be split two ways. 520 km of cable will be laid by STC to join the junction box to Widemouth Bay, Cornwall, while another 310 km will branch off to Penmarche on the Brittany coast of France. The French branch will be the responsibility of a French company, Submarcom.
Cables and satellites share about half each the total capacity of telecommunications across the ocean. At present, including TAT-7, the cable capacity is about 11200 telephone circuits. TAT-8, expected to come into operation in 1988, will more than double this.

## Home energy monitor

On page 36 of this issue is a project to build a differential temperature integrator to monitor temperature differences in a house. Designed by Bob Everett, a research fellow at the Open University, and engineered by the OU Electronics Com-


Amongst the facilities at the Daresbury Laboratory of the Science and Engineering Research Council are the world's largest tandem Van der Graaff accelerator and the world's first high energy electron accelerator dedicated to the production and use of synchroton radiation. In experiments to study the details of atomic nuclei, ions are accelerated to energy levels up to 20 MeV . Synchrotron radiation is emitted when electron have been accelerated to a peak level of 2 GeV and then deflected by the fields of storage ring magnets. It is used in atomic and molecular spectroscopy, $X$-ray spectroscopy and surface science. Microprocessor monitoring and alarm systems are provided by Sattcontrol of Aldershot.
mon Facility, 100 of them were made and installed in houses in Milton Keynes in the summer of 1981 as part of a series of energy conservation field trials. The Building Research Establishment put the device on its list of equipment suitable for such monitoring.

The device has proved to be useful and reliable and the OU has had a continuous stream of letters from architects and research students who would like to borrow one or have the circuit. But the potential for making them commercially is small: "The design will surely be superseded within a year or so by a suitable c.mos processor," says Bob Everett. The current cost of the components for the integrator excluding the p.c.b. and the box is a little over $£ 100$, whereas current competitive commercial systems is mainly restricted to microprocessor systems for ten or single channel ram-based devices at $£ 400$. "Although the world is full of well-intentioned people who would like to monitor the energy performance of their houses," says Everett, "there are few who are prepared to fork out that much money or harness the $\mathrm{i} / \mathrm{o}$ port of their home computers to temperature monitoring for six months solid.
"It would be nice if it were possible to get the integrator as a kit," he commented, "the Open University would have no problems in selling the two double-sided circuit boards required, and the whole thing
would have the blessing of the Department of Energy, though it could be of more interest to countries such as Denmark and France where energy conservation research is not quite as unfashionable as it is here."

## In brief

Giotto, the space probe which is to intercept Halley's Comet in 1986, has undergone a comprehensive check-out on its electrical and electromagnetic characteristics. The tests, on this European Space Agency project, have been carried out by British Aerospace Dynamics group, Bristol. The circular test chamber is 14 m in diameter and 12 m high, where the vehicle has been subjected to r.f. tests from 0.1 Hz to 18 GHz .

The formation of a new computer company and a new computer has been announced. The first product of Compass Computers, of Tetbury, Gloucestershire, will be the Compass 32 . This is a multiuser computer which will run CP/M, MSDos, or Unix under the DEC operating systems. Each user will have a Z80 or an 8088 processor and 64 KBytes of ram. Winchester disc memory will be available. The company is also planning a variety of add-on devices for the DEC range of computers which will include communications boards, mass storage systems, etc.

Under the heading "Moral persuasion" (Com munications Commentary, August issue) the claim is made that China has ceased to operate broadcast stations in the 7000 to 7100 kHz ama teur band. Whilst it may well be true that Chinese broadcast stations in this band are not heard in Europe, it is completely incorrect to say that these stations have quit the so-called amateur-exclusive band at $7000-7100 \mathrm{kHz}$.
As coordinator of the New Zealand Intruder Watch, and as coordinator for the Region 3 IARU Monitoring Service, I daily handle many complaints from amateurs regarding the use of this band by the Chinese broadcasting services - and others! My records for September and October show the following frequencies to be in current usage by the Chinese Service: 7010 , $7025,7030,7035,7040,7045,7050,7055$ and 7095 kHz .
With reference to the 7010 kHz frequency it appears that some rearrangement of schedules may have been made but the frequency is still used by China. The People's Liberation Army station on the nominal frequency of 7025 kHz , and the regular Radio Beijing station on 7055 kHz , hop around between the above noted frequencies depending on the degree of jamming they are being subjected to by the Russians.
The "hopping" from one frequency to another, without warning and often in the middle of an item, brings into question - at least in my mind - the value, if any, of this type of broadcasting.
Resolution 641 of WARC 1979 calls upon stations using this band to vacate it. To date this resolution has been ignored by China - using the "reservations" procedure of the ITU Convention, and simply ignored by Albania with its Radio Tirana on 7065, 7075 \& 7090 kHz .
Albania at least does have the excuse that it is not a signatory to the ITU Convention, not so China and the USSR, although we "down under" do wish somebody "up there" would show the Albanians how to operate their transmitters without the resultant daily high level 2nd harmonics on 20 metres.

The USSR at times re-broadcasts one of its Mayac (home service) programmes on top of Radio Beijing - grossly over modulated - as a jamming technique, and has the lower sideband of its 7100 kHz transmissions in the amateur band. To say nothing of the intense jamming, with 2 nd and 3 rd harmonics appearing on other amateur bands.
The 'footnoting" into the $7000-7050 \mathrm{kHz}$ portion of this band by the fixed services of 13 countries plus its unauthorized use by the Russian fixed service, and the broadcast service as noted above, brings into mockery the whole concept of an "exclusive" band for the amateur service.
A recent random check of this band by the WIA Intruder Watch, and later confirmed by the NZART Intruder Watch, showed that between the hours of 1900 to 1925 u.t.c. on the 13th July 1983 there were 11 broadcast stations present in this band plus seven jammers, and that the activities of these stations accounted for $70.7 \%$ of the available 100 kHz . At this date' (28-11-83) the situation has not changed appreciably!
We can only hope that the 1984 WARC for
h.f. broadcasters will go some way to alleviate the current situation on this band.
R. E. Knowles, ZL1BAD/ZL61W

Coordinator NZART Intruder Watch
Tuakau
New Zealand

## RADIO SOFTWARE

With regard to your picture coverage of our Computer Programme, Datarama, and the subsequent reponse from our colleagues at BBC Radio Leeds claiming that they were the true pioneers of Radiosoftware, I should like to make few salient points.
Firstly, we are not in the business of claiming firsts: we believe the true originators of Radiosoftware as a broadcasting fact to be The Dutch Hobby Scoop Programme,* which began doing it in 1978
Secondly the Datarama team, unlike it would seem the BBC Leeds team and others who've followed suit, conducted its own 'experimental data transmissions' under controlled conditions and out of broadcasting hours, i.e. not during programme time. When the first series of Datarama went on air in March 1983 Radiosoftware, at least in our hands had passed beyond the stage of experiment and was a properly researched piece of broadcast material. Within the current series, Radiosoftware forms as natural a part of the programme, as does conversation. There is no more experimentation necessary. It is time to get on with it.
Thirdly, in conjunction with the IBA, we have produced outline specifications which we hope will form the basis of future technical specifications for any station wishing to broadcast Radiosoftware. These should be available from local IBA officers in all regions

Datarama is broadcast weekly on Radio West (in the Avon area), and on Wiltshire Radio (Swindon/W. Wilts) and very shortly on CBC Radio (Cardiff). Since its inception, each programme has included Radiosoftware for at least one microcomputer.
On the RW transmission, Datarama is supplemented by longer programmes for more micros transmitted after the stations closedown. These 'Nightfile' tapes are repeated at $1 / 4$ hour intervals throughout the night, a technique copied by Barry Norman's excellent 'Chip shop take-away service,' except that ours are free, and theirs require you to spend $£ 3.95$ on a translator kit, which is still not available at the time of writing!
Tim Lyons
Chief Engineer
Radio West
Bristol
*See also News, November, 1982.


## ENERGY SAVING

I read Mr MacHarg's article and the subsequent correspondence with interest. Several of my colleagues have an interest in optimizing heating systems, and many lunch-time conversations have taken place, during which useful exchanges of ideas occur. Many different ideas are aired; individuals rate different aspects of a system with varied importance. To my mind it is necessary to get back to basics if we are to make decisions which enable us to optimize a system.
The object of a heating system is to burn fuel, thereby warming the house. A stable situation exists when heat input equals heat loss. Therefore the better insulated the property, the less energy we have to put in. This may seem very obvious, but is the first step.
Assuming, for the moment, that boiler efficiency is not affected by flame height, then in theory we could adjust the flame height to provide water at a constant temperature, so that the heat lost by the radiators was equal to the heat lost by the house to the outside world

The usual type of system does not work this way; we rely on a variable burner duty cycle followed by the integrating effect of large ther mal masses to iron out the discontinuity. Having said this we next need to define the areas of waste. There is the basic loss of heat from the building, and there is heat loss up the boiler flue. If the boiler was $100 \%$ efficient, all the heat would go into the house. Because of the effects of integration, the temperature will rise before a control thermostat operates, but continue to do so afterwards. It is recognised that the thermal inertia is normally too great to allow a simple thermostat to be used, which is why the "accelerator" heating resistor is fitted into the majority of room thermostats.

Taken in isolation, this arrangement, if operating in a constant temperature, is a duty cycle control device. Fly allowing a passage of air through this device the duty cycle is modified by ambient temperature as well as by manipula tion of the control. Provided that the rate of heating by the accelerator resistor can be adjusted to suit the thermal inertia of the system, a simple means of optimization is available. Unfortunately, most proprietary items do not have such a facility, so a basically sound principle is nearly always subject to maladjustment in a particular installation.

I believe that it is undesirable to have a boiler cycle continuously, particularly when only the pump is controlled by a thermostat. Unfortuna tely Mr Ball, whose system employs a room thermostat to control both pump and boiler simultaneously, seems to have received short shrift from Mr MacHarg in the correspondence column. This is probably because Mr Ball has not gone into as much analysis of his simple system as is desirable. I have used a similar, but not identical, system for several years. The system operates successfully because not only does it avoid excessive cycling of the boiler, but also keeps the boiler temperature as low as possible consistent with providing adequate heat, as advocated by Mr Hargis. The less required, the shorter the duty cycle becomes (controlled by the thermostat with accelerator resistor) and consequently, the lower is the maximum water temperature attained throughout the cycle Therefore the heating effect on the surrounding air is a function of both time and rising water temperature - a point which did not emerge in Mr Ball's letter.


The colder the weather, the greater the heat loss from the house, the longer will be the thermostat (and therefore, boiler) on duty cycle and the hotter the radiators become. To my mind, this is exactly what a sensible system should do. It is only under the most adverse conditions that I have known the boiler thermostat (set to $77^{\circ} \mathrm{C}$ ) to operate. The system works well because I have taken care to "tune" the accelerator resistor as mentioned earlier, using a modified commercial thermostat, placed in a carefully chosen position.
Economies can be made by modifying simple systems as described. First, I have delayed the pump start and stop relative to the controlled boiler cycle. The boiler has a cast-iron heat exchanger, and a pump delay of about 82 seconds enables the boiler temperature to rise quickly, but without overshoot, after ignition and also enables a substantial amount of heat to be extracted from the iron after the flame is extinguished

Another economy is made by designing the domestic hot water heating facility to latch up, so it is not defeated by the clock. This enables the water heating cycle to be completed before the boiler is turned off. The facility is particularly helpful in summer, when it prevents the need for re-ignition of the boiler at the start of the following day.

I should also point out that I heat the whole house consistently; radiator valves have been adjusted and are never normally touched Furthermore I use no supplementary heating; this would upset the balance of the system. If supplementary heating is to be used, the subject of control becomes more complex and thermostatic radiator valves are likely to be needed This would result in changes of heat output in other areas if the duty-cycle system I have described is used.

Finally, I believe long electrical time constants to be a potential problem because of the large values of resistance and capacitance needed. The diagram shows the bare bones of the 82 second delay referred to earlier. $\mathrm{A} \div 2^{12}$ counter counts 50 Hz mains pulses, but is nor mally held in the reset condition. The "go" control signal (which has also fired the boiler) causes the output from the interface and Schmitt to go high. A high or low excursion on this line results in a pulse emerging from 4030A, which sets the latch. Output goes high, maintaining a low at the output of B. Output $Q$ goes low and removes the reset from the counter,
which then counts $2^{12}=4096$ pulses at 50 per second; this takes 81.92 seconds. The output from Q12? goes high and resets the latch; B now has only one high on its inputs - its output goes high and the pump starts. Conversely, when the control input goes low, the counter is started again which sets $Q$ high. As the other input to 4030 B is now low, the pump keeps running until the circuit times out.
Keith Cummins
Southampton
Hampshire

## LOGIC NOISE MARGINS

It is standard practice to talk of noise margins in terms of noise voltage. The meaning of this is, to say the least, vague, although it has its uses. For instance t.t.1. is quoted as having a noise margin of 0.9 volts, so it is obviously asking for trouble to use discrete diodes to expand the fan in, a reasonably common malpractice, because it reduces the margin to 0.2 volts.

The c-mos 4000 series is quoted as having a noise margin of $45 \%$ of the supply voltage clearly superior as compared with t.t.l. - but this is only half the story. When signal lines are short as is desirable and likely within a piece of equipment, they take their impedence from the driving output according to the slogan "Low Z rules, OK?"


Short lines driven by t.t.l. are at an impedance of about 100 and the noise power necessary to overcome the noise voltage margin is $\mathrm{V}^{2} / \mathrm{R}=0.9^{2} / 100$ or about 8 mW . The output resistance of 4000 series c -mos is $1.5 \mathrm{k} \Omega$ to $2 \mathrm{k} \Omega$, so with a supply voltage of 5 V the power needed to raise (or lower) the potential on the line by $45 \%$ is $2.25^{2} / 2000 \approx 2.5 \mathrm{~mW}$. The noise power margin of t.t.l. is over three times as great at this supply voltage, see diagram.
It is worth noting that 54 HC and 74 HC logic has a much lower output resistance and a noise voltage margain of about 1.5 volts. Taking output resistance as $100 \Omega$ - it is in that parish though I have not seen it quoted - this requires a noise power of $1.5^{2} / 100=22.5 \mathrm{~mW}$ to overcome the noise voltage margin.
Using the same noise power concept, 4000 series c-mos requires a supply voltage of 9 volts to match the t.t.l. margain of 8 mW , and only at a supply voltage of 15 V does it achieve a noise power margin of 23 mW , the equal in this respect of 74 HCXX .

So far I have been considering short lines which take their impedance from the driving output. Long lines are a different matter. Correct termination is vital to establish the designed (low) impedance of the line and therefore confirm the designed noise power margin of the receiver device. It also performs its well known task of minimising reflection and radiation, two most potent causes of noise and crosstalk. Once again we are specifying and maximizing the noise power margin.

Our evalution is not yet quite complete. An additional factor to be taken into account is the frequency response of the logic. 4000 c -mos just does not have time to propagate a noise spike of width 10 ns , so its tardiness has considerable advantage if the system can be run at a frequency suitable to this logic family. The noise is effectively band limited and this is where 4000 c -mos really scores in noise immunity. The old 4049 buffer was particularly good in this respect, having a frequency limit of about 180 kHz . Updated versions have a propagation delay of 60 ns. Modern fast logic has a much greater bandwidth and is therefore vulnerable also to high frequency noise. So we are concerned with a balance of two factors; the noise power margin and the noise power bandwidth, both here defined by the characteristics of the logic. It is desirable to arrive at a figure of merit for noise immunity, taking both factors into account and expressed in terms which are, ideally, self-explanatory. I would welcome comments on the subject.
Tim Hartigan
Ballsbridge
Dublin

## FORTH PROCESSORS

In his article and letter in November Wireless World Mr Woodroffe is less scrupulous than the Intel benchmark report that he obliquely criticises. This report, which compares the 68 B 09 with the 8088 , can only really be faulted on the grounds that no allowance is made for code frequency in averaging out relative execution times and code sizes. It indicates, quite correctly, that re-entrancy is handled faster by the 6809 .

By contrast, the table presented in his article by Mr Woodroffe can be faulted on several grounds. First, it omits the Texas 9995 processor, which competes in the same market sector as the 6809 ( 64 k address, nonsegmented). I wonder why? The 9995 has a non-multiplexed bus and fast 16 -bit parallel onboard ram; for 450 ns access time its bus cycle is 670 ns , versus

800 for the 8088 and 1000 for the 6809. It also makes use of prefetch.

Second, and more serious, some funny arithmetic occurs before the bottom line. The relative speeds for the 6809 and the 8088 are given as 4.11 and 3.19 respectively although the 8088 actually executes its code faster. This is derived from this "speed for 450 nanosecond access memory." I have news for Mr Woodroffe; in the real world it is not desirable to run a processor with a bus cycle allowing 695 ns access at a speed which gives 450 ns access. It tends not to work In the real world the 8088 is faster by nearly $30 \%$. Of course it would be perfectly practical to use a faster 6809 - the 68 A or B 09 options but then he should say so. If he is not actually using these faster devices in his own computer, he should tell us what access time his hardware actually requires, and recalculate his last line on that basis.

The third objection, however, is that in reality the 8088 programmer is unlikely to use the "JMP NEXT", as this requires that NEXT be within 127 bytes, necessitating numerous NEXTs scattered throughout the code rather like Underground stations (I nearly wrote public conveniences) in London. He or she will accept the 9 -byte inline code (typical 6809 code is twice as long as typical 8088 code), losing 15 clocks and giving 8.6 microseconds. This execution time is slightly less than for the 6809 running at 1.5 MHz with a comparable memory access time. The point, surely, is that the 8088 is the more expensive device, and the time and effort required to use features like segmentation mean that they are likely to be wasted in a small domestic microcomputer. There is no point in buying unused silicon.

The comments about code usage I agree with, except as regards the very arbitrary $80 / 20$ ratio, seen quoted elsewhere as $75 / 25,1 / 3 / 2 / 3$ - it is true that in most high level languages most of the time is spent pushing garbage to keep the system happy. This is why high level languages waste silicon and time while keeping programmers employed. However, the picture can change dramatically as soon as real arithmetic starts to happen, especially when trigonometry is involved. The makers of home computers assume, generally correctly, that most users will never stretch the resources of the mathematics I would have thought, however, that electronic engineers differed in this respect; in the days when I was limited to a programmable calculator I remember calculations that exercised the poor little thing for hours on end, leading me to wish a bleeper had been fitted to announce the result. For this reason I would have thought that, again, the TMS9995 would have been a strong contender for a CPU because of its ability to handle 16 bit signed and unsigned multiplication and division in the instruction set

Perhaps I should add that I am in no way connected with any semiconductor manufacturer.
Martin D. Bacon
Taunton
Somerse

## WORLD TIMING

I am pleased that Dr J. D. H. Pilkington, head of the time department at Royal Greenwich Observatory, provided better background to the subject of "World Timing" than we were authorized to in our article on the subject; WW October 1983

In our laboratory we make use of the special transmissions which disseminate UTC and CAT (co-ordinated atomic time) for calibrating and monitoring frequency sources and transmis-
sions. Therefore, one of the purposes of our article was to draw attention to the less tightly co-ordinated h.f. broadcast (and m.f.) frequencies by broadcasters since as we said, "errors of frequency can in fact be more of a nuisance than an error of time"

Indeed, in an European Broadcasting Union Report (SBP66) entitled "A study of technical questions of interest to the WARC 1979", it was pointed out (paragraph 1.4) that the then frequency tolerance of l.f./m.f. and h.f. transmitters was unnecessarily generous, and that the stability of all carriers should be within 1 Hz of the nominal assigned frequency by 31 December, 1984. It would appear from Dr Pilkington's letter that some broadcast authorities could have a busy year.
R. C. V. Macario

Department of Electrical and Electronic
Engineering
University College of Swansea

## IMPLANT FOR BLADDER CONTROL

You may be interested to know that since the article on the electronic implant for bladder control was published (January issue) the device is continuing to be used to help paraplegic patients. The MRC workers who developed the implant tell me that 36 patients have now been fitted with this neurological prosthesis.
May I please correct a couple of small errors which canne into the article during your preparation for publication? First, the article should have stated that the patient's hand-held transmitter (Fig. 8) was developed by T. A. Perkins of the MRC Neurological Prostheses Unit. Secondly, reference 3 should be to Proc. $I E E$, and not $I E E E$.
Tom Ivall
Staines
Middlesex

## BEHIND THE MICRO

I've just read your articles 'Behind the micro' with interest, since I am thinking of expanding $m y$ interests in that direction.

Interesting . . . Well, yes, but I feel the writers haven't ever been in an actual shop to make enquiries!

The problem is, alas, compatibility. It's all very well to say that peripherals are available, but if I plug a device made by X into Y 's computer, will it work - or will I get a cloud of smoke?

Don't tell me to 'consult the literature'!
So far as I can see, it is deliberately written in such a way as to discourage any such experiments!

I know what I want . . . but to do it I need to join together gadgets from SIX different makers! But can I, I just don't know!
Ronald G. Young
Peacehaven
East Sussex

## DEAD WATCH TIMERS

To cope with just the sort of situation referred to by A. Roscoe under "Thunderstruck" (Letters February) we routinely include a "dead watch timer" in most of our new products. We also recommend our clients to use a power supply that outputs an advance warning of impending failure. These two hardware features when well integrated into the software enable
mains-related problems to be dramatically re duced, provided a third and equally vital facility is incorporated: an area of battery-backed ram to hold critical variables.

The basic idea of the dead watch timer is to have the software periodically trigger a, retriggerable monostable. As long as the software does this the monostable is prevented from reaching time out. If this happens a maskable interrupt is forced into the microprocessor. This causes activation of a special restart routine.

These facilities are essential when the system is required to "remember" long-term accumulating variables e.g. p-i-d controllers.
Steven Harris
Lodge Associates
Portslade
East Sussex

## INDUCTANCE MEASUREMENT

I don't know whether the subtitle 'Simple practical method, hard to find in the textbooks' is due to the author, D. R. Fownes, or to you, but while I agree with the first half of it I think I have reason to be surprised by the second. From the sales and library loans, I venture to claim that the obvious textbook in which to look for simple practical methods of measuring inductance is my 'Radio \& Electronic Laboratory Handbook', and Mr Fownes's method has been described in every edition of it from the first in 1938 (issued then by WW) to the 9th dated 1980. It was entitled 'The Three-voltages Method'.

I am obliged to Mr Fownes for deriving a simple formula for calculating the inductance. On the other hand most iron-cored inductors need to be measured with known variable amounts of d.c. flowing through them, and my measuring circuit has always shown this. Perhaps nowadays my stress on the voltmeter taking negligible current is no longer needed.
By the way, my letter in your October issue questioning the appropriateness of the term 'current dumping' having evoked no defence of it, I infer that there is no defence, and it is yet another misuse of a word in electronic terminology (e.g. 'slew rate', 'mixer' and 'attenuation distortion').
M. G. Scroggie

Bexhill
East Sussex

## THE NEW BUREAUCRACY

Engineers will be regretful, but not surprised, that only one programmer in the country failed the von Neumann loyalty test. (Wireless World Letters, August and October 1983.)

However, D. W. Scott then writes,
"He - and MAPCON - still have not realised that machine architecture need have little to do with its technological implementation."
This statement beautifully illustrates the blocking position taken by programmers, preventing advances in the art. If, for instance, we can simulate a cam in a ram, then why should we ever want to build a cam? (If we can get there by horse and carriage, then why do we need a motor car?)
Ivor Catt
St. Albans
Hertfordshire

## Apple Macintosh

The latest Apple computer is to be launched in the UK in April. Known as the Macintosh, it offers similar facilities to the Apple Lisa; it is menu driven from a display resembling a desk top where the facilities that a business executive may need can be pointed to with a cursor and selected for use by the push of a button. So notes may be scribbled on a pad, memos, expenses sheets, calculator, graph pad etc. are all available on the screen. They are selected by moving the cursor with a 'mouse', a small rolling box whose movements across the desk top are reproduced on the notional desk-top on the screen.

Macintosh uses a $16 / 32$-bit Motorola MC68000 processor and includes 64 K of rom and 128 K of ram . A 512 K version is due later in the year. The operating system is both rom and disc based and the computer includes a 3.5 in disc drive. Each disk has a capacity of up to 400 K bytes. There is a port for an optional additional disc drive, two RS232C/422 serial ports for attaching printers or for communicating through a modem. Sound facilities give polyphonic sound over more than 12 octaves and are capable of reproducing human speech through the built-in speaker. Apple is developing a point-to-point interconnection bus and the interface is already built in to Macintosh. The integral 9 in c.r.t display offers a bit-mapped 512 by 342 pixel resolution. There is a clock/calendar chip. Although not intended as a portable computer, it does have a carrying handle and at 7.7 kg it weighs less than many socalled portables.
The price of Macintosh has not yet been fixed, though in the US it is likely to be about $\$ 3,000$.
'Apple have produced two software packages for Macintosh; MacWrite word processing and MacDraw graphics. Lotus have developed a Macintosh version of 1-2-3, a spread-sheet and filing system and a number of software houses are preparing programs. Apple Computer (UK) Ltd, Eastman Way, Hemel Hempstead, Herts HP2 7HQ.

WW 303

## Oric Atmos

The Oric 1 computer at the cheap home computer end of the market was never very successful. The

makers made a mistake in providing prototypes rather than complete machines to the computer press who were very unkind to it. A cynical definition of the Oric 1 was "prototype for the Oric 2". The faults were compounded by the non-appearance of many promised additions and peripherals; a disc drive, a communications modem with a teletextdecoder, a rom cartridge with "super extended Basic as powerful as the BBC".

The principal difference between the Oric 1 and the Atmos is the new version of the rom operating system which has, according to Oric, not only ironed out the Oric bugs but also some others inherent in the Microsoft software. A number of additional commands have been added; especially to the cassette routines so that programs can now be verified after they have been saved. Arrays can now be stored and recalled without recourse to machine code.
The Basic is adequate and most of the commands that you would expect to find are there. We were surprised to note that there has been no attempt to improve on the abysmal line editing facility. In this respect many other computers also claiming to use 'extended Microsoft Basic' are much better (for example the Dragon and the Tandy Color Computer). Serial attributes, to change the colour or style of
characters on the screen, take some getting used to but have the advantage of taking up very little memory space.
Also provided is a cassette which has a graphics display program showing how good the display facilities are. Included is an animation of a flying duck which is very impressive especially as it is written in Basic. The program may be broken in to and listed to show how a particular effect is achieved. Also on the tape is a machine-code facility to overcome some of the frustrations of program loading mentioned above; it enables the user to override the error-checking routine. This overcomes the most common problems caused by errors inthe 'header' and leading portion of the tape, which have no relevance to the actual program.
The specification for the Atmos includes a 6502 A processor running at $1 \mathrm{MHz}, 48 \mathrm{~K} \mathrm{ram}, 16 \mathrm{~K} \mathrm{rom}, 57$ keys and a concealed reset button for a 'warm' reset; i.e. one that does not lose any data. The screen format offers eight foreground and the same eight background colours for a text screen of 40 columns of 28 lines and a character set very similar to teletext (and BBC Mode 7) with standard ascii characters, double height and flashing characters and up to 80 userdefineable characters. Highresolution graphics offer 240 by 200
pixels in eight colours and there are line, circle and point facilities.
Areas of the screen may be "filled" with a chosen colour. Three channels of sound over eight octaves with additional white noise and envelope control are output through a powerful internal speaker or may be output to a hi-fi system. There is an expansion port for the addition of some peripheral equipment, such as disc drives or a-to-d converters, a Centronics printer port, a modulated tv output as well as an RGB output for a colour monitor.

The Oric printer/plotter using four-coloured ball point pens has been re-styled to match the Atmos colour scheme and the longpromised 3in disc drive with 160 K bytes per side and a transfer rate of $250 \mathrm{Kbit} / \mathrm{s}$ has been announcedbut at the time of writing we have not been able to get hold of one.

Those who already have an Oric 1 need not despair or throw it in the bin. Oric are looking "very seriously" at the possibility of providing an upgrade kit to turn an Oric 1 into an Atmos. This could cost about $£ 50.160000$ Oric 1s were sold so this could be a major operation. Oric Products International Ltd, Coworth Park, London Road, Ascot, Berks SL5 7SE.
WW 304

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Electronics

# Non-storage oscilloscopes up to 100MHz 

Instruments currently available on the UK market

In the time since the last oscilloscope review appeared in Wireless World - a survey of portable types - it has become unnecessary to classify them in such a way, since the majority are now easily portable. Indeed, it is becoming increasingly difficult to classify oscilloscopes in any way at all: some of the functions of the more modern test instruments are those of an oscilloscope, but in some cases form only a small part of the instrument's repertoire. Logic analysis, spectrum analysis, waveform recording and even computing are now taken in hand by the latest, high-end equipment and the distinctions become blurred.
Not many instruments now exist of the type intended solely for displaying a trace. Very extensive measuring facilities in both axes are offered and, in the case of digital oscilloscopes, these can be made to an extremely high level of accuracy, sometimes with the result displayed on the screen.

To enable readers who may be out of touch with modern oscilloscope design and the characteristics and facilities provided, the terms used in manufacturers' data sheets need explanation. The first part of this survey is therefore devoted to a glossary of terms.

## Signal path

Bandwidth is the passband of the Y amplifier or amplifiers, measured at the -3 dB points. Normally, oscilloscope amplifiers are directly coupled, so that the amplitude response extends to zero frequency: a capacitor can usually be switched in to allow small events on a large d.c. level to appear on the screen, the bandwidth then being limited to around 10 Hz rather than zero.

In some cases, it is possible to offset the d.c. by means of a panel control to achieve the same effect without loss of low frequencies. The bandwidth of the Y amplifier is the characteristic used to indicate the kind of oscilloscope under consideration.
Rise-time is the response time of the Y amplifier to an infinitely steep step. If the amplifier's frequency/amplitude response has a smooth roll-off at high frequencies, as they all do, then the rise time in nanoseconds can be found from the bandwidth in megahertz by the expression $t_{r}=350 / \mathrm{f}$. A


10MHz Trio CS1562A (top). Tektronix 2236100 MHz oscilloscope, with digital display and multimeter function.
bandwidth of 100 MHz will give rise to an amplifier rise time of 3.5 ns . Since, however, voltage steps are not infinitely steep, the displayed rise time (taken from $10 \%$ to $90 \%$ of the excursion) will always be longer than this, and is equal to $\sqrt{t_{r a}+t_{r s}}$, where $t_{r a}$ is the amplifier rise time and $t_{r s}$ is that of the step itself.
Deflection factor is often termed $Y$ sensitivity and is the amount of vertical deflection of the spot on the screen for a given input voltage to the amplifier. It is measured in millivolts per division of the graticule or per centimetre. A common figure is $5 \mathrm{mV} / \mathrm{div}$ and may not be constant over the whole bandwidth of the amplifier: sometimes an increased sensitivity can be
obtained by sacrificing bandwidth and rise time. The sensitivity is controlled at the front panel by a switch, working in the 1 , 2,5 sequence, and often there is a twoposition auxiliary switch to increase the sensitivity by a factor of 10 . When a continuously variable gain control is fitted, the amplifier is not calibrated unless the control is at the end of its travel.
Display modes describe the way in which the input signals are presented on screen, in dual-trace oscilloscopes. A front-panel control selects for display channel 1 , channel 2 (one of which can often be inverted), ch1 and ch2 alternately, ch1 and ch2 effectively simultaneously by chopping from one to the other at high speed so that

| $\begin{aligned} & \overline{ \pm} \\ & \bar{\square} \\ & \Sigma \\ & \hline \end{aligned}$ |  |  |  |  | $\begin{aligned} & \text { ᄃ } \\ & \text { む̀ } \\ & \text { 心 } \end{aligned}$ |  | \# |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BK/Dynascan |  |  |  |  |  |  |  |  |  |
| 1590 | 100 | $5(\times 5)$ | 4 | $20(\times 10)-$ - | $8 \times 10 \mathrm{~cm}$ | 16kV |  |  | WW501 |
| 1570 | 80 | $5(\times 5)$ | 4 | $50(\times 10)-$ - | $8 \times 10 \mathrm{~cm}$ | 12 kV | 1285 | $V$-mode trigger |  |
| 1560 | 60 | 1 (CH3-0.1) | 2 | $500(\times 10)$ - - | $8 \times 10 \mathrm{~cm}$ | 16 kV | 1139 | Trig, holdoff. Auto focus. XY operation. V-mode |  |
| 1522 | 20 | 1 | ${ }_{2}^{2}$ | $\left.{ }_{200}^{100} \times 10\right)$ - | $8 \times 10 \mathrm{~cm}$ | 12kV | 941 | XY. V-mode |  |
| 1466A | 10 | 1 | 1 | 500 (x10) | $8 \times 10 \mathrm{~cm}$ | ${ }_{2} \mathbf{2 k V}$ | 670 380 | XYY. ${ }^{\text {X }}$-mode |  |
| 1476A | 10 | 1 | 2 | 500 (x10) - | $8 \times 10 \mathrm{~cm}$ | 2 kV | 460 | Dual-trace version of 1466A |  |
| 1535 A | 35 | 2 | 2 | 100 (x5) - | $8 \times 10 \mathrm{~cm}$ | 6 kV | 745 | Variable trigger hold off. Differential |  |
| 14798 | 30 | 5 | 2 | $200(\times 5)$ - | $8 \times 10 \mathrm{~cm}$ | 6 kV | 700 | XY. R.f. detector triggering |  |
| 1477 | 15 | 10 | 2 | 500 (x5) - | $8 \times 10 \mathrm{~cm}$ | 2 kV | 453 | XY |  |
| 1405 1420 | 5 | 10 | 1 | 1000 aprx. |  |  | 188 | Free-running time base, synchronized |  |
| 1435 | 15 15 | 10 2 | ${ }_{2}^{2}$ | $1000(\times 10)$ 500 (x5) | $4 \times 5 \mathrm{~cm}$ $4.8 \times 6 \mathrm{~cm}$ | $\stackrel{1 \mathrm{kV}}{15 \mathrm{kV}}$ | 650 677 | Mains/battery |  |
| Crotech |  |  |  |  |  |  |  |  |  |
| 3337 | 30 | 5 | 2 | 200 (x5) - | $8 \times 10 \mathrm{~cm}$ | 10kV | 405 | XY | WW502 |
| 3132 | 20 | 2 | 2 | 500 (x5) - | $8 \times 10 \mathrm{~cm}$ |  | 283 | XY. Tester for passive and active components |  |
| 3034 | 15 | 5 | 2 | 500 ( $\times 2.5$ ) - | $5.3 \times 6.6 \mathrm{~cm}$ | 2kV | 370 | Battery. XY. Battery saver |  |
| 3033 | 15 | 5 | , | $500 \times 2.5$ ) | $5.3 \times 6.6 \mathrm{~cm}$ | 1 kV | 287 | Battery saver |  |
| 3030 | 15 | 5 | 1 | 500 (x2.5) | $5.3 \times 6.6 \mathrm{~cm}$ | 1 kV | 154 | Component tester |  |
| 3035 | 10 | 5 | 1 | 500 (x2.5) | $8 \times 10 \mathrm{~cm}$ | 2 kV | 174 | Component tester |  |
| $\begin{aligned} & \text { Datacheck } \\ & 1200 \mathrm{~B} \end{aligned}$ | 2.5 | 50 | 1 | 2000 (x10) | $5 \times 4.2 \mathrm{~cm}$ | 1.8kV |  |  | WW518 |
|  |  |  |  | 2000 ( 10 ) | $5 \times 4.2 \mathrm{~cm}$ | 1.8 kV | 4223 | Modular. Up to 7 units plugged into rack. Dual, selectable inputs |  |
| 1200B(S) | 2.5 | 50 | 1 | 20,000 ( $\times 10$ ) | $5 \times 4.2 \mathrm{~cm}$ | 1.8 kV | 4545 |  |  |
| Farnell <br> DT12-5 | 12 | 5 | 2 | 500 (x5) - | $8 \times 10 \mathrm{~cm}$ | 2kV | 245 | XY | WW503 |
| DTV 12-14 | 12 | 5 | 2 | 500 (x5) - | $8 \times 10 \mathrm{~cm}$ | 2 kV | 265 | More flexible Y display options. |  |
| DTC-12 | 12 | 5 | 2 | 500 (x5) - | $8 \times 10 \mathrm{~cm}$ | 2 kV | 359 | Fine $X$ and $Y$ controls Component tester |  |
| DTS-12 | 12 | 5 | 2 | 500 (x5) | $8 \times 10 \mathrm{~cm}$ | 2kV | 795 | Digital storage version of DT12-5. Max. event speed 100 kHz . Max. sample rate 0.5 MHz . |  |
| $\begin{aligned} & \text { Gould } \\ & \text { OS } 300 \end{aligned}$ | 20 | 2 | 2 | 500 ( $\times 10$ ) | $8 \times 10 \mathrm{~cm}$ |  | 325 |  | WW504 |
| OS8100 | 100 | 2 | 2 | 50 - - | $8 \times 10 \mathrm{~cm}$ | 16 kV | 8400 | Micro-controlled. Menu display. Auto calculations |  |
| Hameg HM103 | 10 | 5 (x2.5) | 1 | 500 (x2.5) - |  |  |  |  | WW505 |
| HM203 | 20 | $5(\times 2.5)$ | 2 | $500(\times 12.5)$ | $6 \times 7 \mathrm{~cm}$ $8 \times 10 \mathrm{~cm}$ | ${ }_{1}^{1.8 \mathrm{kV}}$ | $\begin{aligned} & 158 \\ & 264 \end{aligned}$ | Component tester Component Tester |  |
| HM204 | 20 | $5(\times 2.5)$ | 2 | $500(\times 2.5)$ | $8 \times 10 \mathrm{~cm}$ | ${ }_{2}^{2 \mathrm{kV}}$ | 365 | Trig. delay |  |
| HM605 | 60 | $5(\times 5)$ | 2 | $50(\times 10)$ - - | $8 \times 10 \mathrm{~cm}$ | 14 kV | 487 | Trig. Delay. Trig. hold off |  |
| HM705 | 70 | 5 (x2.5) |  | $50(\times 10) \quad$ - | $8 \times 10 \mathrm{~cm}$ | 14 kV | 588 | Trig. delay |  |
| Hewlett-Packard 1980 |  |  |  |  |  |  |  |  | WW521 |
|  | 100 | 2 | 2 | $5 \cdot$ - | 10x. 12 cm | 22kV | 8516 | XY Trig-view. Trig delay. Auto-ranging triglevel, deflection factor and sweep speed |  |
| Hitachi V-212 | 20 |  |  |  |  |  |  |  | WW506 |
| V-222 | 20 | 5(x5) | 2 | 200(x10) | $8 \times 10 \mathrm{~cm}$ $8 \times 10 \mathrm{~cm}$ | ${ }_{2}^{2 \mathrm{kV}}$ | $295$ | XY. V-mode |  |
|  |  |  | 2 | $200 \times 10)$ |  | 2 kV | $340$ | D.c. offset for small signal viewing in presence of d.c. Avoids a c. coupling $V$-mode |  |
| V-422 | 40 | $5(\times 5)$ | 2 | 200 (x10) - | $8 \times 10 \mathrm{~cm}$ | 12 kV | 510 | d.c. Avoids a.c. coupting. V-mode |  |
| V-203F | 20 | 5 (x5) | 2 | 200 (x10) - | $7.5 \times 9.5 \mathrm{~cm}$ | 2 kV | 355 | Trig. delay |  |
| V-353F V - 1050 F | 35 | $5(\times 5)$ | 2 | 200 ( $\times 10$ ) - | $7.5 \times 9.5 \mathrm{~cm}$ | 5.2 kV | 495 | Trig delay |  |
| V-1050F V -650F | 100 | $5(\times 10)$ | 4 | $20(\times 10)-$ - | $8 \times 10 \mathrm{~cm}$ | 20 kV | 1200 |  |  |
| $\checkmark$ V-509 | 50 | $5(\times 5)$ $5(\times 5)$ | 3 2 | $50(\times 10)$ $100(\times 10)$ - | $8 \times 10 \mathrm{~cm}$ $5 \times 6.3 \mathrm{~cm}$ | 10 kV 12 kV | 750 | A-trigger view on third channel |  |
| V-209 | 20 | 5 (x5) | 2 | 500 (x5) | 5x6.3cm | 1.5 kV | 995 525 | A.c.-d.c. Trig. delay A.c.-d.c. |  |
| watsu |  |  |  |  |  |  |  |  |  |
| SS5702 | 20 | 5(x5) | 2 | $100(\times 5)$ | $8 \times 10 \mathrm{~cm}$ | 2kV | 290 | XY. Ac/dc | WW519 |
| SS3510 | 50 | $2(\times 5)$ | 2 | $100(\times 10)-$ - | $5 \times 6.4 \mathrm{~cm}$ | 12 kV | 1250 | Batt/mains, $8.25 \times 4 \times 11.875 i n .8 .61 b$ |  |
| SS5710 | 100 | 1 | 4 | $20(x 10)$ - - | $8 \times 10 \mathrm{~cm}$ | 20 kV | 745 |  |  |
| SS5711 | 60 | 1 | 4 | 50 ( $\times 10$ ) | $8 \times 10 \mathrm{~cm}$ | 15kV | 1150 |  |  |
| Kikusui <br> COS6100 | 100 |  |  |  |  |  |  |  | WW511 |
|  | 100 | 5 (x5) | 5 | $20(\times 10)$ - | $8 \times 10 \mathrm{~cm}$ | 20kV | 1145 | XY. Displays $\mathrm{CH} 1, \mathrm{CH} 2, \mathrm{CH} 3, \mathrm{~A}$ trig, B trig. |  |
| COS3010 | 15 | $5(\times 5)$ | 2 | $500(x 5) \quad$ - | $7.6 \times 6.4 \mathrm{~cm}$ | 1.5 kV | 395 | Mains/battery. Trig. hold off. XY off |  |
| $\begin{aligned} & \text { COS5060 } \\ & \text { COS5041 } \end{aligned}$ | $\begin{aligned} & 60 \\ & 40 \end{aligned}$ | $5(\times 5)$ | 3 | $50(\times 10)-$ - | 6 in rect. | 12 kV | 735 | 8 traces. $X Y$ |  |
| COS5040 | 40 | $5(\times 5)$ $5(\times 5)$ | 2 | ${ }_{200}^{200(\times 10)} \times$ - | 6 in rect. | 12 VV | 535 |  |  |
| COS5021 | 20 | 5 (x5) | 2 | 200 ( $\times 10$ ) - | 6 in rect 6 in rect | ${ }^{12 \mathrm{kV}}$ | 445 395 | XY. Trig. hold off |  |
| COS5020 | 20 | 5 ( $\times 5$ ) | 2 | 200 ( $\times 10$ ) | 6 in rect | ${ }_{2}^{2 \mathrm{kV}}$ | 280 | $\begin{aligned} & \text { Trid } \\ & \text { XY } \end{aligned}$ <br> Trig. hold off. XY |  |
| Leader L80514A | 15 | 5 (x5) | 2 |  |  |  |  |  | WW507 |
| B0522 | 20 | $5(\times 10)$ | 2 | 200 (x5) | $8 \times 10 \mathrm{~cm}$ | 1.8kV | 349 |  |  |
| [80523 | 35 | 5 (x10) | 2 | 200 (x10) | $8 \times 10 \mathrm{~cm}$ | 7 kV | 501 | $X Y$ Trig. hold off |  |
| LB0524 | 35 | $5(\times 10)$ | 2 | 200 (x10) - - | $8 \times 10 \mathrm{~cm}$ | 7 kV | 615 | XY |  |
| Non-Linear MS215 | 15 | 10 | 2 | 100 |  |  |  |  | WW520 |
| MS230 | 30 | 10 | 2 | 50 | 2. $2.5 \times 3.2 \mathrm{~cm}$ | $\begin{aligned} & 700 \mathrm{~V} \\ & 700 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 445 \\ & 540 \end{aligned}$ | Batt/mains ( 110 V a.c.) Measures $2.9 \times 6.4 \times 8 \mathrm{in}$. Batt/mains (110Va.c) |  |
| Philips PM3262 | 100 | 2 | 3 |  |  |  |  |  | WW512 |
| PM3267 | 100 | 2 | 3 | $50(\times 10)-$ | $8 \times 10 \mathrm{~cm}$ $8 \times 10 \mathrm{~cm}$ | ${ }_{1}^{17 \mathrm{kV}}$ | 1695 | Trig. hold off. Trig. view |  |
| PM3264 | 100 | 2 | 4 | $50(\times 10)$ - | $8 \times 10 \mathrm{~cm}$ | 17 kV | 3550 | Trig. view on fifth channel |  |
| PM3263 | 100 | 2 | 2 | $50(\times 10)$ - | $8 \times 10 \mathrm{~cm}$ | 17 kV | 3030 | Trig view. Dual delay for time interval |  |
| PM3254 | 75 | 2 |  | $50(x 10)$ - | $8 \times 10 \mathrm{~cm}$ | 10kV | 1145 | Trig. view on third channel |  |
| PM3256 |  |  | 2 |  |  |  | 12.45 | As 3254 with two channels |  |
| PM3215 | 50 | 2 | 2 | $100(\times 10)-8$ | $8 \times 10 \mathrm{~cm}$ | 10 kV | 695 | XY. Trig. hold off |  |
| PM3217 | 50 10 | 2 | 2 | $100(\times 10)-$ - | $8 \times 10 \mathrm{~cm}$ | 10 kV | 850 | As 3215 with delayed time base |  |
| PM 3211 | 10 15 | 2 | 2 | 200 (x5) - | $8 \times 10 \mathrm{~cm}$ | 10 kV | 960 | Dual beam |  |
| PM3207 | 15 | 5 | ${ }_{2}^{2}$ | 500 (x5) | $8 \times 10 \mathrm{~cm}$ $8 \times 10 \mathrm{~cm}$ | 4 kV | 660 |  |  |
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the chopping is invisible, ch1 minus ch2 and chl plus ch2.
The 'alternate' and 'chopped' presentations perform roughly the same function. At low and middle frequencies, chopping between channels occurs many times during the time-base sweep and is generally not phase-related: it cannot, therefore, be seen and the two traces appear simultaneously. At higher frequencies, the chopping may occur only a few times during a sweep and may become visible, so that each trace must then be triggered alternately to give once again an effective simultaneous display of the two signal channels.
Input impedance at the Y inputs is usually $1 \mathrm{M} \Omega$ with $20-30 \mathrm{pF}$ in parallel. In the event that the signal under inspection is from a high-impedance source and would be deformed by this input arrangement, most makers provide as an accessory a probe which, at the expense of a decrease in sensitivity by a factor of 10 , gives $10 \mathrm{M} \Omega$ and 2 pF at the probe tip. Even better performance is provided by probes with a field-effect transistor source-follower, which can give $1 \mathrm{M} \Omega$ and around 1 pF even when the input of the oscilloscope is a $50 \Omega$ coupling - often found with high-frequency instruments.
Input coupling selects a coupling capacitor when the d.c. component of a signal is too high to allow inspection of small features which need a high sensitivity. It is usually marked AC, DC and GND, the latter earthing the input to provide a 0 V reference on the display.
Delay line allows inspection of the leading edge of a transient. Since the signal itself normally triggers the time-base, and since the time-base takes a certain amount of time to fire after the trigger, the leading edge would have occurred before the sweep started, without the delay line.
With the line in the signal path, the signal is delayed by a fraction of a microsecond until the time-base is operative. The delay line does not deform the signal.

## Time-base

Modern time-bases are of the triggered variety - they run when triggered by a pulse. The rate at which the spot sweeps across the screen is controlled from a frontpanel switch, usually in a $1-2-5$ sequence, and by an uncalibrated variable control. The fastest sweep provided must spread the rise-time of the Y amplifier over a useful part of the screen; for example, if the bandwidth is 100 MHz , giving a rise time of 3.5 ns , the highest sweep speed should be around 2 to 5 ns per division or per centimetre. It may be that the fastest sweep on the control is ten times slower than this, at around 50 ns per division, in which case there will probably be provision to magnify the sweep amplitude to overscan the screen by a factor of 10 , effectively multiplying the sweep speed by 10 . The result is roughly the same.

## Horizontal modes

In dual-trace instruments, delayed sweeps vith a number of display modes are comionplace. In essence, the main (A) sweep
traverses the whole area of investigation relatively slowly, small events being identifiable but not easily seen. By means of a delay control, the second (B) sweep is triggered just before the area of interest and, since it is set to run much faster than the A sweep, covers only that part. During this time the A sweep only is displayed, the part covered by the $B$ sweep being brightened up.
When the delay and the duration of the $B$ sweep are adjusted as required, the B sweep is displayed across the whole screen, the aforementioned small event now being magnified horizontally. The front-pànel mode selector is labelled A, A intensified by B, B, or words to that effect. On some instruments, the delayed and delaying sweeps can be mixed to display both simultaneously. It might be possible to see the small occurrence in the normal way with sweep magnification, if it were near the trigger pulse, but a large magnification on a small trace would almost certainly result in a jittery display: the delaying method avoids this problem.

## Triggering

A variety of triggering modes is usually provided. 'Normal' is the condition when the Y signal signal provides a trigger pulse for the time-base, which does not sweep unless the trigger is present. In the 'automatic' mode, the time-base free runs, providing a base-line on the screen in the absence of a $Y$ signal, and locks to an applied signal: it is somewhat similar to the method used many years ago when freerunning time-bases were synchronized with the $Y$ signal. A 'single-sweep' facility is sometimes provided, when the timebase fires once on the next trigger after a frontpanel button is pressed. Trigger hold-off is useful when, say, one cycle in a long train is to be viewed. It would normally not be easy to trigger the sweep just before the wanted cycle, since as far as the trigger circuit is concerned, all the cycles are identical. With trigger hold-off, pulses can be inhibited until the part to be investigated is reached, whereupon the next trigger fires the time-base, which can then run at the desired speed.

Since the $Y$ signal itself normally provides the trigger, it is necessary to select the exact point on a waveform at which the trigger pulse is generated. The 'level' control sets this in the vertical direction and the 'slope' determines whether the trigger is taken from a positive or negativegoing edge. It is usually possible to use an external trigger, selectable from the front panel. Vertical-mode triggering (V mode) enables two traces of differing frequencies to be viewed alternately - normally, triggering from one would give an unlocked display of the other.

In the table, sensitivity and sweep-speed figures are given without taking into account the multipliers shown in brackets. Prices quoted are exclusiive of v.a.t.

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## Manufacturers

BK/Dynascan. B \& K Precision, P.O. Box 27. 39 Whitby Street, Hartlepool, Cleveland TS24 7BR. 042975750.
Crotech. Crotech Instruments Ltd, 5
Nimrod Way, Elgar Road, Reading, Berks. RG2 OEB. 0734866945.
Datacheck. RMR Measurements, 138 Lime
Crescent, Cumbernauld G67 3PQ. 02367 28170.

Farnell. Farnell Instruments Ltd, Sandbeck
Way, Wetherby, West Yorks. LS22 4DH. 093761961.

Gould. Gould Instruments Division,
Roebuck Road, Hainault, Essex IG6 3 UE.
01-500 1000. Electroplan Ltd, P.O. Box 19,
Orchard Road, Royston, Herts ST8 5HH. 076345145.

Hameg. Hameg Oscilloscopes Ltd, 74-78
Collingdon Street, Luton, Beds LU1 1RX.
0582 413174. Lawtronics Ltd, 139 High
Street, Edenbridge, Kent TN8 5AX. 0732 865191.

Hewett-Packard. H.P. Ltd, Nine Mile Ride, Easthampstead, Wokingham, Berks RG11 3LL. 034463100.
Hitachi. Hitachi Denshi (UK) Ltd, 13-14
Garrick Industrial Centre, Garrick Road,
Hendon, London NW9 9AP. 01-202 4311
Reltech Instruments, New Road, St. Ives,
Huntingdon, Cambs. PE17 4BG. 0480 63570.

Iwatsu. STC Instrument Services,
Edinburgh Way, Harlow, Essex CM20 2DF 027929522.

Kikusui. Telonic Instruments Ltd, 2 Castle Hill Terrace, Maidenhead, Berks SL6 4JP. 062873933.

Non-Linear Systems. Lawtronics Ltd, 139 High Street, Edenbridge, Kent TN8 5AX. 0732865191.

Leader. Thandar Electronics Ltd, London
Road, St. Ives, Huntingdon, Cambs PE17
4HJ. 0480 64646. Also Electroplan Ltd, P.O.
Box 19, Orchard Road, Royston, Herts. SG8 5HH. 076345145.
Philips. Pye Unicam Ltd, York Street,
Cambridge, CB1 2PX. 0223358866.
Electronic Brokers Ltd, $61 / 65$ Kings Cross
Road, London WC1X 9LN. 01-278 3461.
Rohde und Schwarz. R \& S GmbH\&Co KG. D-8000 Munchen 80, Mühldorfstrasse 115 , West Germany. (089) 4129-1.
Scopex. Scopex Electronics Ltd, 63-65 High
Street, Skipton, N. Yorks. BD23 1EF. 0756 69511.

Siemens. Siemens Ltd, Siemens House, Windmill Road, Sunbury-on-Thames, Middlesex TW16 7HS. 0932785691.
Solartron. Solartron Schlumberger,
Victoria Road, Farnborough, Hants GU14 7PW. 0252544433.
Tektronix. Tektronix UK Ltd, P.O. Box 69,
36/38 Coldharbour Lane, Harpenden, Herts, AL5 4UP. 05827 63141. Also Electroplan Ltd, P.O. Box 19, Orchard Road, Royston, Herts SG8 5HH. 076345145.
Thandar. Thandar Electronics Ltd, London Road, St. Ives, Huntingdon, Cambs. PE17 4HJ. 048064646.
Trio. House of Instruments, Clifton Chambers, 62 High Street, Saffron Walden, Essex CB10 1EE. 0799 24922. Also Lawtronics Ltd, 139 High Street,
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# Designing with the 68008 microprocessor 


#### Abstract

Ideal for use in low-cost, high-volume applications like personal computers and small business machines, the 68008 is an eight-bit microprocessor with a 32-bit architecture.

This two-part article describes its main features and how it's used with other microcomputer components like rom, ram and peripheral devices.


All of the microprocessors in the M68000 family of high-performance processors and peripherals, including the 68008, are based on the same 32 -bit architecture. The 68008 has an eight-bit external data bus; others have 16 or 32 -bit buses. The once-clear divisions between eight, 16 and 32-bit microprocessors are becoming blurred; with the 68008 the designer is now able to have a high-performance microprocessor with a 32 -bit architecture in small costeffective systems using eight-bit data buses.

The architecture of the 68008 is identical to the original member of the family, the 68000 , a processor with a 16 -bit external data bus. From the programmer's point of view the two processors look identical, so that the 68008 is completely code-compatible with the 68000 . This means that any program developed for one processor will run on the other. This is true for object code as well as source code. Other 68000 -family microprocessors such as the 68010, virtual memory version of the 68000 , and the 68020 , very high performance 32-bit mpu, have achitectures which are upward-compatible with that of the 68008, making it easier to upgrade 68008 -based systems. For example, any user program written for the 68008 will execute correctly on the 68000,68010 and 68020 without need for modification.

Using standard rams and roms a smaller minimum-sized system can be constructed with the 68008 than with the 68000 . Cost savings are made by producing the 68008 in a 48 -pin dual-in-line package as opposed to the 64 -pin version for the 68000 . Eight pins are saved by halving the reduced data bus. Other minor hardware differences allow more pins to be shed (Fig. 1), for instance a few of the high-order address lines of the 68000 are not brought off-chip on the 68008 . Even so, this still allows direct addressing of over one megabyte of memory - huge compared to that of conventional eight-bit microprocessors and more than enough for the low-end applications for which the 68008 is intended.
The 68008 is as fast as the 68000 when

## by A. J. Barth

accessing byte-sized operands. However, because of its byte-sized data bus the 68008 needs to access 16 -bit words as two successive bytes. As a result, the overall throughput of the 68008 is less than that of the 68000 . For the same processor clock and for a typical mix of instructions, the 68008 's performance is about $60 \%$ of that of the 68000 . This is still a lot of raw processing power and will meet a need for low-end applications.

Because the architectures of the 68000 family microprocessors are so similar, knowing the 68008 means knowing much about the other processors. The 68008 is characterized by its 'clean', regular and consistent structure and in particular, emphasis was given to the architecture to make it regular with respect to the registers, instructions, addressing modes and data types.

## Register set

The 68008 programming model has a large number of general-purpose 32-bit data and address registers, Fig. 2. There are eight
general-purpose 32 -bit data registers, $\mathrm{D}_{0}{ }^{-}$ $\mathrm{D}_{7}$, for byte ( 8 -bit), word (16-bit), and long word ( 32 -bit) operations. Seven address registers $\mathrm{A}_{0}-\mathrm{A}_{6}$ and two system stack pointers $\mathrm{A}_{7}$, may be used as software stack pointers and base address registers. In addition these registers may be used for word and long-word address operations. All 17 registers may be used as index registers.

High-performance microprocessors are expected to rapidly handle complex functions having a large number of parameters. The 68008 can maintain most or all of these parameters in processor registers, which is both fast and makes the programs efficient and elegant. Microprocessors with only a few registers in such situations need to continuously swap parameters between registers and external memory.
As the 68008 has general-purpose registers, the programmer and not the microprocessor-chip designer decides which registers are used. It does not dictate that certain instructions use certain registers. This not only eases the task of the assembler language programmer but also makes high-level language compilergenerated code more efficient. Many of the instructions and addressing modes which


Fig. 168008 signal lines. The microprocessor has an internal 32-bit architecture and an eight-bit external data bus. Packaged in a 48-pin package the 68008 has non-multiplexed buses and a non-segmented 1 megabyte address space.
operate on the address registers may also be used with the 32 -bit program counter. This makes it easy to write positionindependant software that will execute correctly no matter where the code is loaded in memory.

The 68008 has a 16 -bit status register which consists of two parts: a user byte and a system byte. The user byte is accessible by any program and contains the usual condition code flags associated with the execution of instructions, condition like Negative, Zero, Carry, Overflow, etc. The system byte of the status register is accessible only by a supervisory program (usually the operating system) and is used to control the operating mode.

## Addressing range

The 68008 has a large linear addressing range. It can directly access one megabyte of external memory without paging or segmentation. Many microprocessors are able to access fairly large memory space but need to do so via a narrow window called a segment or page. This may be useful in a few applications, but in most situations it is an irritating handicap because the programmer is obliged to keep repositioning the window to access the desired location.

Like other Motorola microprocessors the 68008 has memory-mapped i/o. This enables the programmer to use the m.p.u's sophisticated instructions and addressing modes to operate on $\mathrm{i} / \mathrm{o}$ as well as memory.

## Instruction set

The 68008 has a powerful, flexible and easy-to-use instruction set. There are 56 basic instructions (Table 1). This is actually less than the ten-year-old 6800 microprocessor. However because of the regularity of the 68008 architecture, those instructions which use registers may use any register with almost any addressing mode and data type. These permutations yield many thousands of useful operations, compared to less than 100 for the 6800; the 68000 family philosophy being to provide a small number of easy-to-remember and flexible general-purpose instructions.

The instruction set covers the following classes of operations:
-data movement
-integer arithmetic

- logic
-shift and rotate
-bit manipulation
-binary-coded decimal
-high-level language support
- program control and
-system control.
Operations on data in registers and memory are independent of the data size and usually involve a source and a destination operand. The programmer need only remember one mnemonic for each type of operation and then specify data size and addressing modes for both the source and destination operands. Consistency is maintained as all data registers and memory locations may be a source or destination for most operations on integer data.


Fig. 268008 programming model: eight general-purpose data registers for 8, 16 and 32-bit operations, seven address registers, and two system stack pointers for software stack pointers and base address register. All 17 maybe used as index registers.

Like all M68000 microprocessors the 68008 instructions are implemented by microcode rather than random logic, so that, for example, the execution of undefined instructions no longer leads to unpredictable results.

## Data types

The 68008 operates on five main data types. Operations may be on bits, b.c.d. digits, bytes, words and long-words. For integer arithmetic the programmer need not remember different instructions for different data sizes. The required data size is simply appended to the instruction as the program is written.

## Addressing modes

An addressing mode is the method by which the data or other operand is accessed by the processor. The availability of powerful and flexible modes usually means performing an operation with just one instruction which would otherwise take many. This results in programs executing faster, being smaller, easier to read and to maintain. The 68008 has 14 powerful addressing modes (See Table 2). They operate consistently and are independent of the instruction itself.

## Program privilege scheme

A two-level program privilege scheme
provides security and high reliability. Programs should access only their own code and data areas, and ought to be restricted from accessing the information which they do not need and must not modify. Such a scheme not only prevents the deliberate tampering with data but also guards against a faulty program running wild and altering other programs.

The 68008 operates at one of two privilege levels, the supervisor level or at the user level. At the supervisor level programs have access to all processor resources and can execute any instruction or access any register. Normally, only the controlling operating system or its kernel runs at this level. This code is normally relatively small, well-tested and therefore reliable. All the rest of the software, which includes both the utility and application programs, executes at the user level and has access only to a subset of the total processor unit resources, the resources governing control of the system being protected from these programs. If a userlevel program attempts to execute a 'privileged' instruction or to access a supervisor register, control is immediately taken away and given to the controlling supervisor program which can take some corrective action.

## Interrupt structure

In most applications, programs are seldom executed instruction-after-instruction without a break. The need frequently arises to respond to an event or exception. Such exceptions may be the hardware interrupts caused by external logic, or the software interrupts caused by the recognition of some condition internal to the processor unit. High-performance microprocessors must be able to respond rapidly to a large variety of exceptions with varying degrees of priority.

Three levels of priority are provided for external hardware interrupts. By use of the three-bit interrupt mask in the 68008 status register (Fig. 2) the supervisor program may postpone handling external interrupts with priorities less than that contained in the mask. When an interrupt


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microprocessor systems design in
Germany and the USA, as well as in the UK.

Table 1. 68008 instruction set

| Mnemonic | Description |
| :--- | :--- |
| ADBC | add decimal with extend |
| ADD | add |
| AND | logical and |
| ASL | arithmetic shift left |
| ASR | arithmetic shift right |
| BCC | branch conditionally |
| BCHQ | bit test and change |
| BCLR | bit test and clear |
| BRA | branch always |
| BSET | bit test and set |
| BSR | branch to subroutine |
| BTST | bit test |
| CHK | check register against bounds |
| CLR | clear operand |
| CMP | compare |
| DBCC | test condition, decrement \& branch |
| DIVS | signed divide |
| DIVU | unsigned divide |
| EOR | exclusive or |
| EXG | exchange registers |
| EXT | sign extend |
| JMP | jump |
| JSR | jump to subroutine |
| LEA | load to effective address |
| LINK | link stack |
| LSL | logical shift left |
| LSR | logical shift right |
| MOVE | move |

is recognised the processor performs an interrupt acknowledgement sequence (IACK). During IACK the peripheral being acknowledged may indicate that program control should be given to any one of 256 interrupt service routines (vectored interrupt method), or to one of three service routines corresponding with the hardware interrupt priority level (autovector interrupt method). Most of the M68000-family peripherals use the vectored interrupt method in which the peripheral provides an eight-bit vector number on the data bus. The 68008 uses this vector number to determine which of the 256 interrupt routine addresses in its interrupt vector table to use. The less sophisticated peripherals use the autovector interrupt method which have seven vectors reserved for them. In either case the external hardware needed to interface both kinds of perpherals to the 68008 is minimal.

Some 68008 instructions are designed to cause internal interrupts, some always and others only upon detection of certain conditions. An example of the last is the execution of a 'privileged' instruction. If a supervisor-level program executes such an instruction, the instruction will execute normally and no exception will occur. However, if a user-level program attempts to execute it, a prividege violation exception occurs and program control is given immediately to the appropriate interrupt service routine.
A number of exceptions correspond to error conditions, either those detected by external hardware or by the processor itself. For example, the Bus Error input (BERR) may be used by external hardware to cause the 68008 to abandon the current bus cycle and give program control to the Bus Error interrupt routine, or, by the simultaneous use of BERR and HALT, to retry the current bus cycle.
A very useful feature is the trace exception, which enables a supervisorlevel program to step through a target program on an instruction-by-instruction

| Mnemonic | Description |
| :--- | :--- |
| MOVEM | move multiple registers |
| MOVEP | move peripheral data |
| MULS | signed multiply |
| MULU | unsigned multiply |
| NBCD | negate decimal with extend |
| NEG | negate |
| NOP | no operation |
| NOT | one's complement |
| OR | logical or |
| PEA | push effective address |
| RESET | reset external deuces |
| ROL | rotate left without extend |
| ROR | rotate right without extend |
| ROXL | rotate !eft with extend |
| ROXR | rotate right with extend |
| RTE | return from exception |
| RTR | return and restore |
| RTS | return from subroutine |
| SBCD | subtract decimal with extend |
| SCC | set conditional |
| STOP | stop |
| SUB | subtract |
| SWAP | swap data register halves |
| TAS | test and set operand |
| TRAP | trap |
| TRAPV | trap on overflow |
| TST | test |
| UNLK | unlink |

basis. Each time the target program executes an instruction, no matter which instruction it may be, control is returned to the supervisory program. No external hardware is required to implement the program tracing as it is part of the processor architecture.

## Asynchronous data bus

Like most of the other Motorola microprocessors, the 68008 data bus is not multiplexed - the m.p.u. pins used for the data bus are not shared with other signals. Some microprocessors multiplex the data and address buses onto the same pins to reduce the total number of pins. Non-multiplexed microprocessors such as the 68008 require more pins and sometimes a more expensive package. However, non-multiplexed buses have many advantages: they can operate much
faster, dissipate less chip power, and do not require external demultiplexing hardware. Analysis shows that multiplexed microprocessor systems are more costly than non-multiplexed systems because the microprocessor and demultiplexing i.cs together cost more, occupy more board space and have more pins overall.

The 68008 has an asynchronous data bus. The time taken to transfer data to or from a memory or peripheral device via the data bus is variable. The memory or peripheral device signals the processor when it is ready to make the data transfer by use of a special handshake line called data transfer acknowledge (DTACK). The advantage of this asynchronous scheme is that each bus cycle can be fine-tuned to the speed of the particular device being accessed. If the device is rather slow, the processor simply marks time until the device is ready. In this way the 68008 runs at the fastest rate that memory and peripherals can go, which maximizes system throughput.

Most M68000-family peripherals have a pin for the DTACK handshake signal, and interfacing such parts to the 68008 microprocessor is simple. Even those peripherals originally designed to work with synchronous processors, like the 6800 or 6809 microprocessor units, may be interfaced to the 68008 with minimal hardware. This is because the 68008 has several signal pins specially for this purpose. By use of these signals, the M6800-type peripheral device signals the processor to perform the current bus cycle synchronously, making the 68008 behave like a synchronous microprocessor for this one bus cycle.

The 68008 m.p.u. uses a two-line bus arbitration scheme which enables the data bus to be shared efficiently with other microprocessors unitss in a multiprocessor system and with other bus masters such as d.m.a. controllers.

To be continued with interfacing details.

| Mode | Generation |
| :---: | :---: |
| Register direct addressing |  |
| Data register direct | $E A=D_{n}$ |
| Address register direct | $E A=A_{n}$ |
| Absolute data addressing |  |
| Absolute short | EA=(next word) |
| Absolute long | $E A=$ (next two words) |
| Program counter relative addressing |  |
| Relative with offset | $E A=(P C)+d$ |
| Relative with index and offset | $E A=(P C)+\left(X_{n}\right)+d_{8}$ |
| Register indirect addressing |  |
| Register indirect | $\mathrm{EA}=\left(\mathrm{A}_{\mathrm{n}}\right)$ |
| Postincrement register indirect | $E A=\left(A_{n}\right), A_{n} \leftarrow A_{n}$ |
| Predecrement register indirect | $A_{n} \leftarrow A_{n}-N, E A=\left(A_{n}\right)$ |
| Register indirect with offset | $E A=\left(A_{n}\right)+d_{16}$ |
| Indexed register indirect with offset | $E A=\left(A_{n}\right)+\left(X_{n}\right)+d_{8}$ |
| Immediate data addressing $\begin{aligned} & \text { Immediate }\end{aligned}$ |  |
|  |  |
| Quick immediate |  |
| Implied addressing Implied register | EA = SR, USP, SP, PC |
| EA effective address |  |
| $\mathrm{A}_{n}$ address register |  |
| $\mathrm{D}_{n}$ data register |  |
| $\mathrm{X}_{\mathrm{n}}$ address or data register used as index register |  |
| SR status register PC program counter |  |
| $\mathrm{d}_{8}$ eight-bit offset (displacement) |  |
| $\mathrm{d}_{16}$ sixteen-bit offset (displacement) |  |
| $\mathrm{N}=1$ for byte 2 for words and 4 for long words () contents of |  |
|  |  |
| $\leftarrow$ replaces |  |

# 16-line p.a.b.x with options 

## Hints on construction complete Jaap Kuiper's description of a versatile electronic/electromechanical exchange

Current passing through the telephones has to be kept within acceptable limits. Having used $700 \Omega$ relays throughout the O relay requires a $470 \Omega, 1 W$ series resistor (at 45 V supply). As relays $\mathrm{O}, \mathrm{G}, \mathrm{II}, \mathrm{EI}$ and R are all controlled from the individual stations they must switch positively. Typical values for limiting resistors turned out to be $390 \Omega$, 1 W for II, EI and R, and $1 \mathrm{k} \Omega, 1 \mathrm{~W}$ for G relays and others working off the 45 V supply. Relays using the 12 V rail don't need series resistors and so operate economically and reliably. The limiting resistor for $G$ relays, if required fits between the G-bus and contacts $\mathrm{gh}_{2} / \mathrm{gi}_{2}$ in the external control section.
Most Continental telephones include a ground key but where not, momentary push-buttons may be fitted and connected directly to the set's a-line. The original switches, if available, may be fitted in the space provided on top of UK sets in front of the cradle. Holes for the leds have to be drilled or melted in a suitable position and are also connected directly to the a-line. Previous diagrams gave details for both Continental and UK sets.
Special mounting plates (RS Components RS349-119) are available for fitting Siemens/Varley type relays. Each plate holds six relays. Joining these plates together allows daisy-chain wiring of the bussed contacts. The mounting plates have each station's $O, T$ and $G$ relays grouped together for ease of wiring with ribbon cables running to the T-drivers. Terminator, oscillators and line interface were constructed on home-made p.c.bs and 30 -way connectors were used to plug in the various telephones.
Resistors in the ground-key toggle have to be approximately the same value as the relay coil and must be capable of dissipating the full power during switching ( $1 \mathrm{k} \Omega$, 5 W ). The muting i.c. is an LM311 which is rated at 36 V maximum, so a voltage divider was included to reduce the supply. These are resistors ra and rb . The reference point is connected through a $1 \mathrm{M} \Omega$
resistor so as not to affect proper operation of EI which has to follow dial pulses. At $700 \Omega$ EI coil value and a telephone presenting $300 \Omega$ when operating, the reference voltage will be approximately 31.5 V . Therefore divider rc/rd has to be adjusted to provide around 35 V . As soon as the dial is moved the reference point goes to the full supply voltage; the $1 \mathrm{M} \Omega$ resistor protects the i.c. The LM311 will switch up

## by J. H. Kuiper

to 40 V so the additional transistor was included for protection.
With the introduction of more and more d.t.m.f. (system $\mathbf{X}$ ) exchanges it is sensible to construct the line interface on a separate p.c.b. so that when change-over is required only the line interface needs replacing. A dual tone circuit (Exar application note AN-08) then feeds the 4514 latch. Wiring to the individual sets is by standard four-core cable as each station's $b$ and


Automatic dialling by computer requires two buffered output ports each driving a relay. Additional hardware requirements are minimal as shown here.

Power supply diagram. Current of the 33 V secondary producing 45 V direct is 1.5 A . Using higher impedance coils will reduce this. Current from the $9 V$ secondary is 100 mA ; a 12 V regulator is used on this supply. The $1 \mu \mathrm{~F}, 250 \mathrm{~V}$ ringer-line capacitor is not needed for UK sets.


ground-key wire have to be discrete throughout. This largely applies to the awire as well to avoid speech induction to unwanted sets. Led-lines may, however, be joined together at convenient places to reduce the number of leads.
The line isolating and matching transformer is available from RS Components (RS217-826). The RC shunt across the interruptor contact consists of a $1 \mu \mathrm{~F}, 250 \mathrm{~V}$ capacitor and a $560 \Omega, 1 W$ resistor on the Continent and $2 \mu \mathrm{~F}, 250 \mathrm{~V}$ and $600 \Omega$, 1 W in the UK. In view of interface requirements relays EI and $M$ should be new types as they must have a contact bounce of less than 4 ms and contact resistance of less than $200 \mathrm{~m} \Omega$. All other relays may be surplus types. Diodes are general-purpose high-speed silicon types. Many diodes used combine or separate switching actions to reduce the number of relay contacts; these are rated at 100 mA (BA155). Diodes used in the oscillator circuits and sections working at 12 V may be rated lower.

Note that in stations not requiring the muting-inhibit action the $\mathrm{g}_{4}$ contact becomes redundant. Since relays usually come with two or four contacts, a component can be reduced by omitting the diode between contact $t_{2}$ and the $G$ coil and connecting spare contact $g_{4}$ directly from $\mathrm{t}_{2}$ to ground (marked with asterisk on page 63 of November issue).

MNO


## Micro-floppy

Following other Japanese manufacturers, Teac have announced the availability of FD30A, a 3in floppy disc drive that has all the same characteristics as their 5.25in drives; capacity, format, density, disc rotation speed, transfer rate and power and data interface connections are all identical. This makes it fully compatible and a direct replacement for its larger cousin. With a brushless d.c. direct-drive motor, the drive is claimed to be very durable and electrical noise is eliminated. Available in the UK through Tekdata Electronics, Federation Road, Burslem, Stoke-on-Trent ST6 4HY
WW 305

## Transistor tester

An addition to their range of handheld test units is the Osgorne 4500 transistor tester. Completely selfcontained, it can be used easily to check p-n junctions of discrete semiconductors whether in or out of circuit. It features a series of leds which indicate the junction status; p-n-p or n-p-n, open or short circuit can be instantly identified and it will work reliably even when parallel circuits have values approaching 270 ohms or 33 microfarads. Osborne Electronics, Binstead Road, Ryde, Isle-of-
Wight.
WW 306

## Voice digitizer

A voice digitizer may be used to enable the transmission of voice and data down the same telephone line. An American model, the Switchco TSP series 1000 works at a very low data rate of $2400 \mathrm{bit} / \mathrm{s}$ which makes it easy to use with data modems or, by using a multi-
port modem it can transmit four voice conversations over the same line. It is distributed by Vanderhoff Communications Ltd,
Haunchwood Estate, Bermuda Road, Nuneaton, Warwicks CV10 7QF.
WW 307

## Conduct heat - not current

Another American product is a thermally-conductive dry filled silicone rubber that provides 2000 V isolation between power semiconductors and heat sinks. The low-cost Aarvid Rubber-Duc pads are vulcanised onto the heatsinks in the factory and eliminate mica washers and grease or silicone rubber pads and adhesives, while offering better thermal conductivity than either. Configurations suitable for TO-3, TO-66 and plastic power devices as well as DO-4 and DO-5 diode washers. Warth International Ltd, Oxted, Surrey. WW 308

## Shaft cutter

The cutting of shafts on potentiometers, rotary switches and variable capacitors has been made much easier by the introduction of the Telpro shaft shear. This guillotine-type tool will cut copper, aluminium, mild and stainless steel, and plastics rods of diameters up to 0.25 in or 6 mm . It does not transmit any shock or vibration and may be used on such delicate components as helical trimmers, providing a clean cut
with no need for further filiing or finishing. It is claimed that the tool will pay for itself by cutting as few as half-a-dozen shafts because of the reduction in time and damage to components. Electronic and Computer Workshop Ltd., 171 Broomfield Road, Chelmsford Essex CM1 IRY
WW 309

## Laser for communication

A new high-frequency GaAlAs diode laser with a modulation bandwidth of 6 GHz is mounted in an impedance matched high frequency module which includes an integral power-monitoring photodiode for the automatic control of carrier wave output power. The laser diode can be used for the transmission of analogue or digital signals from d.c. up to microwave frequencies over long or short optical links. For a complete high-speed link, there is a matching photodiode with a 7 GHz detection bandwidth. The small size, light weight and very low power consumption of the laser make it suitable for airborne or remotely powered system use. Typical applications include multi-channe communications, phased array antennae, or radar signal transmission. Walmore Electronics Ltd, 11 Betterton Street, London WC2H 9BS. WW 310

## Polyester capacitors

An alternative to the multi-layered ceramic capacitor in decoupling application is offered by the Suflex range of metallized polyester capacitors. The SUF168 is a subminiature device that allows for high packing density and is printed on the top to allow identification of values when closely mounted Values range from 1000 pF to $1 \mu \mathrm{~F}$ with ratings of 50,60 and 100 V d.c Suflex Lid, Risca, Newport, Gwent NP1 6YD. WW 311


## Sinclair goes into business

No modesty has been exercised by Sinclair Research in the naming of their latest computer which they have called the QL for Quantum Leap. It certainly is a leap into an entirely different world from that occupied by the ZX 81 or the Spectrum. The QL is being promoted as a purely business machine and is provided with four business-oriented software packages; a word processor, a database, a spreadsheet and a graphics program for the production of graphs and charts.
The computer is based on Motorola MC68000 processor which Sinclair claim is a 32 -bit processor. The 68000 has 32 -bit internal architecture but uses 16 bits externally and the 68008 version used in the QL has an 8-bit data bus. So it's really an $8 / 16 / 32$ bit processor depending from where you look at it. A second processor, Intel 8049, is used to control the keyboard, generate the sound and act as an RS232C receiver. QL has 128 K of ram and there will be a 0.5 M byte plug-in ram module as an optional extra. Program storage is on Sinclair Microdrive, a tape cartridge medium with 100 K bytes of storage on each of the two built-in drives.
There is an expansion slot for up to six further drives.

Sinclair have designed their own operating system, called QDOS, although no discs are involved. QDOS is a single user, multitasking system which has the ability to run several programmes concurrently and to display the result simultaneously in different windows on the screen. The operating system uses a new version of Sinclair Basic, called SuperBasic, which is claimed to be so superior to 'normal' Basic as to constitute a different language. It has the ability to define procedures written in individual blocks. A 'constant execution speed' is claimed, that does not get slower if a program is longer.

The computer has a full typewriter-pitch keyboard with 'real' keys, 65 of them, including cursor-control keys and five programmable function keys.
The display facilities are from a wide choice of character sets with a normal format of 84 columns by 25 lines. Two modes of highresolution graphics are offered; 512 by 256 pixels with four-colour (red, green, black and white) display, and 256 by 256 with an eight-colour display. A 'stipple' command allows the mixing of foreground and background colours to add to the palette. In both modes a varying grey scale is produced on a monochrome monitor. The quality

of the display is such that a highresolution monitor is necessary to take full advantage of the system. Much would be lost by using a tv receiver even though a tv modulated output is provided.

A number of interfaces are built in; two RS232C interfaces, two analogue joystick ports, a romcartridge slot, a u.h.f modulated tv output as well as an RGB monitor output. There is a general-purpose expansion slot which may be used to plug in a ram module, or other peripherals as they become available. There are also two local area network ports and up to 64QLs and/or ZX Spectrums may be daisy-chained together sharing such facilities as a printer or a data base. Data may be transmitted along the QLAN at 100 K baud and there is a handshake protocol to ensure that a receiver station is 'listening'.

The QL is due to be issued to customers toward the end of February. As is usual with Sinclair new products, it will be available on mail-order only and may appear in retail shop after about six months. There is a $£ 7.95$ charge for postage and packing and users are invited to join a users' group or QLUB, for an additional $£ 35$ a year. Members will get software up-dates and news of all additions.

Planned enhancements already under development include a C comiler, 6800 assembler, emulation of a main-frame terminal, a-to-d converter, a hard disc interface, a modem, a parallel printer interface, and an IEEE-488 interface.

Sinclair Research Ltd, Computer Division, Stanhope Road, Camberley, Surrey GUl5 3PS.

WW 301

## Wren for $£ 1,000$

Designed by Transam for Prism Business Systems, the Wren computer is based around a Z80B processor running at 6 MHz . It has 64 K or ram exandable to 256 K , with a diagnostics rom of 8 K . A real-time clock is included as is a 50byte c.mos ram, both with battery back-up. It includes a 7 in monochrome amber display c.r.t with 36 K of screen memory, three selectable screen formats; 80 columns by 24 lines, 40 columns by 24 lines Prestel format, or 512 by 256 elements high-resolution graphics. Although the internal display is monochrome, full colour graphics are supported and there is an RGB output to a colour monitor. The keyboard, which is not detachable, has 67 full size qwerty keys with separate cursor keys and five function keys which allow up to 15 different programmable operations. Two 5.25 in disc drives are included with 200 K byte storage for each drive.

There are a number of interfaces; an RS232 serial port, a Centronics parallel printer port, two analogue inputs for paddle cursor controls, a hard disc interface, and a built in autodial modem which is Prestel and CCITT compatible. Software may be downloaded from Micronet 800 through the inbuilt download facility. For transport, the screen and disc drives in the upper section slide forward over the keyboard, revealing a sturdy carrying handle at the back, it weighs "under 20 lb" ( 9 kg ).

The software includes a Z 80 version of BBC Basic, a desk-top facility which includes a diary, an address file, a system for creating simple documents such as memos, or expense forms, a filing system, a calculator and it may be used in conjunction with a printer as a typewriter. Perfect Writer, Perfect Calc and Perfect Filer are included along with CP/M 3.
Prism Business Systems Ltd, 18 Mora Street, London ECIV 8BT. WW 302



## CHUM ONE

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lator, f50.
Rohde \& Schwarz Power Signal Generator Type BN 4105, 30 kHz to 300 $\mathrm{MHz}, \mathrm{f} 125$.
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Pye 12V Power Unit Type AC 15, $£ 25$.
Wandel Golterman Carrier Frequency Level Meter. Type TFPM 76, f60 Schoman Schwarz Video Skop Type BN 4241, f250.
Tektronix Frequency Moter Type fDI, 30 to 900 MHz , E 50
Bruel \& Kolay Cable Type 113, f 50.
Advance Pulse Vibation Moter Type 2502, E50
Advance Pulse Generator Type PG 54, £40
Systron Donner LF. Spectrum Analyzer Model $805,200 \mathrm{~Hz}$ to 1.6 MHz , $£ 550$ Ministry Oscilloscope Type CT 436 Dual Beam D.C. to 6 MHz, $\mathrm{EB5}$.
Marconi Signal Ganerator Type TF 995A3// (CT402), f95
Marconi 100-Watt 7dB Aktenuator Type 7 M 280,150 to $185 \mathrm{MHz}, \mathrm{f} 40$.
Pye Aeriai Tuner Unit Ype A1u 4,2 to MHz . Pre-set,
Marconi V.H.F. Signal Generator Type TF $1064 \mathrm{~B} / 5 \mathrm{M}, \mathrm{f} 125$. Marconi Tx \& Rx Output Test Set Type TF 1065, 885 Marconi $1 / 4 \%$ Universal Bridge Type TF 1313, f2z0. Tektronix L-C Meter Type 130, f65.
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Advance Oscilloscope Type DS25A, DC to 3 MHz , f 120 . Telequipment Oscilloscope Type O43, DC to 10 MHz , £100. Telequipment 0sciloscope TYpe S43, 1 C
Telequipment Oscilloscope Type S32A, DC to 3 MHz , fes5. Tektronix Rack Mount Oscilloscope RM17, OC to 10 MHz , f 85 . Tektronix Oscilloscope Type 317 , DC to $15 \mathrm{MHz}, \mathrm{£} 120$. Marconi R.C. Oscilloscope Type TF1101, $\mathbf{f 6 5}$.
Airmec Millivolt Meter Type 301A, $£ 75$.
Advance Audio Generator Type H1, £20.
Tektronix Oscilloscope Type 543A with Type B plug in, f160 Tektronix Oscilloscope Type 531A with Type H plug in, f16 Sander Oscillator Type CLC 2-4, 2 to 4.5 GHz , 595. Bruel 81 Kjoer Microphone Amplifier Tpe 2603, $£ 50$. EAM1 Oscilloscope Wide Band Amplifier Type 7/1, $£ 25$ Airmec Sweep Signal Generator Type 352, 20 Hz to 200 kHz , £45. Belix Variable Power Unit, 0 to 50 V at 2 amp, $£ 40$. BTR Silvertown Anti-Static and Conductive Footwear Tester, f2s. Dawe True RMS Valve Voltemeter Type 612A, E20. Rohde \& Schwarz Power Signal Generator Type BN41001, 0.1 to 30 MHz f75.
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Marconi A.M./F.M. Signal Generator Type TF 995A/5, £230. Marconi R.F. Power Meter Type TF 1020A/4, 300W, 75 ohm, f 65 Marconi R.F. Power Meter Type TF 1020A1, 100W. 50 ohm, f65.

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| $2200 / 10$ | 5000 | 0.08 |
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| $470 / 16$ | 4000 | 0.07 |
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| 15pf | 40000 |
| 12pf | 16000 |
| 68pf | 20000 |
| 22pf | 2000 |
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| :--- | :--- | :--- |
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| 0.05 | 0.03 | 0.02 |
| 0.08 | 0.05 |  |
| 0.04 | 0.03 | 0.02 |
| 0.04 | 0.025 | 0.02 |
| 0.07 | 0.05 |  |
| 0.06 | 0.04 |  |
| 0.05 | 0.03 |  |
| 0.11 | 0.07 | 0.05 |
| 0.03 | 0.02 |  |
| 0.09 | 0.05 |  |
| 0.05 | 0.03 |  |
| 0.18 | 0.11 |  |
| 0.12 | 0.07 |  |
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The CST PROCYON comes with a highly efficient IEEE filing system, supplied in EPROM, and responds to any high level language, including LISP, FORTRAN, FORTH, APL and BASIC. A specially-written Commodore data-exchange routine, allows you to link your BBC micro to CBM machines and disc drives. At 70 k bytes of information per second, the CST PROCYON channels data quickly and efficiently between up to sixteen devices, responding to standard system commands as wetl as specialised filing instructions. Its capabilities are fully documented in a straightforward but comprehensive manual.
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Engineeryou could be involved with either digital or analogue design in the early development of equipment. The equipment can involve novel advanced transducer techniques; sophisticated signal processing; advanced microprocessor technology; recording \& instrumentation; power conditioning for high power densities and high efficiency; VLSI and high density packaging.

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For further details please write to the address given below. As our careful selection process takes some time, it would be particularly helpful if you could detail your qualifications, your personal fields of interest and practical experience, and describe the type of of working environment most suited to your career plans.

The Recruitment Officer, HMGCC, Hanslope Park, Buckinghamshire MK19 7BH.

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 Systems is about to commission the UK's most advanced satellite test facilities. There is an immediate requirement for an Antenna Range Test Superintendent and for an Antenna Test Systems SupervisorThe SuperIntendent will institute test runs and be responsible for range personnel, test procedures, safety the integrity of test equipments, and will also contribute to the development of the test range facility. Applicants should have an HNC as a minimum qualification and at least 5 years experience of R.F. and antenna testing utilising computer based systems.
The Supervisor will be responsible to the Range Superintendent for the implementation of test runs and generally contribute as a member of the range test team Applicants for this should possess ONC in electronics plus at least 3 years computer based test experience of R.F equipments

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Telephone Portsmouth (0705) 674019 for an application form or write direct to Derek Withers Marconi Space and Defence Systems Limited. Browns Lane. The Airport, Portsmouth, Hants PO3.5PQ quoting reference BL 152
(All posts are open to men and women)

## Marconi

Space \& Defence Systems

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A technician is required to design, build and develop microprocessor-based in struments including both associated hardware and software
The person appointed will join a small team of scientists and technologists providing a service to Atkinson Morley's Dospital and to other Hospitals in the District and Region.

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The starting salary will be $£ 8,009$, with increments up to a maximum of $£ 9,835$ including London Weighting. Post avail able from April 1984.
For further information please contac lan Eversden, Principal Physicist
Application form and job description available from

> Hospital Administrator
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of practical bent required in department of international reputation, to maintain electronic imaging equipment containing computers, particularly two X-ray CT Scanners in modern teaching hospital. Training will be pro vided.
Salary within Grade 1A Scale for Other Related Staff, $£ 7,190-£ 11,615$ per annum, depending on qualifications and experience.
Further particulars and application forms from The Secretary, The University, Aberdeen with whom applications (2 copies) should be lodged by 15 March 1984. (2461)

## Appointments

## BHECHONIC WNGINDRS

Due to promotion, two Electronic Engineers, qualified to a minimum of HNC level, are required for our Electronic Maintenance Department

## Electronic Maintenance

One opportunity is to join the section responsible for repair to component level of studio broadcast equipment, including Video Switching and Processor Systems, Field Synchronisers, Telecine and Cameras. Applicants should be familiar with colour television technology and have experience in fault finding on analogue, digital or microprocessor based hardware

## Routine Maintenance

The second vacancy is within a team which ensures that the Industry Code of Practice is met through a comprehensive policy of measurement and routine maintenance of the electronic broadcast systems on the station. Test engineering experience on such systems with a television company or
equipment manufacture is essential.
Starting salaries will be in a range up to $£ 13,000$, depending on qualifications and experience. plus overtime payments.

Applications in writing to
Personnel Officer (Recruitment)
Yorkshire Television Limited
The Television Centre, Leeds LS3 1JS


YORKSHIRE
TELEVISION

## VIDEO ENGINEERS

Rediffusion Consumer Manufacturing Ltd is seeking an intermediate and a senior video engineer with OND, HND or similar quallfications, together with a knowledge of modern consumer electronics circuitry techniques, to join a small team looking after Rediffusion's mammoth investment in domestic video recorders and video disc players.
In addition to analysis of performance and long term raliability factors, assessment reporting is an important part of the team's function and the ability to express oneself verbally and in writing is essential. Our laboratories are situated at Chessington within easy commuting distance of the surrey countryside. Attractive salaries and the usual big company benefits, which include assistance with relocation expenses, are offered to suitably qualified and experienced engineers. If you believe you can make a significant contribution to our video projects please write to or phone:-

## Harry Brearley,

Rediffusion Consumer Murufacturing Ltd.,
Fullers Way South,
Chessington, Surrey. KTG 1 HJ .
Telephone: 01-397-5411.
REDIFFUSION

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To provide all aspects of technical support. Promotion prospects are good and linked with active encouragement to acquire further skills and experience. Minimum qualifications are a TEC Certificate in Telecommunications or equivalent plus two or more years' practical experience.
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For further information and your application form, please telephone Cheltenham (0242) 32912/3 or write to:


Recruitment Office, Government Communications Headquarters, Oakley, Priors Road, Cheltenham

Gloucestershire, GL52 5AJ.

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Ability to work on own initiative. Knowledge of music and sound would be appreAled ciated but
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Telephone 01-2650722 (24-hour p
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Now, due to expansion, we're looking for highly competent Repair Engineers to fill the following positions:

## Senior Base Repair Engineer (Message Switching Equipment)

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A sound background in data communications and experience of repairing and testing equipment, down to component level, is essential. The ability to program and some knowledge of Texas 9900 and Motorola 6800 micro-processors would be advantageous.

Probably in your mid 20's you must be able to demonstrate sufficient experience in a similar environment to equip you for these demanding and responsible positions. Competitive negotiable salaries, depending on the extent and relevance of your experience, are offered.
Our company's continuing success and exciting plans for the future create excellent prospects for career advancement and mean that we can offer a generous range of benefits, including bonus and profit share.

To apply, please write to, or telephone, Chris Burns at:
$\qquad$ Computer and Systems, Engineering plc, Caxton Way, Watford Business Park, Watford WD1 8XH. Hertfordshire. Tel: Watford 33500.

## GUY'S HOSPITAL

DEPARTMENT OF CLINICAL PHYSICS AND BIOENGINEERING

This active, well-established and well-equipped Department provides a physical sciences service for a number of clinical departments in the hospital. We require a technician to join our electronics servicing group. This work includes the maintenance and servicing of a varied range of medical electronic equipment, and covers all aspects of patient orientated equipment from fixed installations to small portable instruments.

Experience in this type of work would be an advantage, but candidates with HM Forces experience, or a good background of TV servicing are encouraged to apply

An ONC/HNC or equivalent qualification, plus at least three years' technical experience is essential.

The appointment will be on the Medical Physics Technician Grade 3 scale.

Salary: $£ 7,174$ to $£ 8,968$ р.a inclusive.

Application forms are available from the Personnel Department, Guy's Hospital, London SE1 9RT. Tel: 01-407 7600, Ext. 3471. Please quote Ref: P/2. Closing date for completed application forms, March 30, 1984

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Inner London Education Authority
LEARNING RESOURCES BRANCH
Television Centre, Thackeray Road, London SW8 3TB

## TECHNICIAN (ST1/2)

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Candidates should have educational as well as relevant technical experience and should be able easily and quickly to establish a helpful relationship with visitors

Salary $£ 5,517-£ 8, \mathbf{3 1 6}$ plus $\mathbf{£ 1 , 2 8 4}$ London Weighting
Further details and application form from EO/Estab 1b, Inner London Education Authority, Room 365, The County Hizll, Lon don SE1 7PB

The closing date for receipt of completed application forms is 29th February, 1984.
This vacancy is suitable for job sharing.
All applicants will be given equal consideration irrespective of sex, age, disabilities, race, colour, ethnic or national origins, marital status, sexual orientation, family responsibility, trade union activity or political belief.

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Vacancies exist for Radio Officers (Marine) to serve on the Survey's research vessels. Successful applicants would be required to commence duties on August 1, 1984. Voyages are normally seven months long and vessels sail from the United Kingdom in the autumn
The Survey's vessels re-supply Antarctic land stations, support scientific parties in the field and in addition undertake shipborne research.
Candidates should possess valid certificates of proficiency recognised by the Department of Trade and have served the necessary sea time to work a single-handed station.
Starting salary in a scale up to $£ 8,640$, rising to $£ 10,917$ per annum. In addition an allowance of $£ 1,200$ per annum is payable for periods of service spent south of Montevideo.

For further details and an application form, please write, stating full qualifications and experience, to: The Establishment Officer, British Antarctic Survey, High Cross, Madingley Road, Cambridge CB3 OET. Please quote ref: BAS 5. Closing date: March 14, 1984.
NATURAL ENVIRONMENT RESEARCH COUNCIL

## Appointments

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## TEST/SERVICE TECHNICIAN

## Interactive Video - Computer Products

Salary: £ Negotiable Based: Reading Plus: Car
An interesting position is oftered which will involve carrying ou regular quality control checks on pre-manufactured 'Interact systems passing through our Reading distribution and service depot. The post will also invoive service and units returned from the field and the preparation investiturned reports. Formal qualifications in electronics would be an advantage
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We offer an aftractive remuneration package with competitive solaries and company profit sharing scheme. All replies will be dealt with in the strictest confidence.

Write for an Application Form quoting the
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Mr JF Cowan
Personnel Department at
Company Head Office
C W Cameron Lid
Communications Division
Burntield Road
Glasgow G46 7TH
Tel: 041-633 0077

## TECHNICAL MANAGER

Laser Sporting Products Limited are looking for an Electronics Engineer based at their office in North Yorkshire. The company is about to launch a new product and package on to the Game Shooting scene.
The applicant should have a sound knowledge of electronic and sonic technology together with a flare for innovation. An interest in fire-arms and shooting would also be a great advantage.
Please send applications together with curriculum vitae to
The Managing Director, Laser Sporting Products Ltd Manor Farm House Garriston Leyburn
N. Yorkshire DL8 5JT

## TEST EQUIPMENT DESIGN ENGINEERS

Rediffusion Consumer Manufacturing design and manufacture a full range of advanced specification colour television receivers and monitors.

We are looking for experienced Electronic Design Engineers to help us maintain our industry lead in sophisticated computer controlled test gear for production testing of our products. Future test equipment will be an interesting mix of digital and analogue circuitry almed at increasing the automation of the production testing operation.

If you are able to conceive, design and implement production test equipment with minimal supervision, we'd like to hear from you.

These positions are based in our Chessington Engineering Centre but some visits to our factories in the North East and Lancashire will be required at infrequent intervals. Salaries are obviously dependent on qualifications and experience, but will reflect the importance of future test gear projects to the Company's long term development.

Interested ? ... Then write or phone:
Harry Brearley,
Rediffusion Consumer Manufacturing Ltd., Fullers Way South, Chessington, Surrey. KT9 9 HJ . Telephone: 01-397-5411.

## REDIFFUSION

(2408)

## DOES THIS COMPANY EXCITE YOUR IMAGINATION?

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## THEY REQUIRE

## RF CIRCUIT ENGINEERS and DESIGN/DEVELOPMENT ENGINEERS

to design a very wide range of mobile radio products - including those for commercial users, public bodies and other professional users. Technology includes RX, TX, frequency synthesisers, hybrid and microprocessor circuitry, frequency right up to microwave bands.

## SOFTWARE ENGINEER-GROUND-FLOOR OPPORTUNITY

required to provide the necessary SW expertise in support of the above project including the use of 6800 family microprocessors. The candidate will be required to advise on latest techniques. Knowledge of Assembler and Pascal essential.

## Location:

Rural fringe of Britain's Silicon Valley - motorway to South Coast and London. Outstanding scenic beauty nearby.

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FOR FURTHER DETAILS PLEASE CONTACT
Charles Airey Associates
Tempo House, 30 Fairfield Street, London SW18 10W Telephone: 01-870 4504

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The new microprocessor controlled EP8000 Emulator Programmer will program and emulate all EPROMs up to $8 k$ $\times 8$ sizes, and can be extended to program other devices such as $16 \mathrm{k} \times 8$ EPROMs, Bipolar PROMs, single chip microprocessors with external modules.
Personality cards and hardware changes are not required as the machine configures itself for the different devices.
The EP4000 with $4 k \times 8$ static RAM is still available with EPROM programming and emulation capacity up to $4 \mathrm{k} \times 8$ sizes.

## FEATURES

- Software personality programming/emulation of all EPROMs up to $8 \mathrm{k} \times 8$ bytes including 2704, 2708, 2716(3), 2508, 2758A, 2758B, 2516, 2716, 2532, 2732, 2732A, 68732-0, 68732-1, 68766, 68764, 2564, 2764. Programs 25128, 27128 with adaptors.
- No personality cards/characterisers required.
- Use as stand alone programmer, slave programmer, or EPROM development system.
- Checks for misplaced and reversed insertion, and shorts on data lines.
- Memory mapped video output allows full use of powerful editing facilities.
- Built-in LED display for field use.
- Powerful editing facilities include: Block/Byte move, insert, delete, match, highlight, etc.
- Comprehensive input/output - RS232C serial port, parallel port, cassette, printer O/P, DMA.
- Extra $1 \mathrm{k} \times 8$ scratchpad RAM for block moving.
- EP8000 8k x 8 Emulator Programmer £695 + £12 delivery BSC8 Buffered emulation cable - £49 SA27128 Programming adaptor - £69 SA25128 Programming adaptor - £69 EP4000 $4 \mathrm{k} \times 8$ Emulator Programmer $-£ 545+£ 12$ de-
livery BSC4 Buffered emulation cable £39 BP4 (TEXAS) Bipolar PROM Module - £190 - Prinz video monitor - £99 UV141 EPROM Eraser with timer - £78 GP100A 80 column printer - £225-GR1 Centronics interface - £65

Unit E, Huxley Close, Newnham Industrial Estate, Plymouth PL7 4JN




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[^2]:    J. Vandewege

    Ghent University
    Belgium

[^3]:    * Battery-powered instruments, by lan Hickman, Wireless World, vol. 87, 1981, pp.57-61.

[^4]:    Dr Purves is with the department of pharmacology, University of Otago, New Zealand, and Mr Prescott is at the department of anatomy \& embryology, University College, London.

[^5]:    I enclose $\mathrm{PO} /$ Cheque for $£$
    Barclaycard/Access/American Express. No. or.
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[^6]:    *Also subscription agents

[^7]:    

[^8]:    Printed in Great Britain by QB Lid., Sheepen Place, Colchester, for the proprietors, Business Press International Lid., Quadrant House, The Quadrant, Sutton, Surrey SM2 SAS. (C) Business Press nternational Lid, 1984. Wireless World can be obtained abroad from the following: AUSTRALIA and NEW ZEALAND: Gordon \& Goich Lid. INDIA: A. H. Wheeler \& Co. CANADA: The WIm. Dawson Subscription Service Lid., Gordon \& Gotch Lid. SOUTH AFRICA: Central News Agency Lid.: William Dawson \& Sons (S.A.) Ltd. UNITED STATES: Eastern News Distribution Inc 14ih floor, 111 Eighth Avenue, New York, N.Y. 10011

